



Session 9 Special Tests

Testing the Mars Helicopter

Author:

G.L. Seal, Jet Propulsion Laboratory, California Institute of Technology

SPEAKER: Gabriella L. Seal

e-mail: Gabriella.L.Seal@jpl.nasa.gov

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Agenda

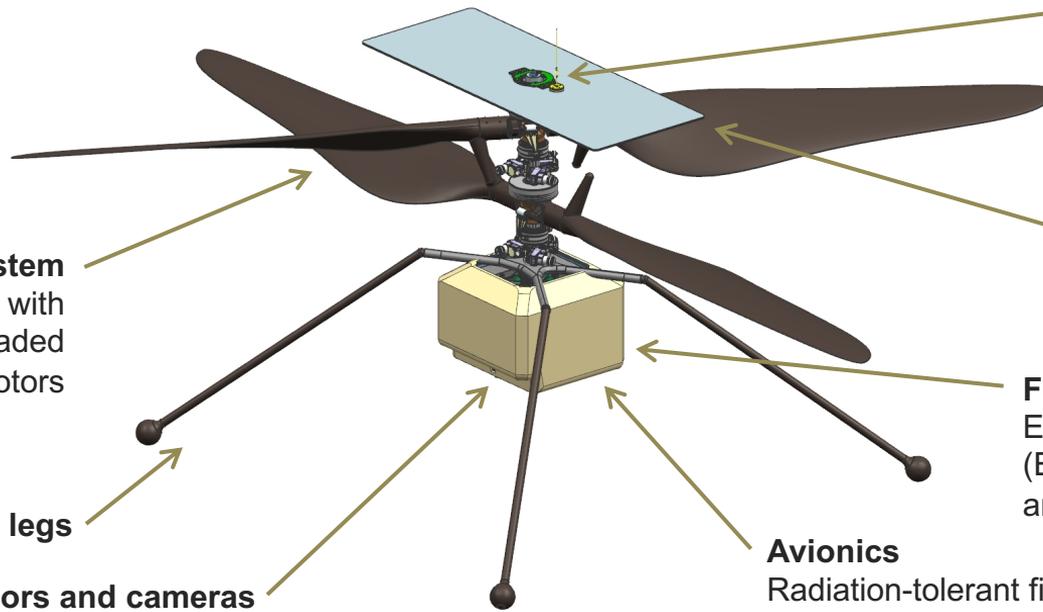
- Overview of the Mars helicopter technology demonstration
- Testing the Mars helicopter
 - Key challenges
 - Our approach
 - Results and discussion
- Conclusions and acknowledgements

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Overview of the Mars Helicopter

~1.2 m in diameter, <1.8 kg, 2800 max rpm



Telecommunication
Command and communication via base station on Mars 2020 rover

Solar panel

Fuselage
Electronics core module (ECM) housing batteries and electronics

Avionics
Radiation-tolerant field programmable gate array (FPGA), dual-redundant automotive-grade processors, and flight control algorithms

Rotor system
Coaxial design with counter-rotating two-bladed carbon fiber rotors

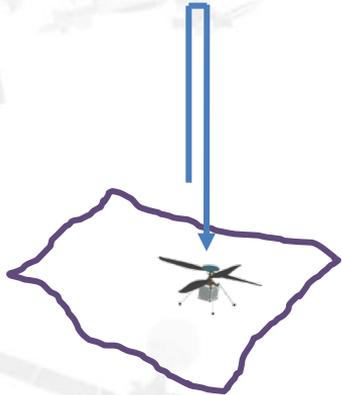
Lightweight landing legs

Sensors and cameras
Inertial measurement unit (IMU), altimeter, inclinometer, navigation camera, and color camera

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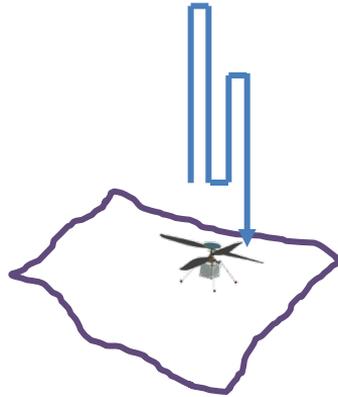


Helicopter Technology Demonstration (Notional)



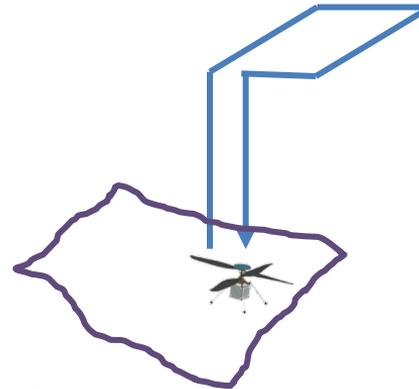
Flight 1

Ascend, hover, land



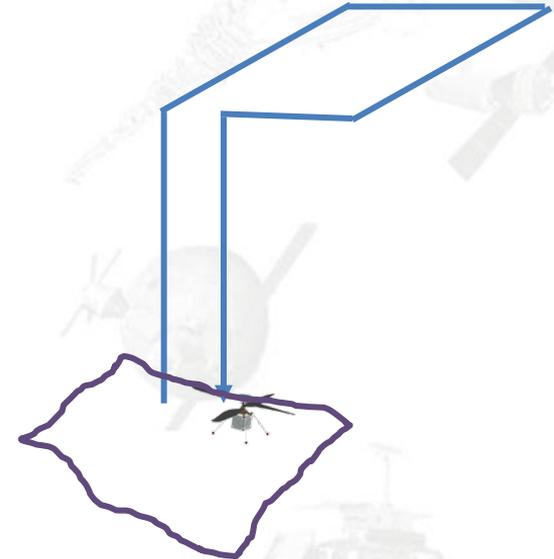
Flight 2

Vertical ascent and
descent profiles at
different thrust settings



Flight 3

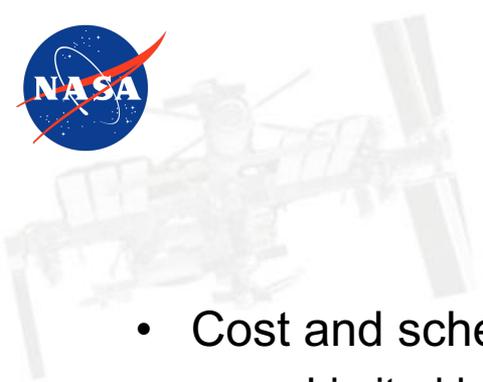
Lateral flight path that
returns to starting point



Flights 4–5

More challenging flight paths
(e.g., larger lateral flights that
return to safe experiment area,
increased altitude)

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Key Challenges

- Cost and schedule constraints
 - Limited budget, no room for error
- Unknown delivery system
 - Uncertain vibration and shock environment, boundary conditions
- Helicopter unable to lift its own weight on Earth
 - Need sophisticated support equipment
- No joystick
 - Helicopter must fly autonomously in a range of environmental conditions (ground terrain, wind speed and direction, etc.)



Our Approach

- **Modeling and analysis** of flight dynamics to inform design of both the vehicle and the control algorithms
- Limited **system identification testing** to characterize the flight dynamics of the as-built vehicle in partially replicated Mars conditions
- **Engineering development model (EDM)** helicopter as a learning platform for vehicle and test fixture characterization



(Partially) Replicating Mars Conditions

- Mars gravity
 - Gravity offload system
 - Tether affects the fidelity of the system dynamic response
- Steady-state wind
 - Low-speed swing-arm motions, high-speed wind wall with fixed helicopter
- Terrain
 - Mock surfaces, visual targets with appropriate lighting for navigation



Hover Test, Engineering Development Model



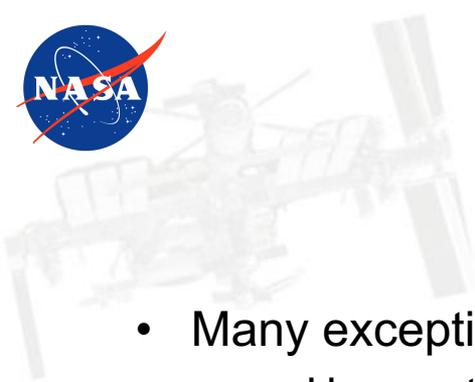
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Flight Helicopter Test Campaign

- Environmental testing
 - Thermal vacuum/Mars pressure to validate survival energy predictions and demonstrate start-up and functionality at cold
 - Random vibration with delivery system
 - Shock (via deployment device firings)
- Abbreviated system identification testing
 - Full spin in Mars atmosphere
 - Motor characterization at hot and cold

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Conclusions

- Many exceptions to the “test as you fly” principle
 - Have not tested helicopter with base station
 - Have not demonstrated flight at colder than room temperature
 - Have not fully simulated Mars wind conditions, particularly transient gusts
 - Have not tested navigation sensors (camera, lidar) with realistic Mars terrain
 - Have not tested helicopter take-off or landing with realistic Mars terrain, particularly slope
- However, the piecemeal approach used in the EDM and FM helicopter test campaigns gives us confidence that the helicopter will operate as intended during the mission



Thank you: Michael Kokorowski, MiMi Aung, Bob Balaram,
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