

RainCube: a New Paradigm to Observe Weather Processes

Ousmane O. Sy, E. Peral, S. Tanelli, S. Statham, S. Joshi,
E. Im, T. Imken, D. Price, J. Sauder, N. Chahat

Radar Science & Engineering Section
Jet Propulsion Laboratory, California Institute of Technology

©2019 California Institute of Technology.

July 24, 2019

Radar in a CubeSat: PI Dr. Eva Peral, radar/JPL

2013
6U Concept
miniKaAR + KaRPDA 0.5 m

Proposed RainCube Architecture

The diagram illustrates the proposed RainCube architecture, showing the flow of data and power through various subsystems:

- S/C bus 1.5U**: Connected to the **Digital assembly** (0.15U).
- Digital assembly** (0.15U): Contains a **RFIC** and **RFIC** components.
- Up/Down conversion assembly** (0.2U): Contains **RFIC** and **RFIC** components.
- All radar electronics: 2U**: Contains **RFIC** and **RFIC** components.
- HPA assembly** (0.1U): Contains **RFIC** and **RFIC** components.
- FESA** (0.5U): Contains **RFIC** and **RFIC** components.
- Antenna 2.5U**: A parabolic antenna connected to the FESA.

Two plots are shown on the left:

- Top plot: A graph showing a signal spectrum with a peak at approximately 35.75 GHz.
- Bottom plot: A graph showing the measured - vertical signal power (dBZ) versus range (km), with a red curve representing the measured signal and a blue curve representing the model.

A photograph showing two individuals in cleanroom suits working on the RainCube instrument, which is a small satellite component with a large antenna.

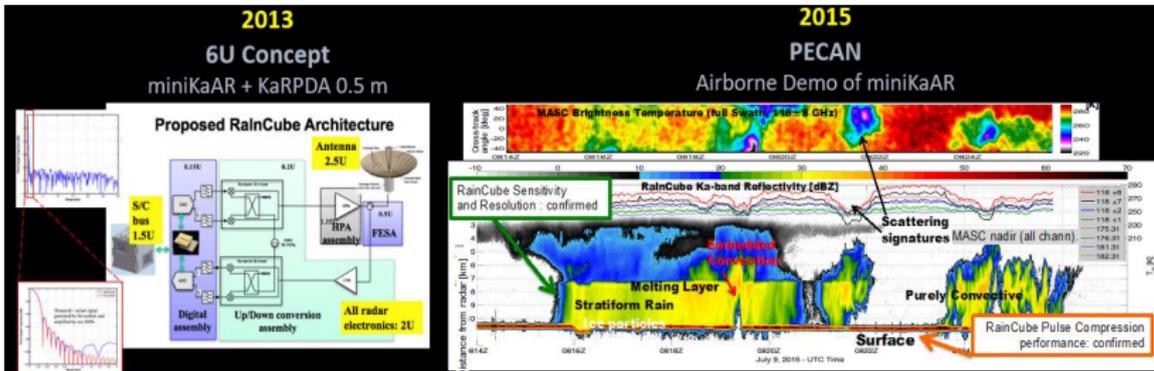
	RainCube
Frequency	35.75 GHz
Antenna size	0.5 m
Sensitivity	13 dBZ
Hor. Resolution	8 km
Range Res	250 m
Beams	1 (nadir)
RF Power	10 W
Processing	Pulse compression

Tech demo objectives

Can such a radar, in LEO (400 km),

- detect precipitation?
- capture the vertical structure of storms?

RainCube: PI Eva Peral, radar/JPL, launch&ops/Tyvak



Since August 2018

July 2018
Deployed from ISS

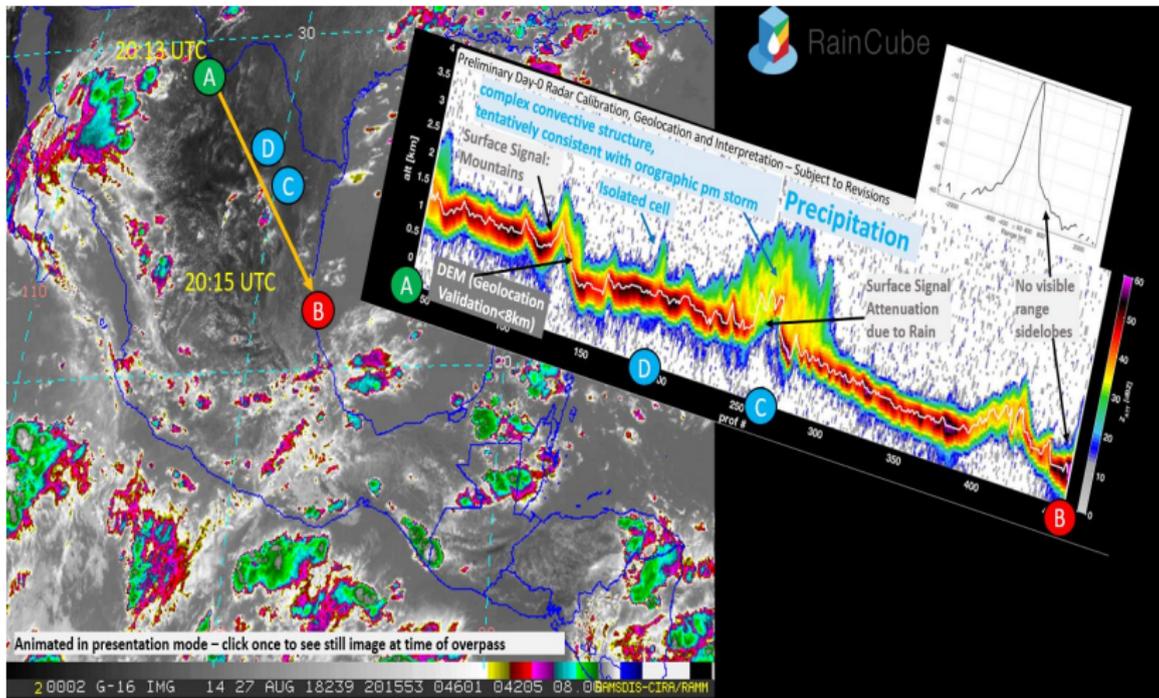
May 2018
RainCube 6U
Launched to ISS



(Artist's illustration)

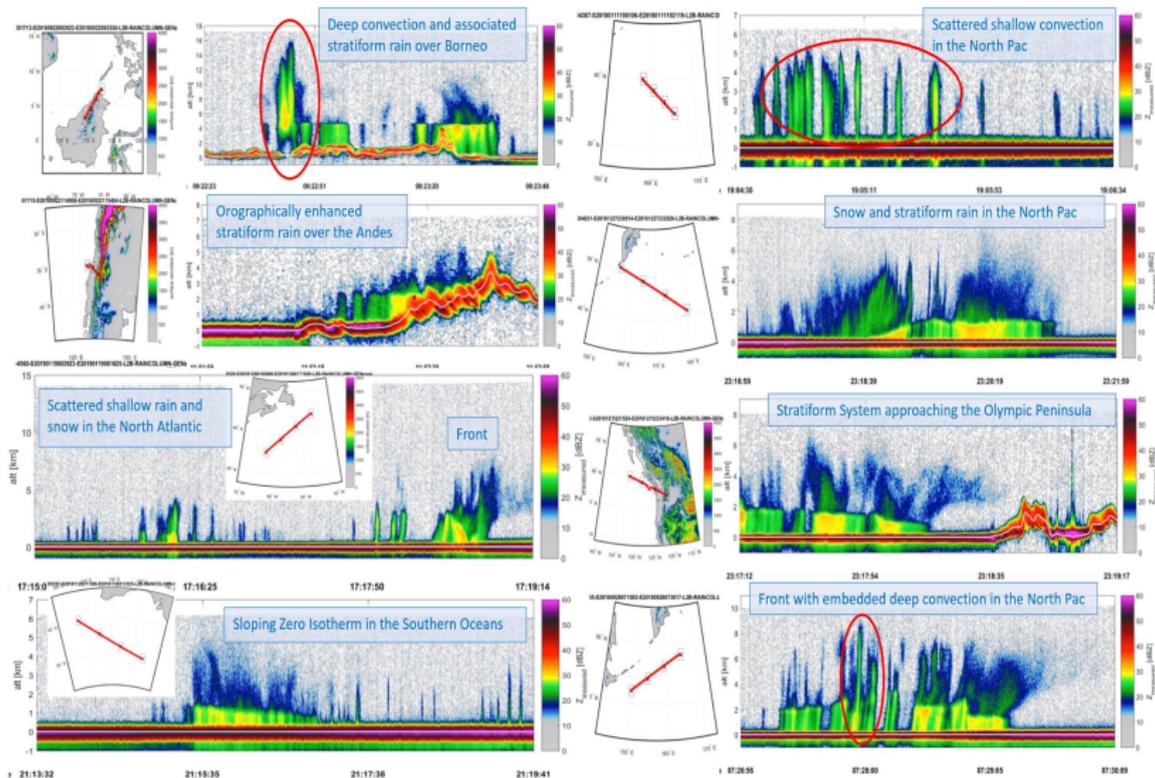


1st detection of rain: 27 Aug 2018, Sierra Madre, Mexico



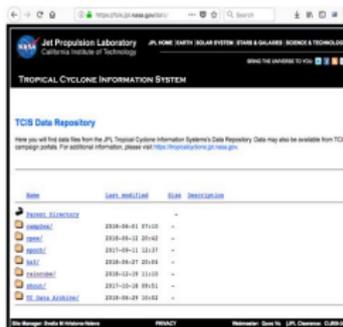
Fast growing orographic precipitation developed shortly before RainCube's pass

RainCube collection of storms



RainCube data hosted by TCIS portal

<https://tcis.jpl.nasa.gov/data/raincube/>

Name	Last Modified	Size	Description
INDEX_DIRECTORY	-	-	-
INDEX	2019-09-01 15:02	-	-
INDEX	2019-09-01 15:02	-	-
INDEX	2019-09-01 15:02	-	-
INDEX	2019-09-01 15:02	-	-
INDEX	2019-09-01 15:02	-	-
INDEX	2019-09-01 15:02	-	-
INDEX	2019-09-01 15:02	-	-
INDEX	2019-09-01 15:02	-	-
INDEX	2019-09-01 15:02	-	-

Data Distribution
#P5.1

Site Manager: Svetla M Hristova-Veleva

The Tropical Cyclone Information System hosts RainCube data.

Huge thank you to

PI : **Svetla Hristova-Veleva**,

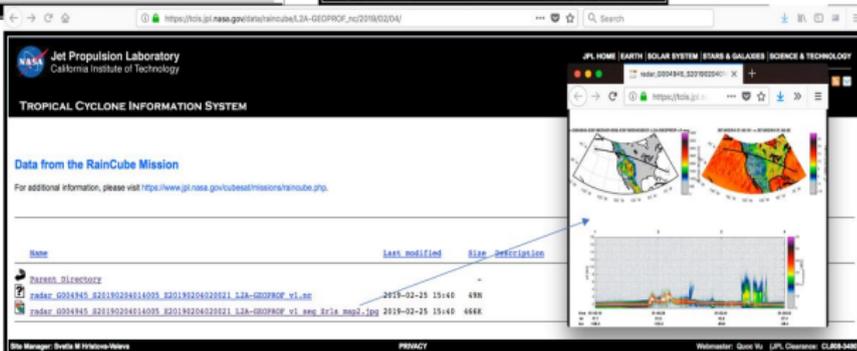
Site Administrator: **Quoc Vu**,

Data Manager: **Brian Knosp**

L2A are posted (data & browse images).

L2B Data will be made public when QC is satisfactory.

No plan to open L0 and L1 data to the public.



Name	Last Modified	Size	Description
Parent Directory	-	-	-
zader_004845_02190204014009_020193204020201_37A-GRIPFOP_v1.nc	2019-02-25 15:40	43K	
zader_004845_02190204014009_020193204020201_37A-GRIPFOP_v1_new_bria_mop2.jpg	2019-02-25 15:40	466K	

Overview

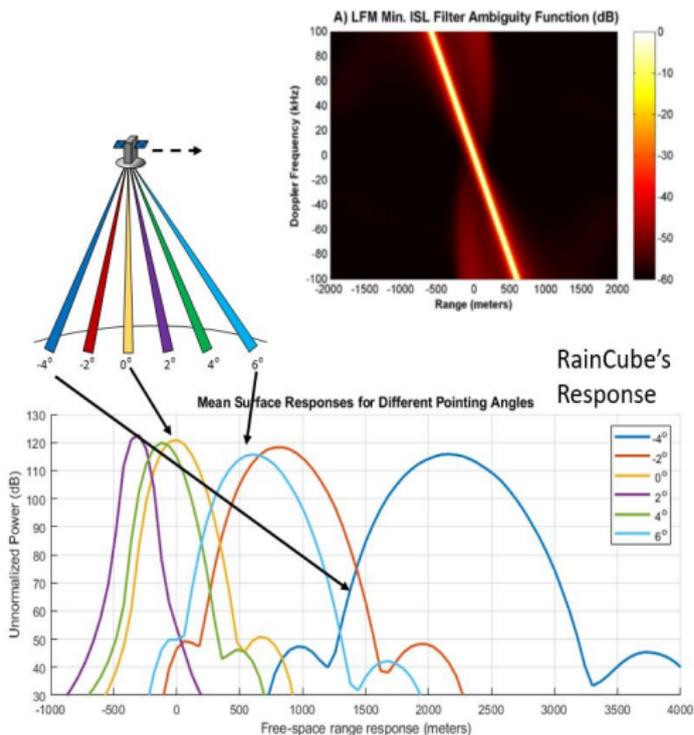
RainCube: Completed the Primary Objective of the Tech Demo

- ✓ detect rain from a 6U CubeSat
- ✓ measure the structure of storms from a 6U CubeSat

RainCube: additional objectives:

- 1 Validate Pointing for geo-location
 - Flat Surface Response (FSR) method
 - Topographic Feature Correlation (TFC) method
- 2 Augmented measurements
 - Deconvolved measurements
 - Environmental context from reanalysis (MERRA)
- 3 Calibration and Validation
 - NEXRAD
 - GPM
- 4 Combined Active-Passive

Flat Surface Response method



Occasional pointing drifts of platform

The Doppler shift from the surface
 ⇒ apparent shift in the range
 ⇒ broadening of surface response

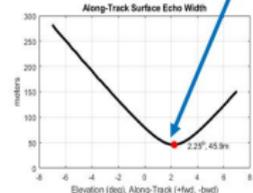
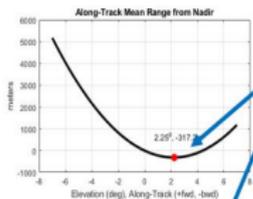
Advanced modeling predicted that the apparent **pointing offset due to Doppler effects** should be $\sim 2.24^\circ$ forward for RainCube

R.M. Beauchamp, S. Tanelli, E. Peral, V. Chandrasekar, "Pulse Compression Waveform and Filter Optimization for Spaceborne Cloud and Precipitation Radar,"

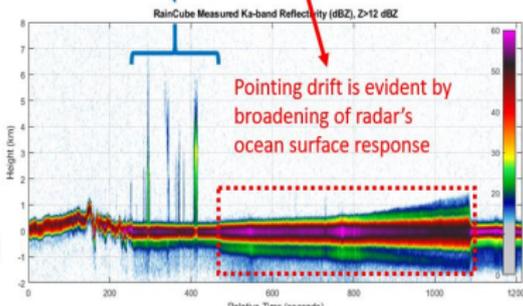
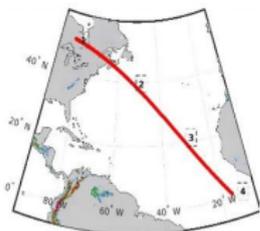
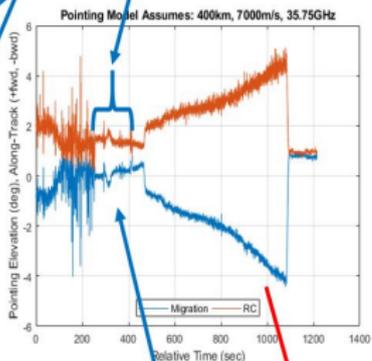
in *IEEE TGRS*, vol. 55, no. 2, pp. 915-931, Feb. 2017.

Challenges

Flat Surface Response method: example Sept. 1st 2019, 11:10:10



RainCube data confirm “apparent” off-nadir offset of $\sim 2^\circ$ consistent with pre-launch modeling results.

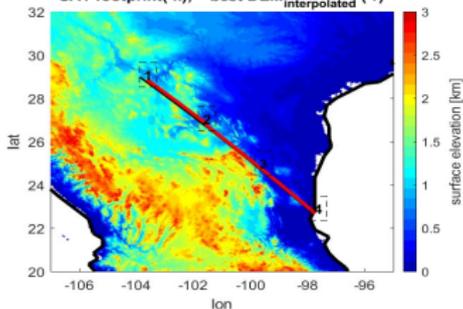


Occasional pointing drifts of platform
 \Rightarrow detected clearly within the radar data
 \Rightarrow Within $\sim 6^\circ$ off-nadir, RainCube processing system can compensate and correct geolocation

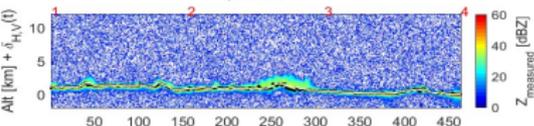
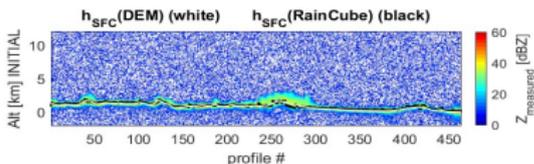
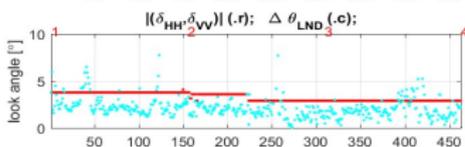
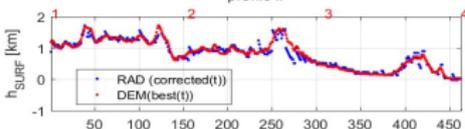
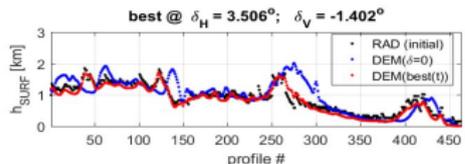
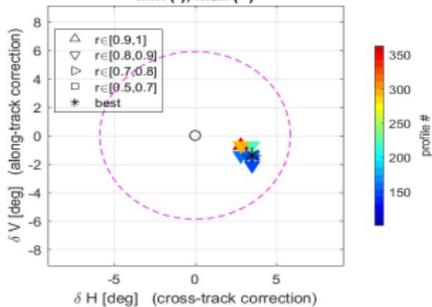
Flat surface response data validated amplitude of off-nadir angle within a fraction of a degree

Topographic feature correlation (TFC) method

3r-telemetry-G001100-S201808Z/201828-E201808Z/201843.nc
2018/8/27 @ 20:13:26 -> 2018/8/27 @ 20:15:37
SAT footprint (-k), best DEM_{interpolated} (-r)

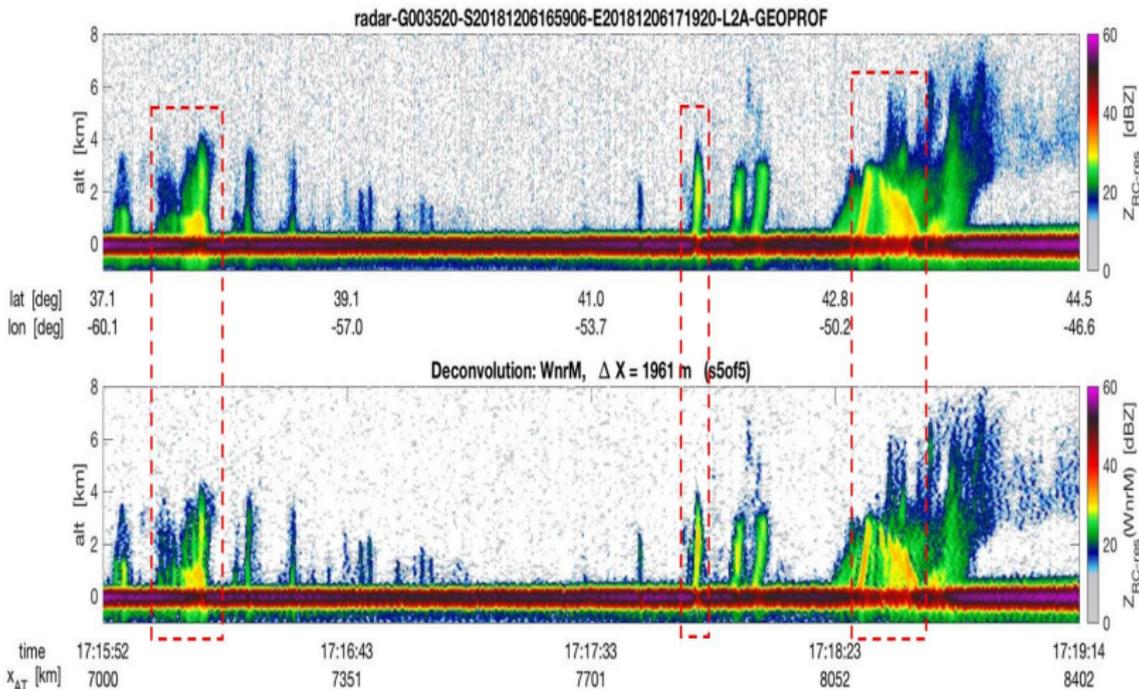


circles = range of $\Delta \theta$ from BW test:
ocean (red); land (black)
min (-); max (-)



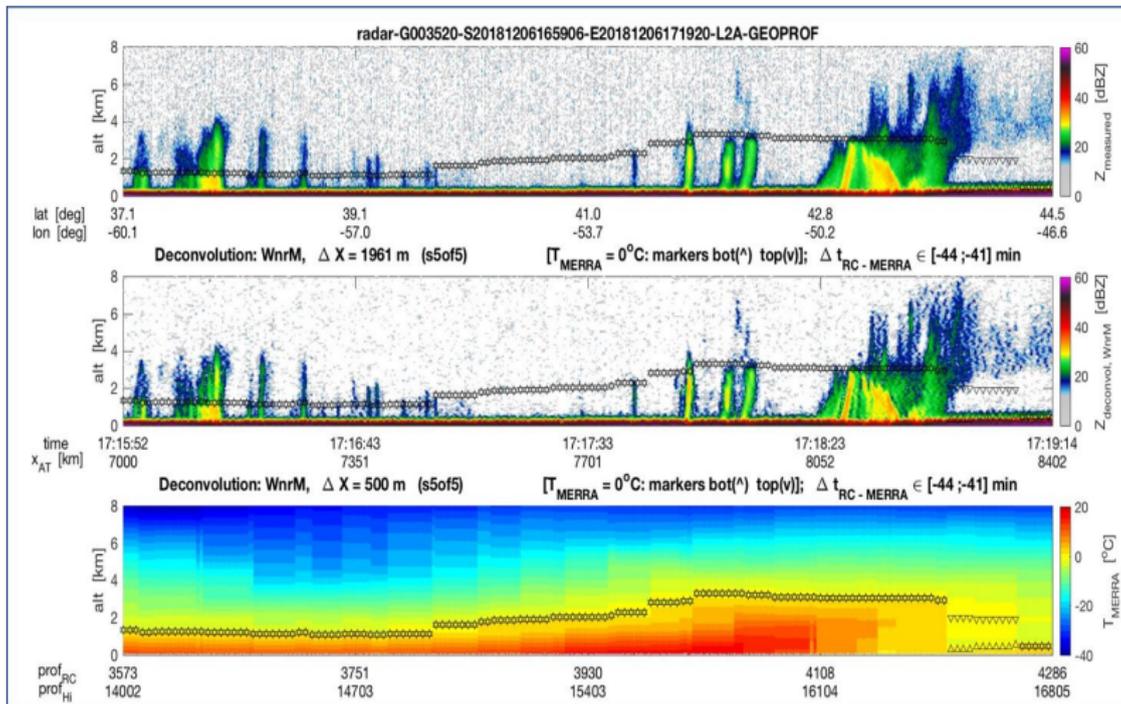
✓ unambiguous estimation of pointing angle

RainCube-deconvolution (8 km footprint, ~1.9 km sampling, N. Atlantic)



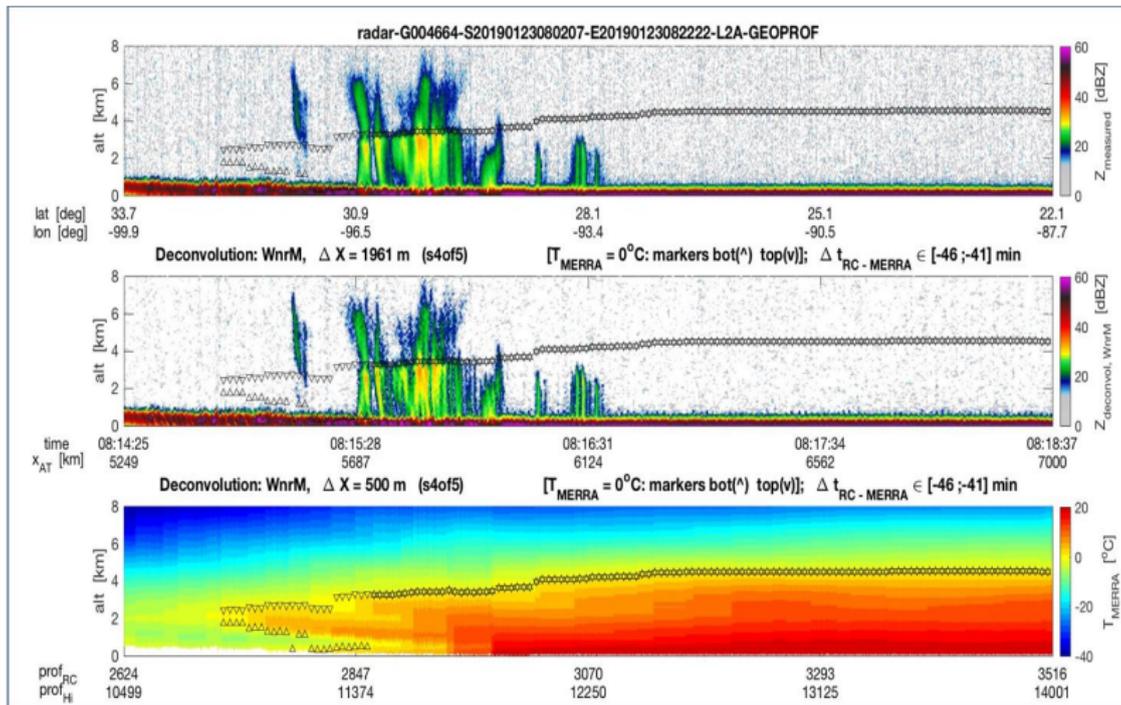
✓ sharper features, better resolution

Storms in their environment (NASA MERRA_3d_inst3_asm, $0.5^\circ \times 0.625^\circ \times 72$)



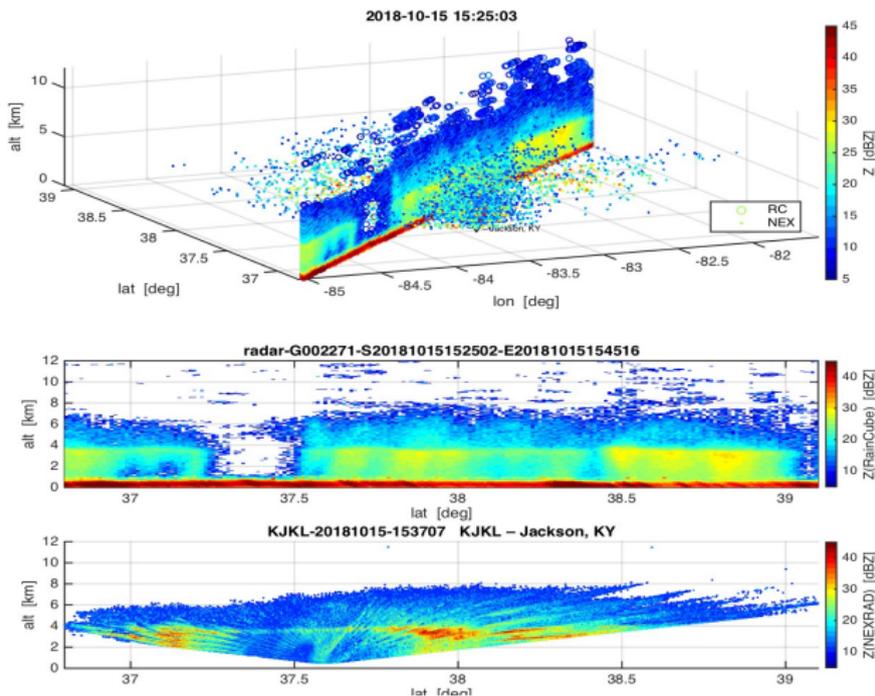
✓ Environmental context from reanalysis

Storms in their environment (NASA MERRA_3d_inst3_asm, $0.5^\circ \times 0.625^\circ \times 72$)



✓ Environmental context from reanalysis

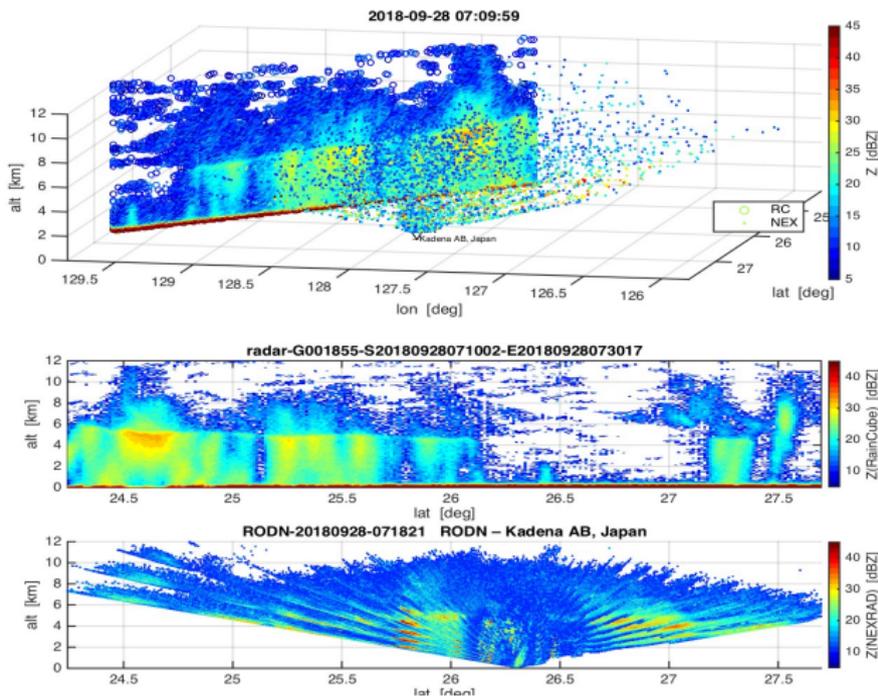
Co-location to NEXRAD (intended for rain rate retrievals)



Complementarity

≠ viewing geometries, ≠ frequencies

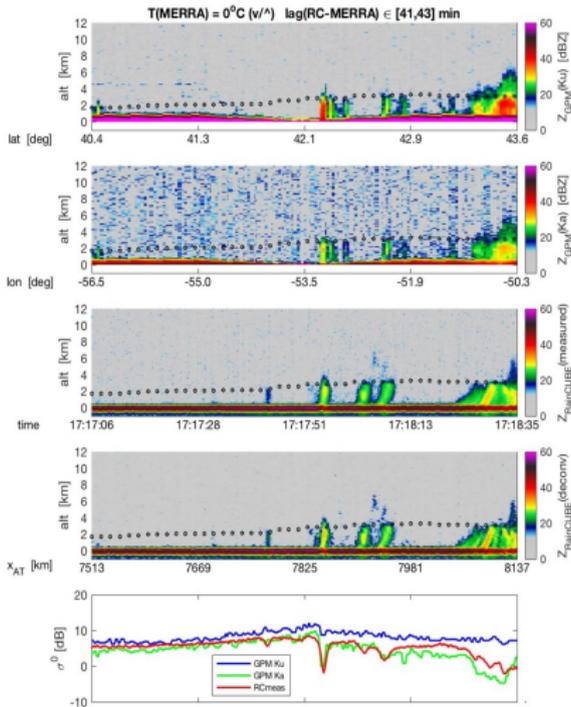
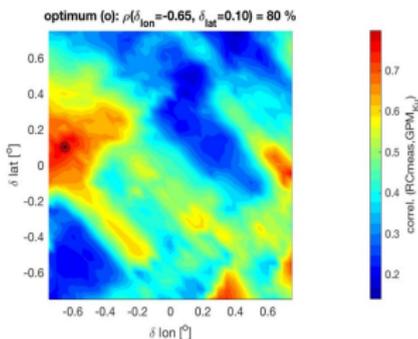
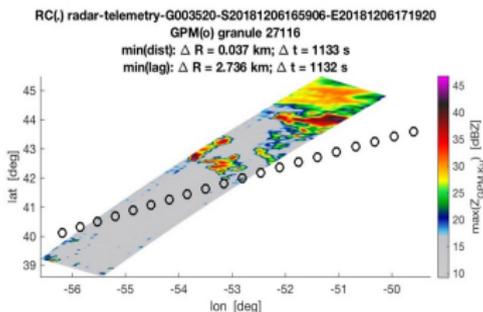
Co-location to NEXRAD (intended for rain rate retrievals)



Complementarity

≠ viewing geometries, ≠ frequencies

RainCube-GPM/DPR (NASA/JAXA, Dec 6th 2018, 16:59:06, N. Atlantic)



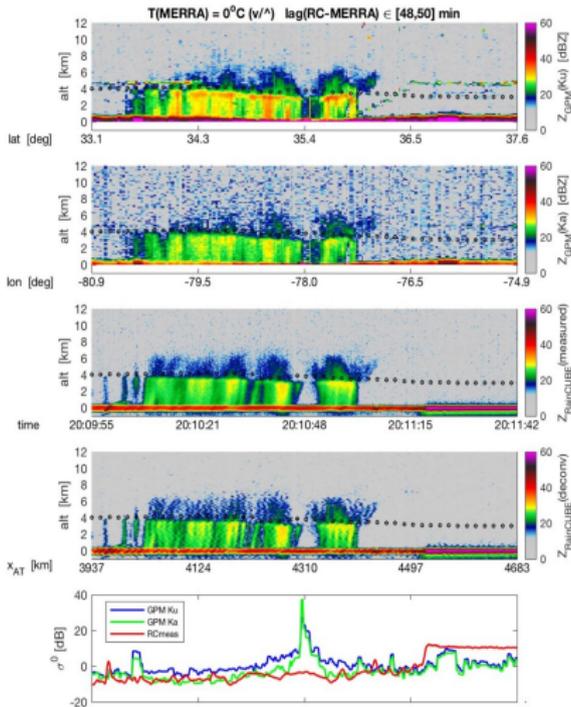
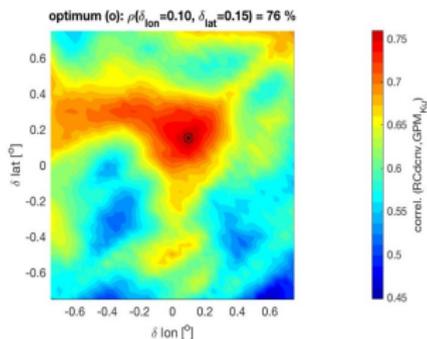
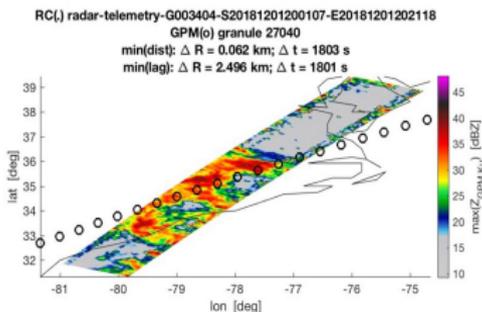
GPM
 Ku
 Ka

RainCube
 measured
 deconvol.

NRCS

✓ 1-to-1 comparisons of Z and σ^0

RainCube-GPM/DPR (NASA/JAXA, Dec 1st 2018, 20:01:07, N. Carolina)



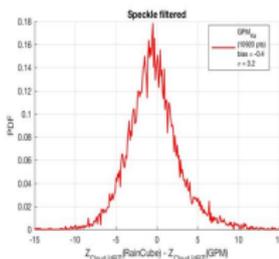
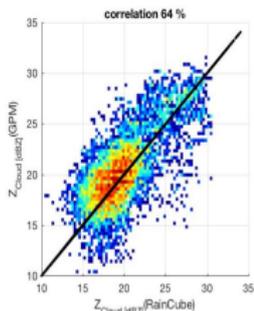
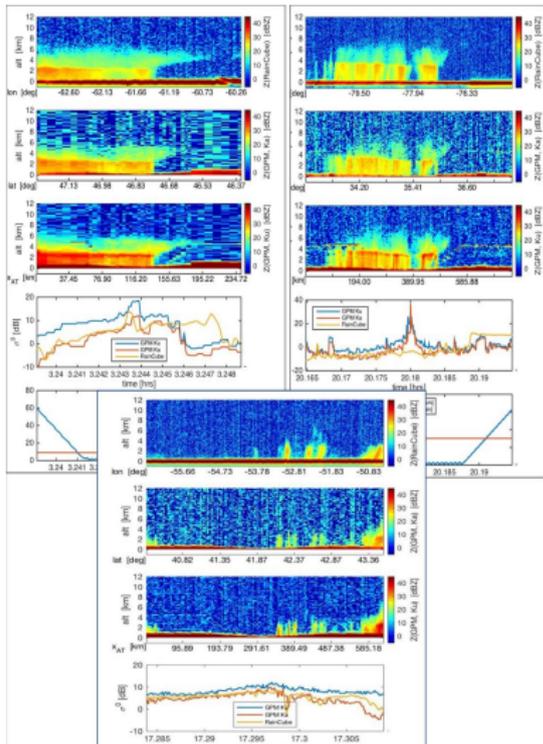
GPM
Ku
Ka

RainCube
measured
deconvol.

NRCS

✓ 1-to-1 comparisons of Z and σ^0

RainCube vs GPM/DPR-relative calibration validation



Bias RainCube vs DPR Ka

- $|Bias| < 1.5$ dB
- $|Bias| \ll \sigma$

Outcomes:

→ no calibration correction planned for next public release of science data

→ inclusion of this assessment in the product document for user awareness

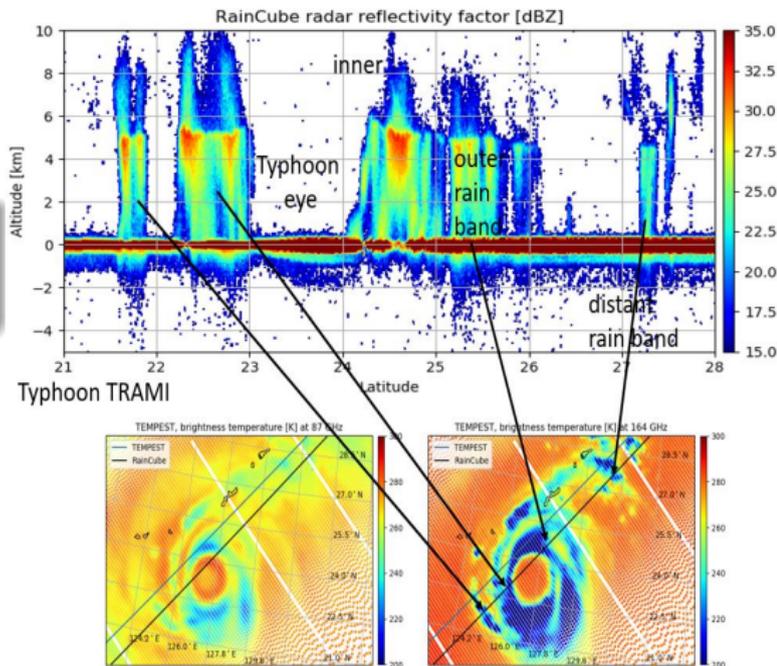
Storm Properties from Active & Passive

2 radar-radiometer datasets

- RainCube + TEMPEST-D
- RainCube + GPM

Engaged GPM Science Team (e.g., Mircea Greu at GSFC, Alessandro Battaglia at U. Leicester) to develop & evaluate combined radar-radiometer products.

Ongoing effort also at JPL



Summary

- RainCube: 1st spaceborne precipitation radar in a CubeSat
 - ① new implementation of observations of clouds & precipitation
 - ② spaceborne C&P radars = RainCube, GPM-DPR, CloudSat
- Mission
 - ① prime mission ⇒ demonstrated radar capability
 - ② extended mission ⇒ validation of pointing & calibration
⇒ grows dataset for science studies
- Scientific community
 - engaged to demonstrate value of combined observations

RainCube (radar in a *CubeSat*) cloud & precipitation profiling:
comparable performance to a *subset of GPM-DPR*

Full potential of RainCube technology hinges upon
deployment of multiple units in a (multiple) train(s)

Thank you!

For more information:

data: <https://tcis.jpl.nasa.gov/data/raincube/>

- eva.peral@jpl.nasa.gov
- simone.tanelli@jpl.nasa.gov
- eastwood.im@jpl.nasa.gov
- ziad.s.haddad@jpl.nasa.gov
- ousmane.o.sy@jpl.nasa.gov