

# Electric Propulsion Thruster Random Vibration Test with FEM Predicted Isolation System

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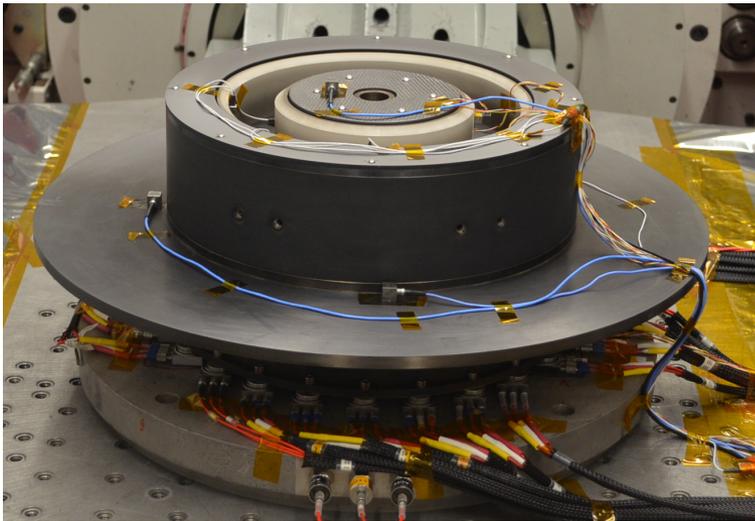
# Overview

- Background
- Problem Statement
- Method
  - *Finite Element Model Updates*
  - *Analytical Response Limit Derivation*
- TDU-2 Environmental Testing
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- Summary

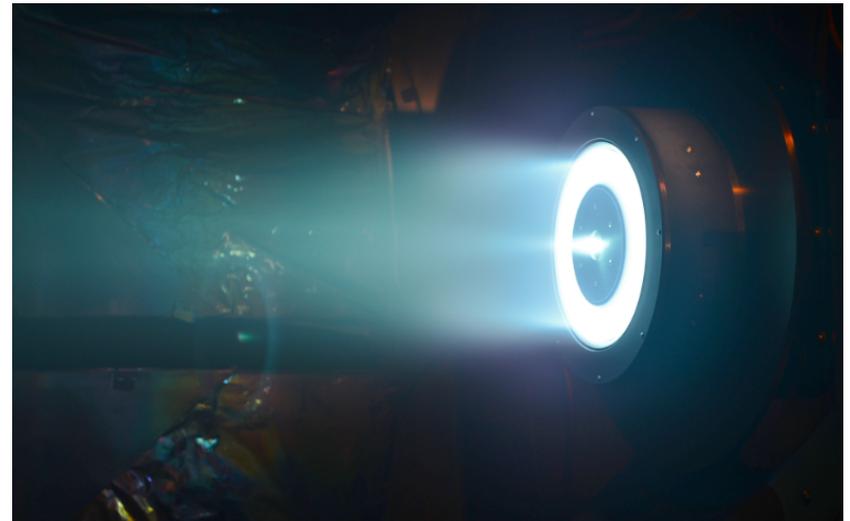
# Background

## *HERMeS TDU-2 Hall Thruster*

- The Hall Effect Rocket with Magnetic Shielding (HERMeS) is a 12.5 kW magnetically shielded Hall thruster currently under development for deep-space missions
- Technology Development Unit-2 (TDU-2) underwent environmental testing in both 2016 & 2017



TDU-2 (2017) on shaker



TDU-2 (2016) functional test

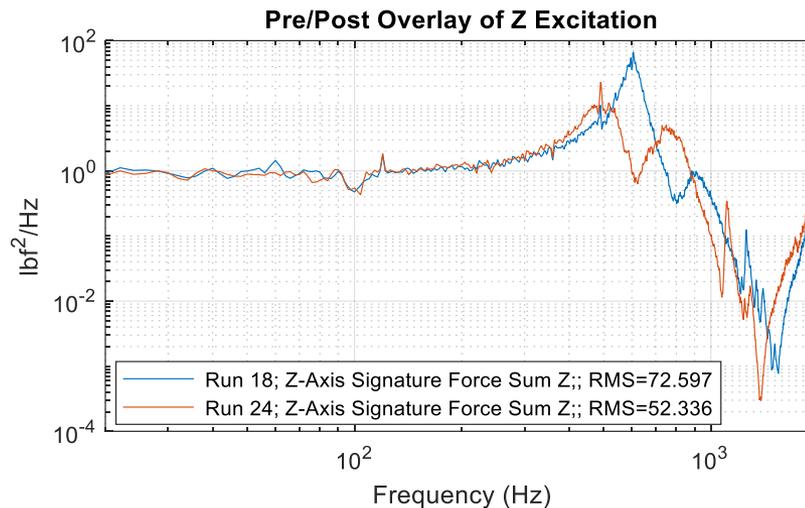
# Background

## 2016 Random Vibration Test

- In July 2016 the HERMeS thruster underwent RV testing at JPL Environmental Test Lab (ETL)
- TDU-2 did not successfully survive vibration testing
  - *Particulate emission from thruster during -6 dB and higher runs*
  - *Significant shifts of structural modes seen in all three excitation axes*
  - *Post vibration magnetic mapping of coils showed significant differences*

## Qualification Level Random Vibration Spectrum

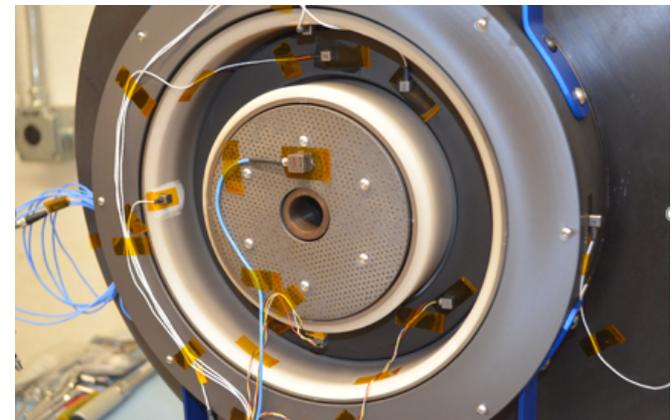
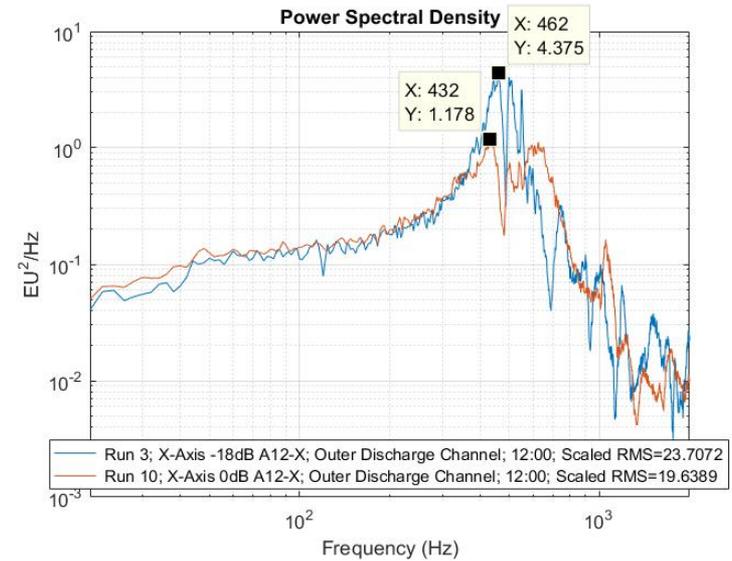
| Frequency (Hz) | PF/Qual Level (G <sup>2</sup> /Hz) |
|----------------|------------------------------------|
| 20             | 0.052                              |
| 50             | 0.13                               |
| 600            | 0.13                               |
| 2000           | 0.012                              |
| Overall        | 11.4 GRMS                          |
| Duration       | 120 Seconds                        |



# Background

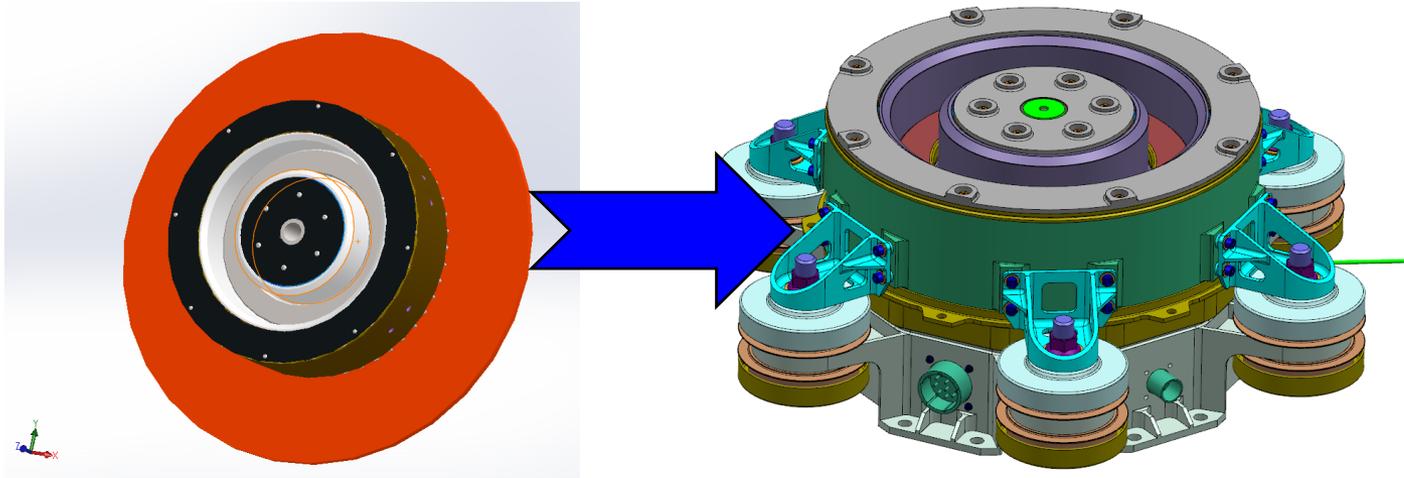
## *TDU-2 Discharge Channel*

- The TDU-2 discharge channel was the component of most concern going into dynamic testing
- No damage to the ceramic discharge channel was found following the test
- Excessive damping was observed in test due to structural failures and discharge channel did not see qualification levels



# Problem Statement

- TDU-2 underwent several design changes including the addition of a shock isolation system



- **Problem Statement: Design and execute a test to expose discharge channel to predicted isolated qualification random vibration levels using TDU-2 hardware with no isolators**

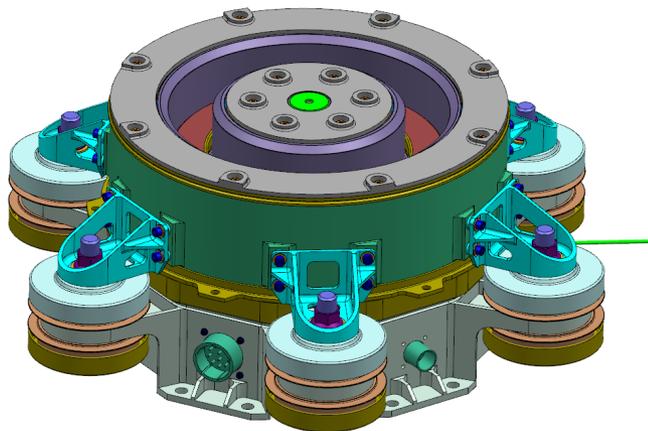
# Method

- Update TDU-2 FEM to include notional isolation system
- Perform force limited Qual RV analysis of isolated TDU-2 FEM
- Use original & isolated TDU-2 analysis results to develop response limit at accelerometer locations between spool mount and thruster
- Develop margin predictions and not to exceed limits for RV test
- Perform RV test
- Evaluate success of test and testing methodology

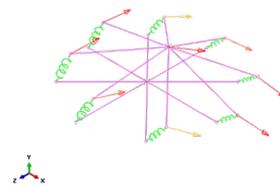
# Update TDU-2 FEM

## *Isolation System*

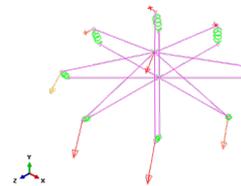
- The isolation system consists of 6 spring dampers between the thruster mounting ring and the thruster stackup
- An Abaqus mass-spring model was used to predict fundamental modes of the isolation system
- This simplified model was provided to JPL to use for FEM updates



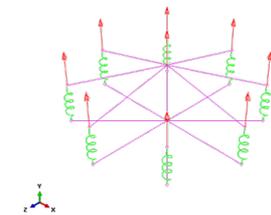
Mode 1: 87 Hz



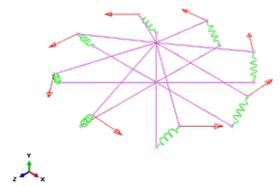
Mode 2: 87 Hz



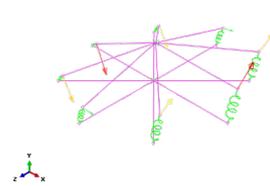
Mode 3: 105 Hz



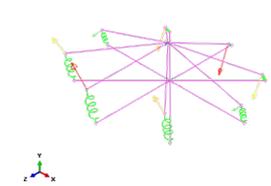
Mode 4: 174 Hz



Mode 5: 195 Hz



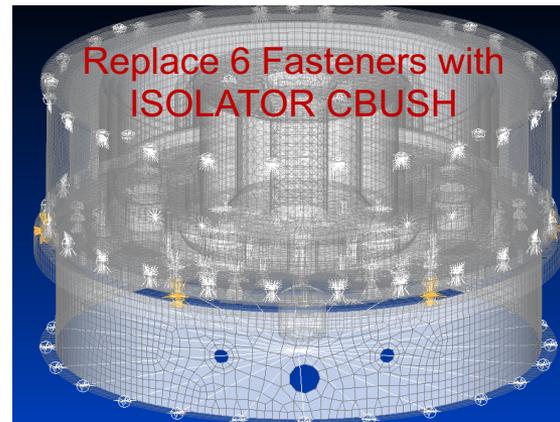
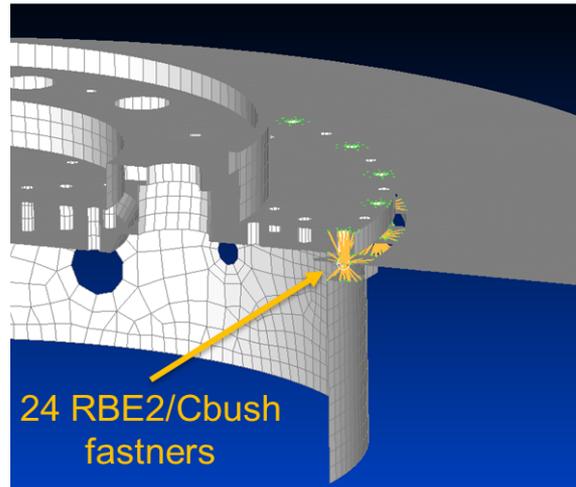
Mode 6: 195 Hz



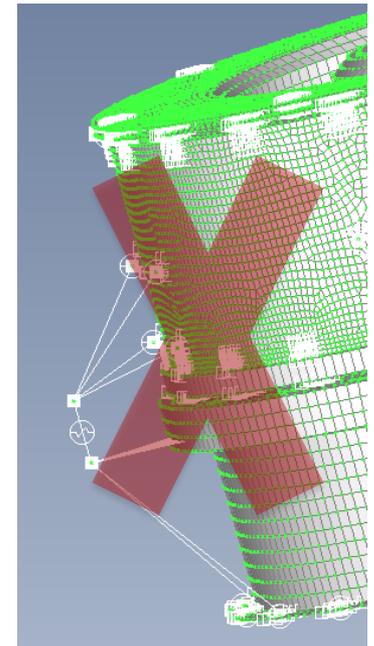
# Update TDU-2 FEM

- The TDU-2 FEM attaches the mounting ring to the radiator and the radiator to the thruster backplate at 24 locations – Remove all
- Remove Radiator
- Create 6 Isolator CBUSH elements
  - *Looked at two methods of implementing CBUSH*
  - *Simplest method worked best*

TDU-2 FEM



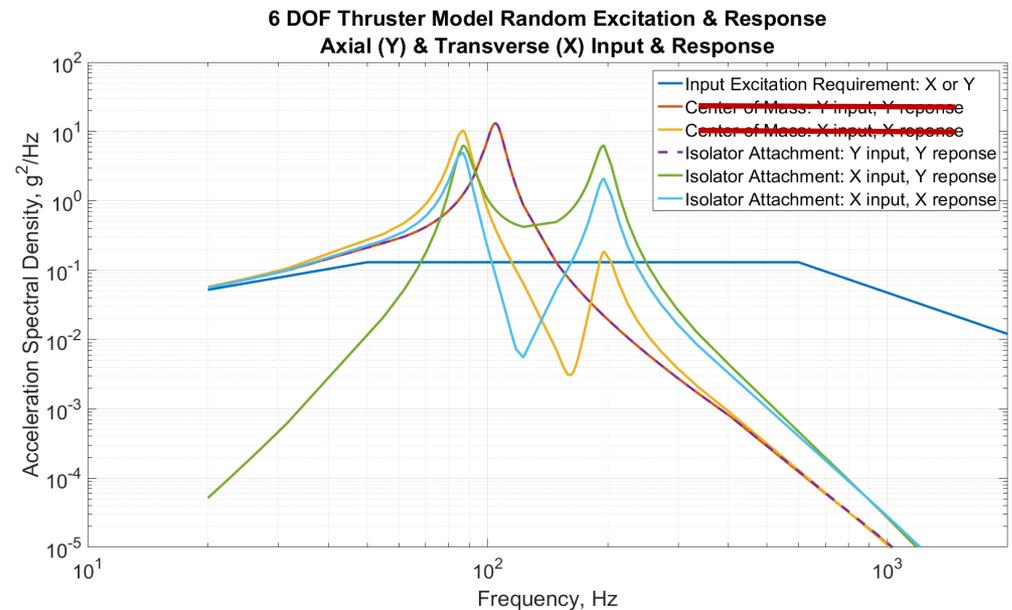
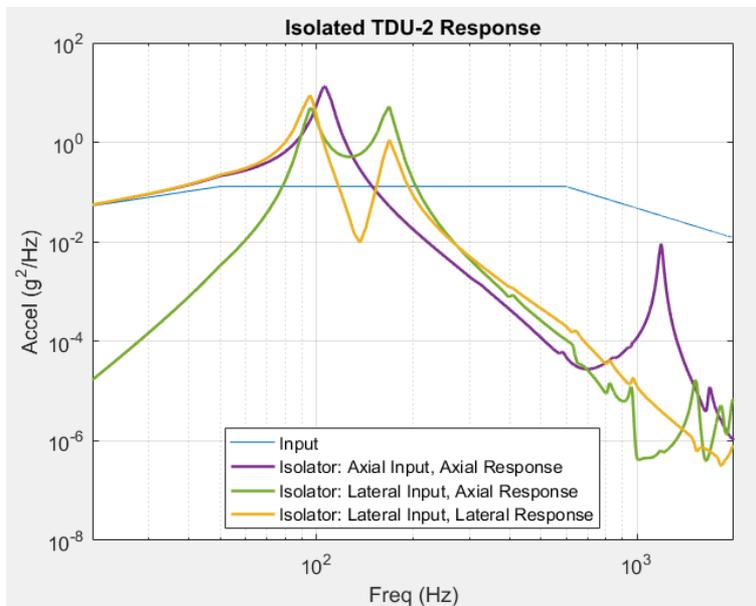
Create offset isolator using rbe2 and cbush elements



# Update TDU-2 FEM

*Probably Remove*

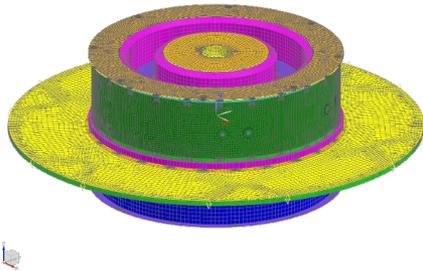
- Responses from simpler isolation FEM and provided CBUSH stiffness and damping are similar to provided rigid body response



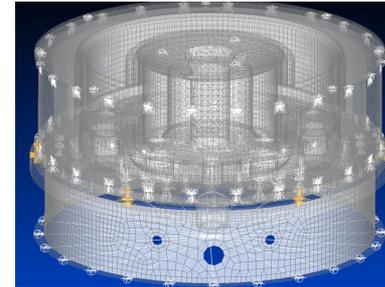
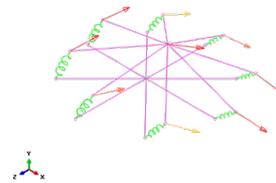
# Perform RV Analysis

## Interface Force Comparison

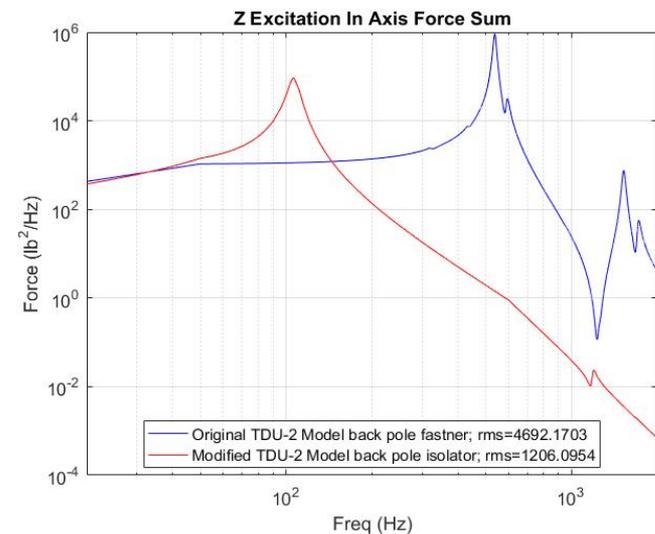
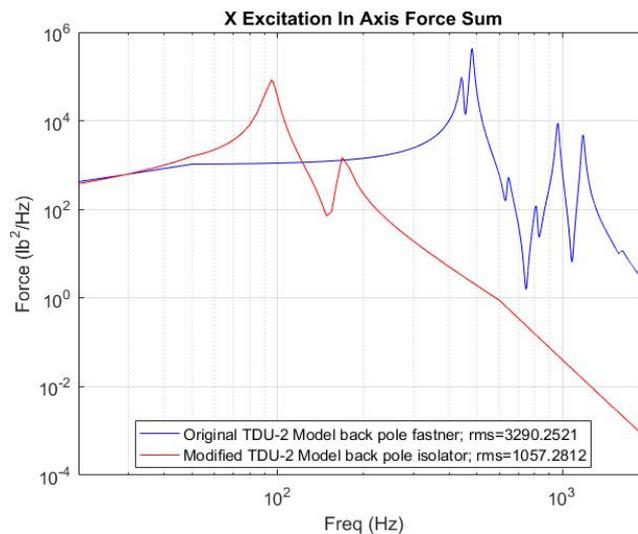
### Original FEM



### Isolated FEM



| Frequency (Hz) | PF/Qual Level (G <sup>2</sup> /Hz) |
|----------------|------------------------------------|
| 20             | 0.052                              |
| 50             | 0.13                               |
| 600            | 0.13                               |
| 2000           | 0.012                              |
| Overall        | 11.4 GRMS                          |
| Duration       | 120 Seconds                        |

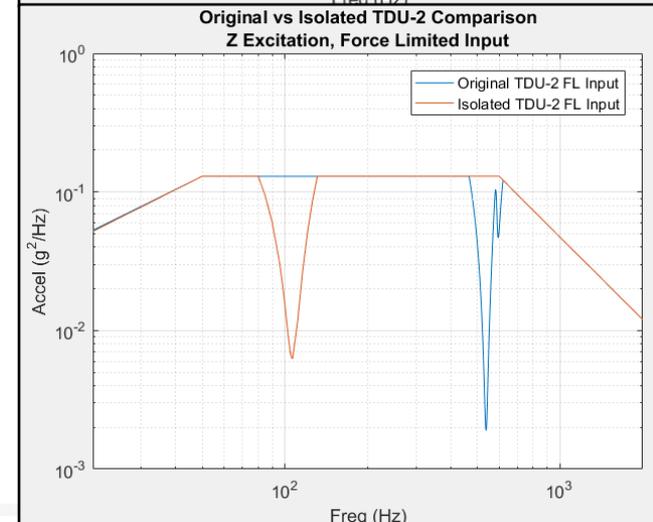
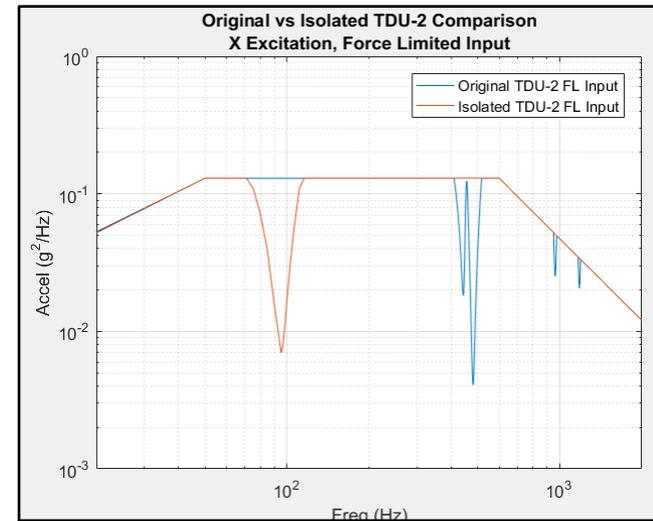


# Perform RV Analysis

## Force Limiting

- Apply force limiting to all accelerometers
- Use nodes at corresponding accelerometer locations to find isolated thruster predictions

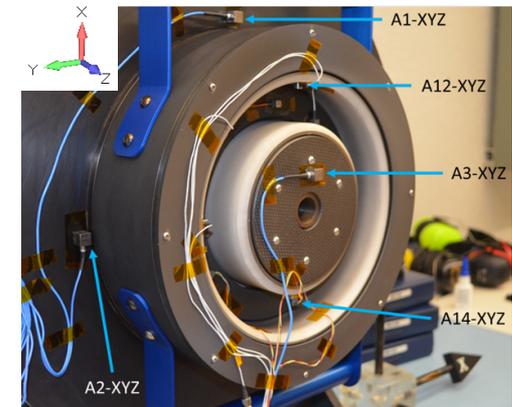
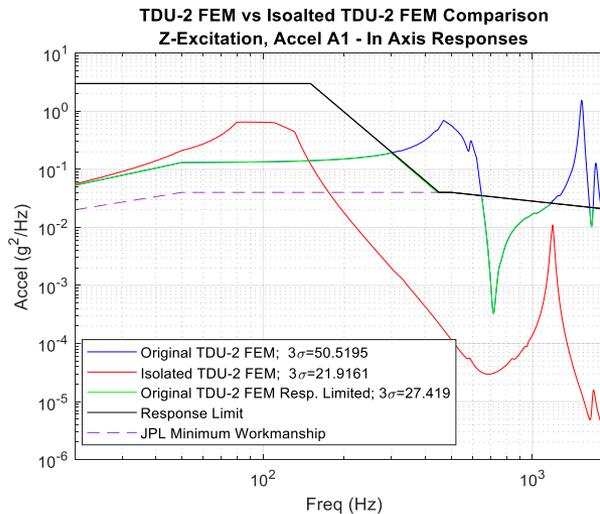
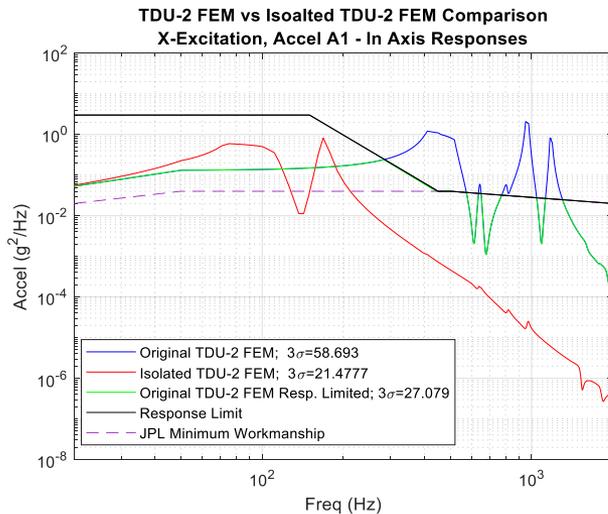
| Accel # | Location                    | Node # |
|---------|-----------------------------|--------|
| 1       | Radiator Top +Y             | 124086 |
| 2       | Radiator Top -X             | 139155 |
| 3       | Front Pole Cover            | 30845  |
| 4       | Outer Core +X               | 222468 |
| 5       | Anode +Y                    | 186532 |
| 6       | Anode -X                    | 187117 |
| 7       | Anode +X                    | 186994 |
| 8       | Anode Middle                | 186725 |
| 9       | Propellant isolator bracket | N/A    |
| 10      | Cathode Mount Flange        | 280278 |
| 11      | Radiator Bot -X             | 134407 |
| 12      | Outer Discharge Channel +Y  | 151684 |
| 13      | Outer Discharge Channel -X  | 157922 |
| 14      | Inner Discharge Channel -Y  | 153347 |



# Perform RV Analysis

## *Develop Response Limit*

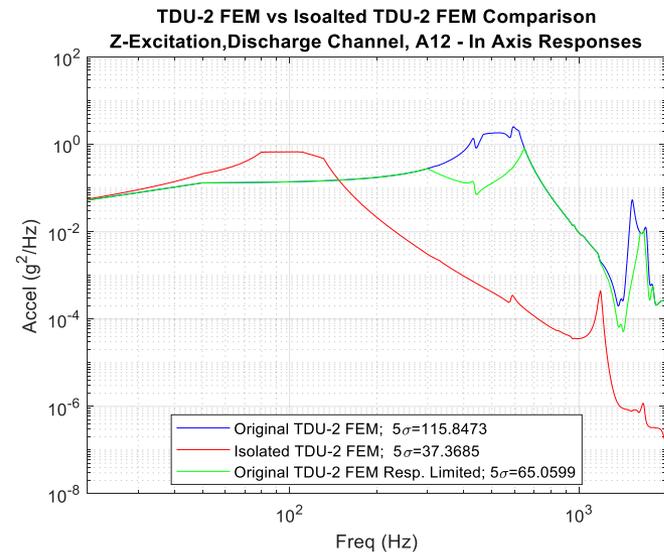
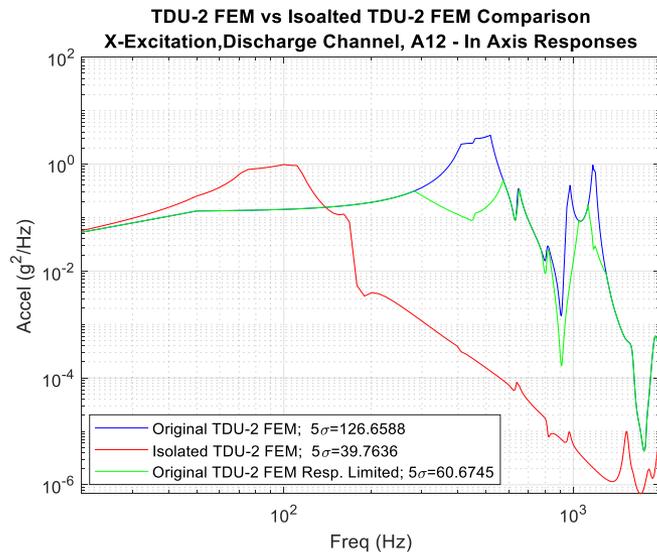
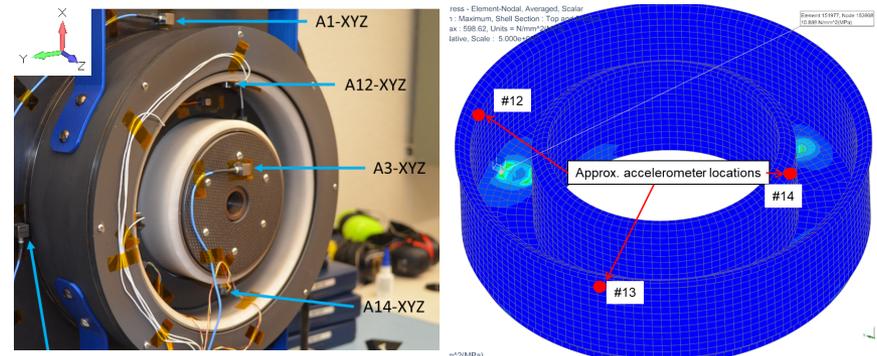
- FEM nodes near A1 & A2 were used to develop the response limit that will be used to implement the potential isolation system
- The response limit envelopes the TDU-2 Isolated FEM response and JPL minimum workmanship



# Perform RV Analysis

## Ceramic Channel Response

- Accels on tip of ceramic channel used to monitor peak stresses at base of ceramic
- Predicted Responses are well below NTE limits from 2016 test

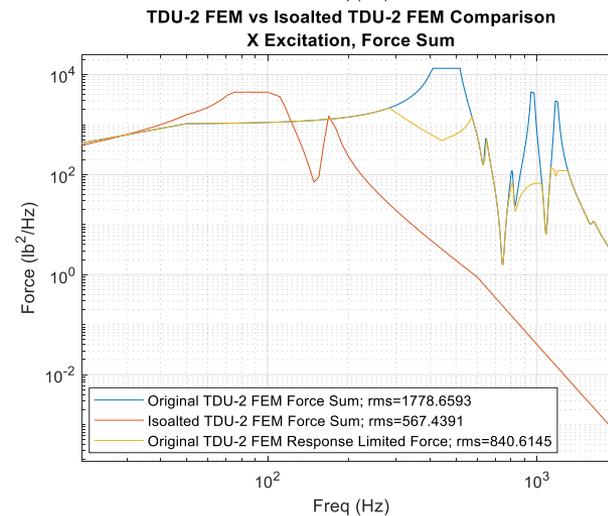
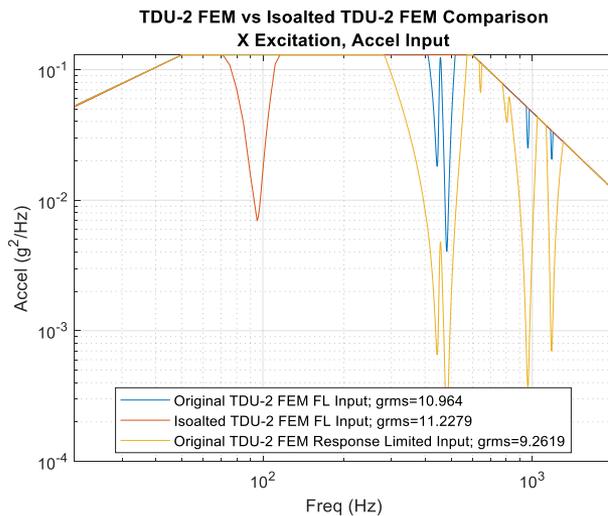
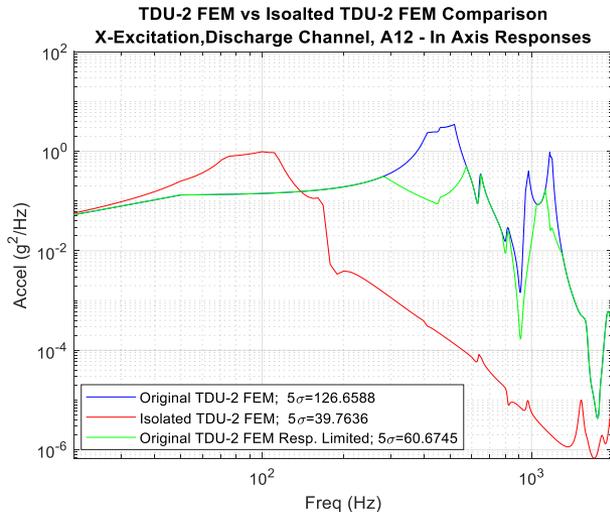


# Perform RV Analysis

## Lateral Excitation Predictions

### Lateral Excitation:

| FEM Model   | Base Force (lb) | Ceramic Accel ( $5\sigma$ ) |
|---|-----------------|-----------------------------|
| 2016 TDU FEM w/ FL                                      | 1779            | 126                         |
| 2017 TDU FEM w/ FL                                      | 567             | 39.8                        |
| 2017 TDU FEMw/ Resp Lim & Min Workmanship @ Spool Mount | 840             | 60.7                        |



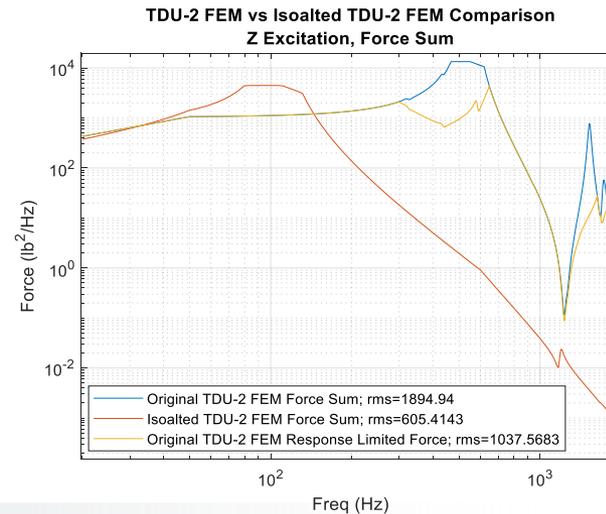
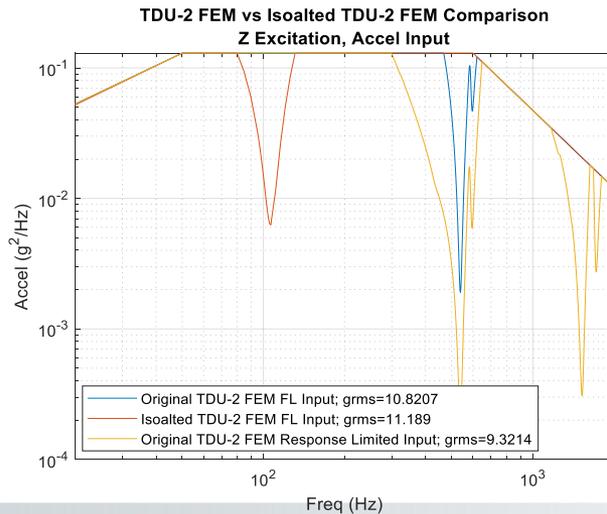
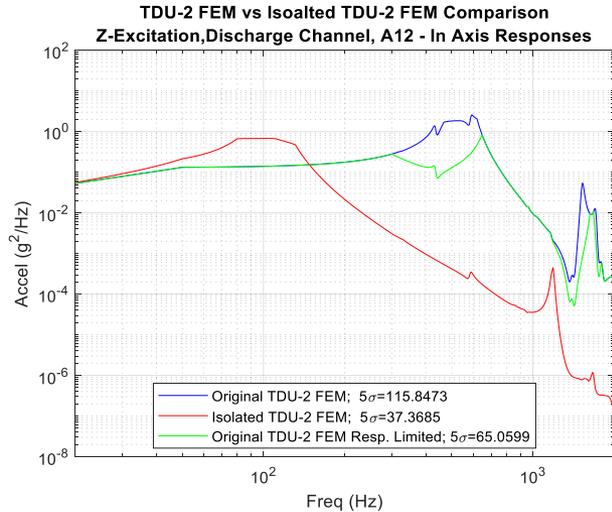
# Perform RV Analysis

## Axial Excitation Predictions

### Axial Excitation:

| FEM Model   | Base Force (lb) | Ceramic Accel (5 $\sigma$ ) |
|---|-----------------|-----------------------------|
| 2016 TDU FEM w/ FL                                      | 1895            | 115.8                       |
| 2017 TDU FEM w/ FL                                      | 605             | 37.4                        |
| 2017 TDU FEMw/ Resp Lim & Min Workmanship @ Spool Mount | 1037            | 65.1                        |

| Minimum Ceramic Chamber Stress Margin per 5 $\sigma$ Stress Results |                         |             |               |
|---|-------------------------|-------------|---------------|
| Worst Case direction is Z   | Flexural Strength (Mpa) | Min. Margin | Note          |
| 2016 TDU w/ Resp Limit - Prediction                                 | 34                      | 1.25        | Will Not Slip |



# Perform RV Test

## Test Levels, Configuration, and Instrumentation

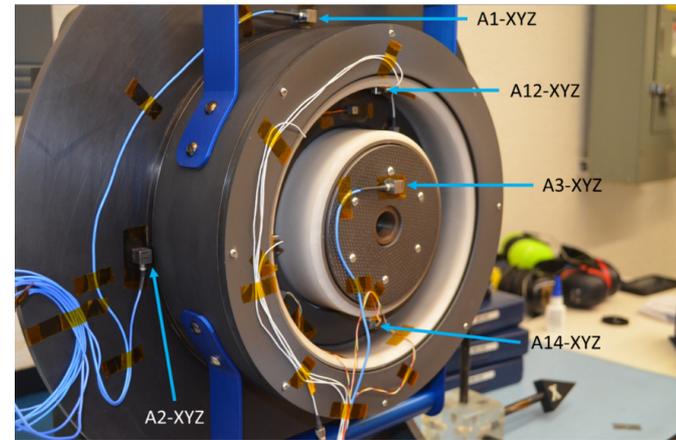
### Qual Level Input

| Frequency (Hz) | Qual Level (g <sup>2</sup> /Hz) |
|----------------|---------------------------------|
| 20             | 0.052                           |
| 50             | 0.13                            |
| 600            | 0.13                            |
| 2000           | 0.012                           |
| Overall        | 11.4 GRMS                       |
| Duration       | 120 Seconds                     |

### Response Limit applied at A1 & A2

| Frequency (Hz) | Response Limit (g <sup>2</sup> /Hz) |
|----------------|-------------------------------------|
| 20             | 3                                   |
| 150            | 3                                   |
| 450            | 0.04                                |
| 500            | 0.04                                |
| 2000           | 0.012                               |

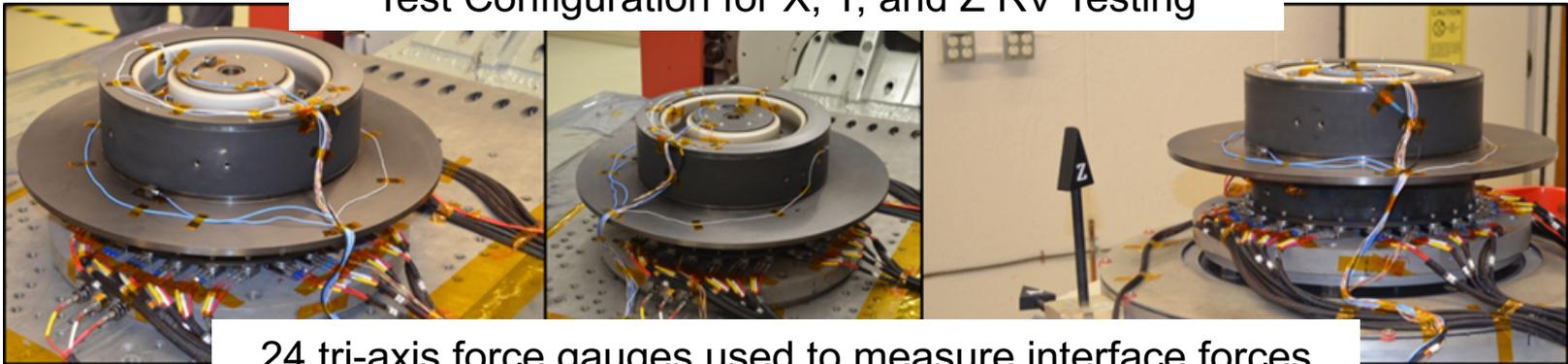
### 14 tri-axis accelerometers



### Maximum Ceramic Chamber Acceleration in Axis - 5σ (g's)

|               | 2016 TDU - Prediction | 2016 RV Test | 2016 TDU w/ Resp Limit - Prediction |
|---------------|-----------------------|--------------|-------------------------------------|
| X- Excitation | 126                   | 98           | 61                                  |
| Y- Excitation | 126                   | 92           | 61                                  |
| Z- Excitation | 116                   | 148          | 65                                  |

### Test Configuration for X, Y, and Z RV Testing



24 tri-axis force gauges used to measure interface forces

# Perform RV Test

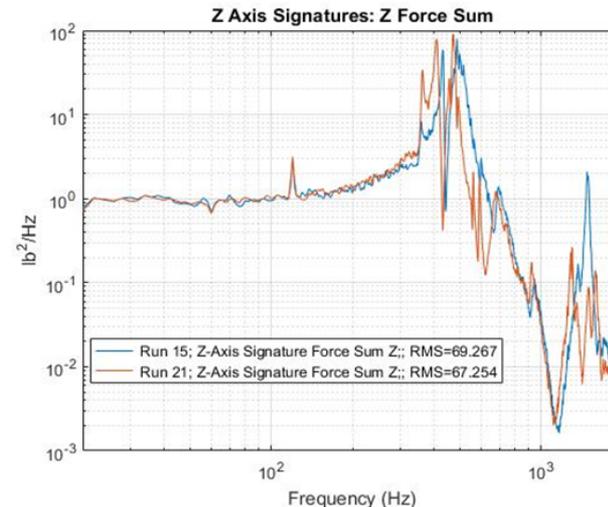
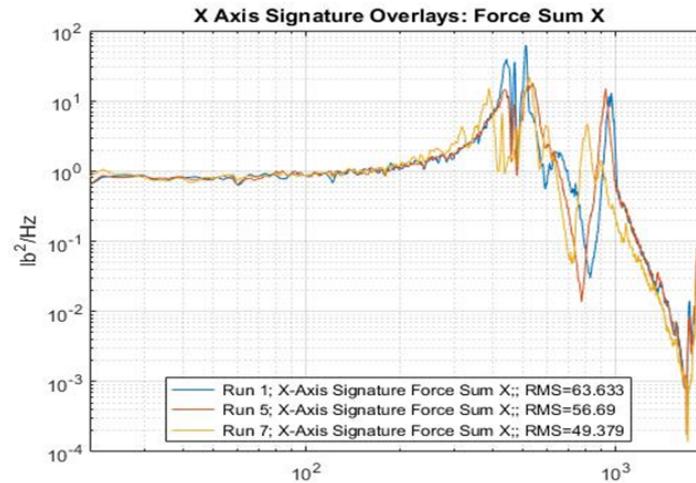
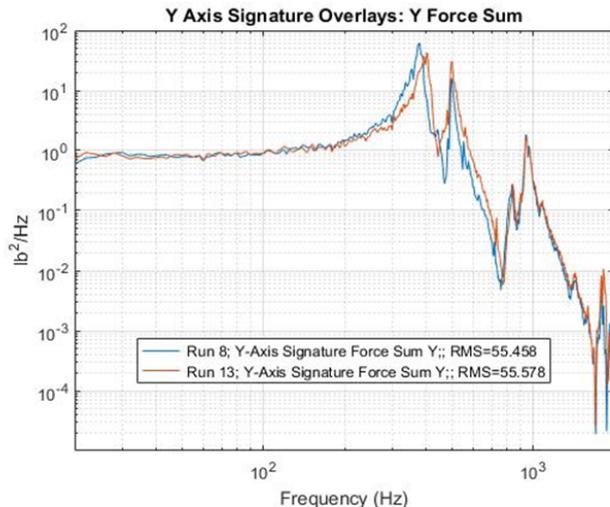
## *Test Flow*

- Performed low level pre signature at the start of each axis
- Performed low level tests w/ response limiting (-18, -12, and -6 dB)
  - *All axes showed some mode shape shifts during -6 dB*
  - *Move forward with tests as it is much less than 2016 test and ceramic accelerometers are below capability predictions*
- Performed full level tests
  - *X & Y tests completed with no visual damage to thruster or discharge channel detected*
  - *Z test (Done in two segments due to shaker abort)*
    - White particulate emitted from inner/outer core for first time this test series
    - No damage to discharge channel detected after visual inspection
- Performed low level post test signature

# RV Test Results

## Pre/Post Signatures

- Modal peaks and shape shift for all three axes
- X axis signatures (first axis tested) shows largest deviation from pre and post

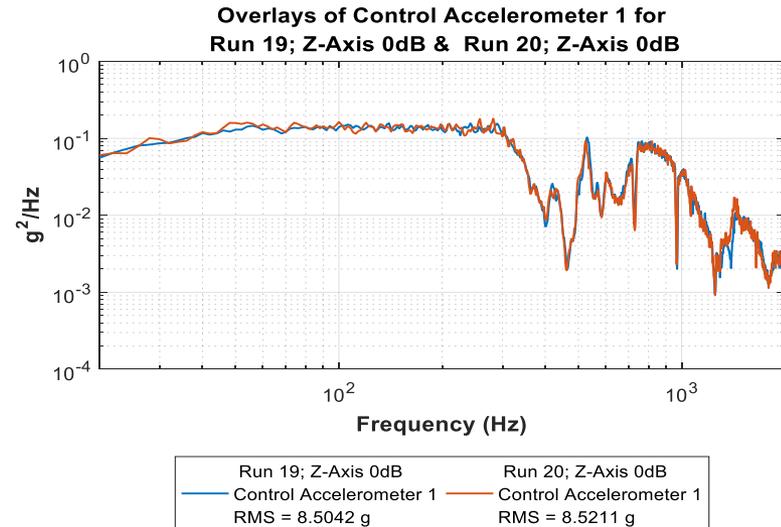
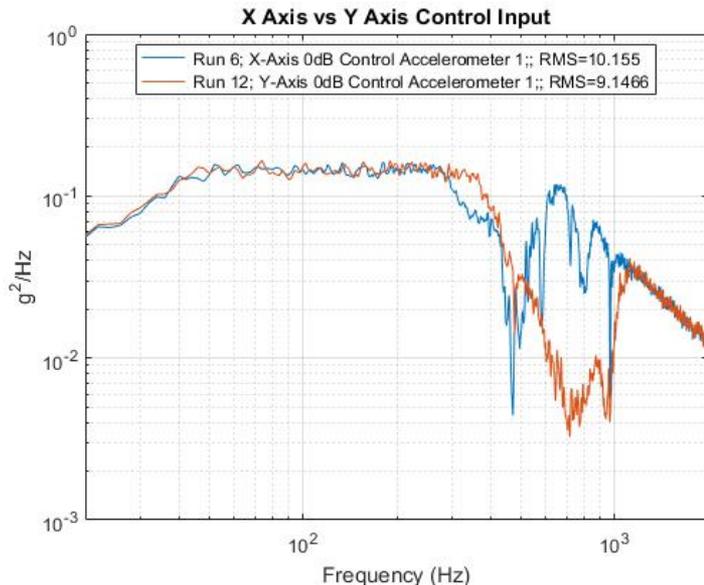


# RV Test Results

## Shaker Input & Discharge Channel Response

- Hardware damping in test was higher than analysis but max response of discharge channel accels within 10% for X & Z testing
- Y axis input was 10% lower than X axis
  - Structural shifts caused change in notching
  - Y axis discharge channel response within 20% of prediction

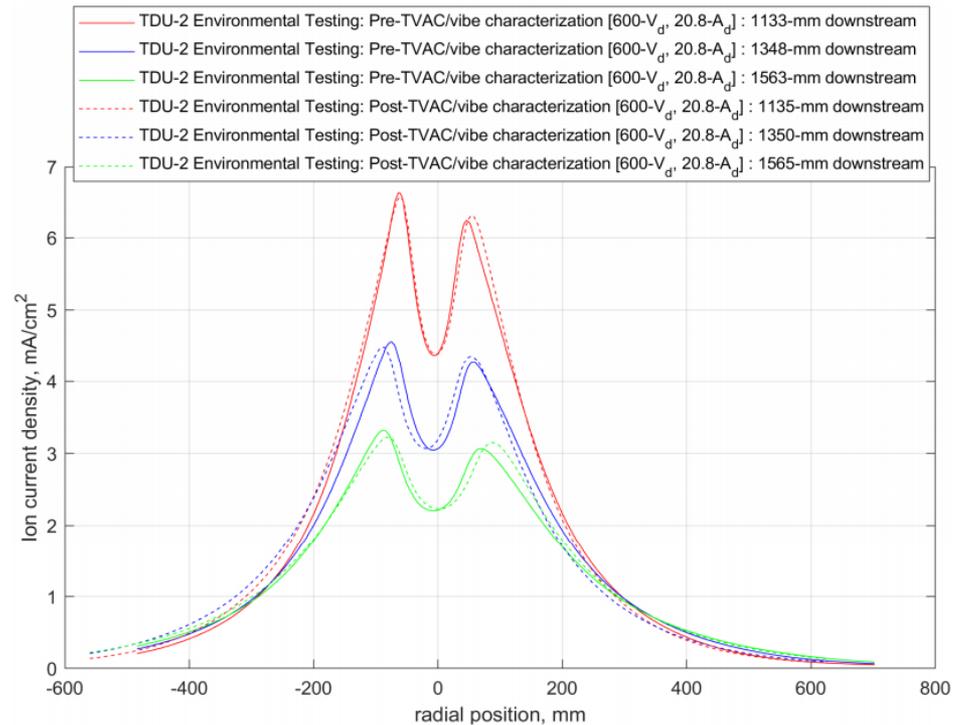
| Maximum Ceramic Channel Acceleration in Axis - $5\sigma$ (g's) |                           |       |       |       |
|--|---------------------------|-------|-------|-------|
| Axis   | TDU Resp Limit Prediction | A12   | A13   | A14   |
| X- Excitation  | 61                        | 54    | 57    | 52    |
| Y- Excitation  | 61                        | 48.5  | 45.5  | 46.5  |
| Z- Excitation  | 65                        | 57.75 | 59.75 | 62.85 |



# Environmental Testing

## Post RV Tests

- Following RV testing the thruster underwent magnetic mapping and all post RV measurements were within tolerances of pre test measurements
- The thruster then underwent functional testing in TVAC
- Following successful TVAC the magnetic mapping was once again completed with no deviations measured



# Summary

- The goal for this test series was to expose the ceramic discharge channel to predicted qualification levels based on a future design featuring an isolation system
- The following approach was taken:
  - *TDU-2 FEM modified to derive isolated responses*
  - *TDU-2 underwent RV testing w/ response limits*
  - *Environmental testing was completed following RV testing*
- The test effort was successful
  - *Discharge channel accelerometers were within 10% of predicted qual levels*
  - *Structural changes occurred but overall performance of thruster was not impacted*
- No future work by JPL dynamics team is currently planned but it would be interesting to compare results from this effort to future test

# Questions?