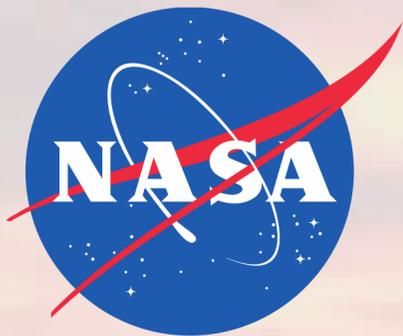


# Thermal Modeling of Mars Ground for Surface Missions

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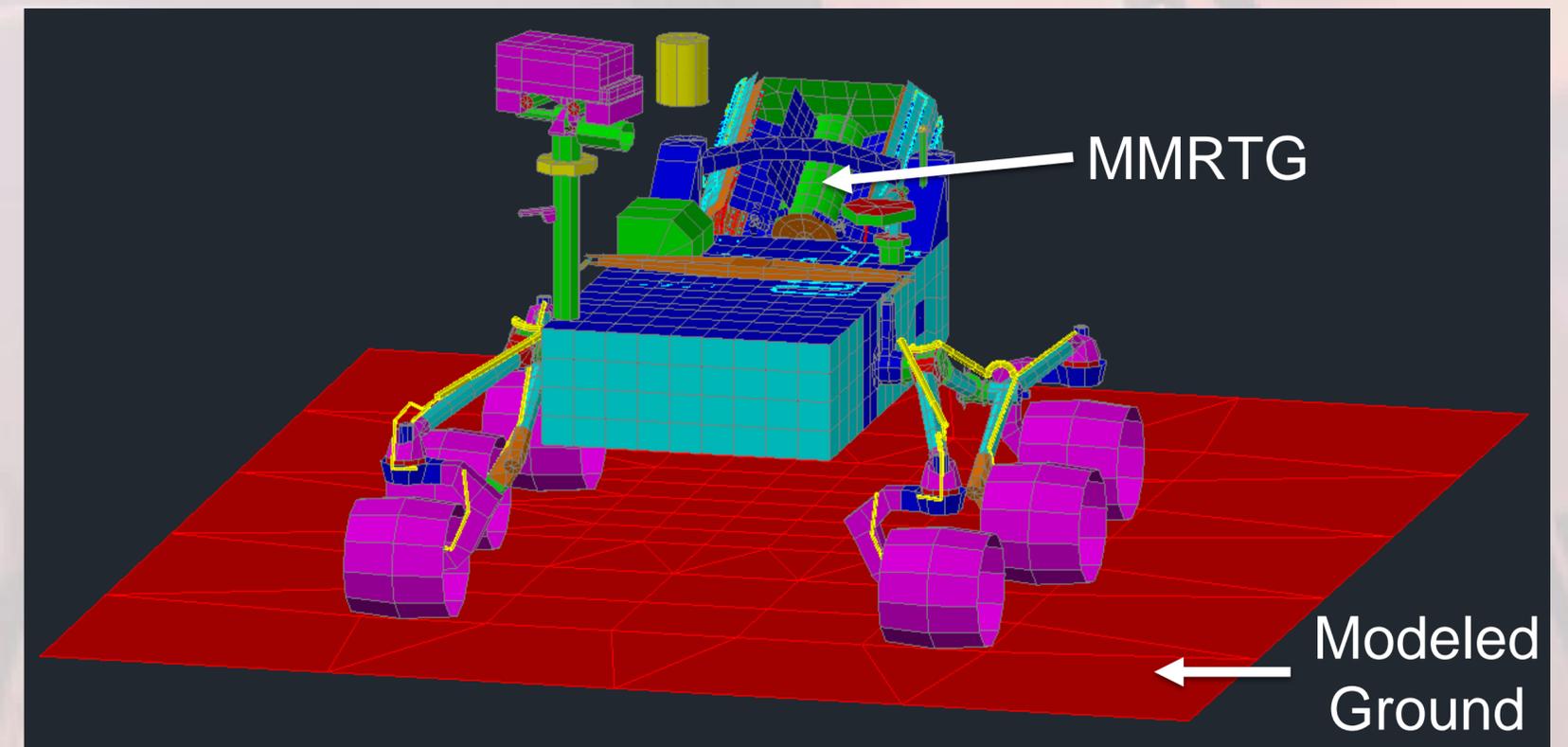
# Outline

- Ground modeling introduction
- Worst Case Cold and Worst Case Hot environments
- Local ground modeling
- Effects of Mars 2020 rover on local ground
  - Shadowing
  - MMRTG dissipation
- Subsurface ground temperatures
- Conclusions

# Introduction

- Thermal modeling software has capability of including ground temperature as a boundary. This approach does not capture local ground interactions which could change the ground temperature.
- Interest in explicit ground modeling:
  1. Mars 2020 Rover Model: capture effects of rover shadowing and Multi Mission Radioisotope Thermoelectric Generator (MMRTG) heat dissipation
  2. Sample Acquisition: understand temperature history of subsurface ground

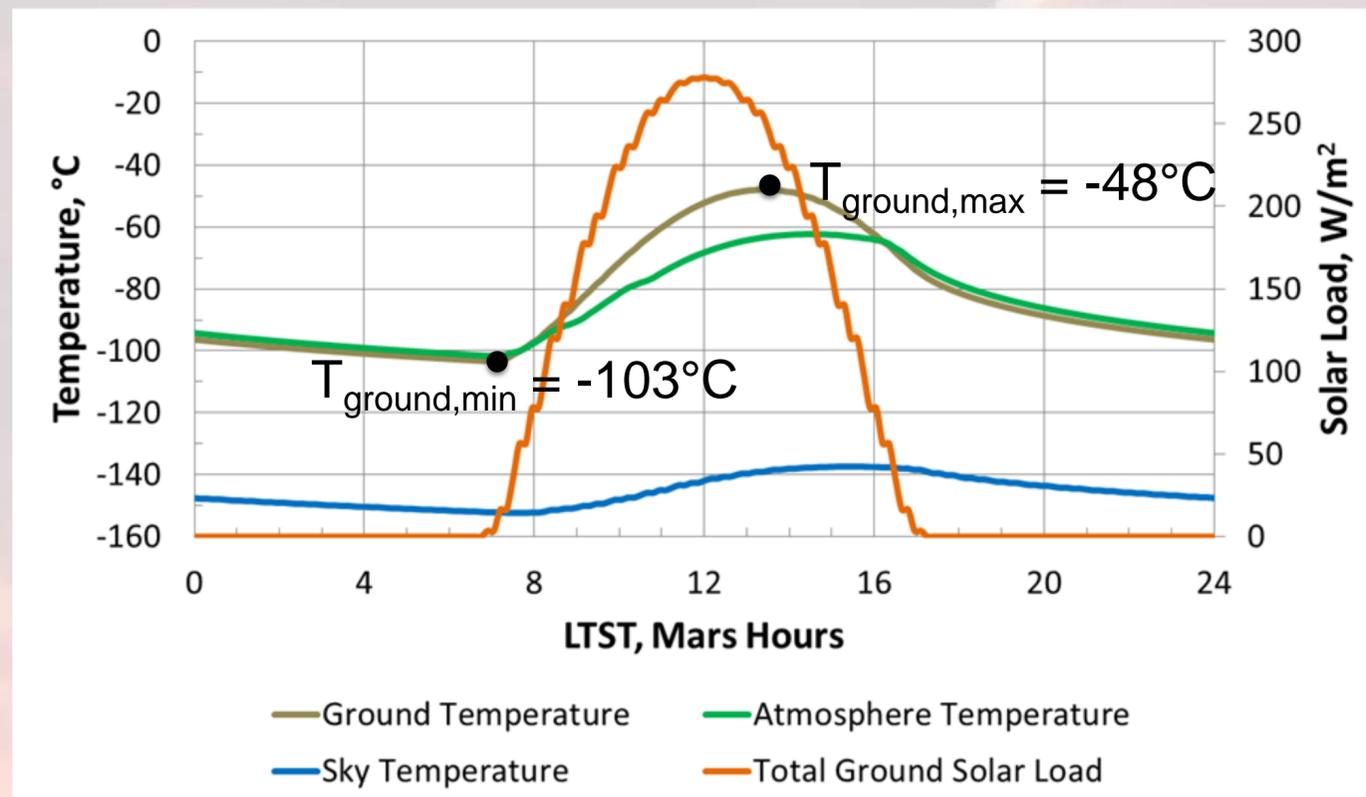
## Mars 2020 Rover System Thermal Model



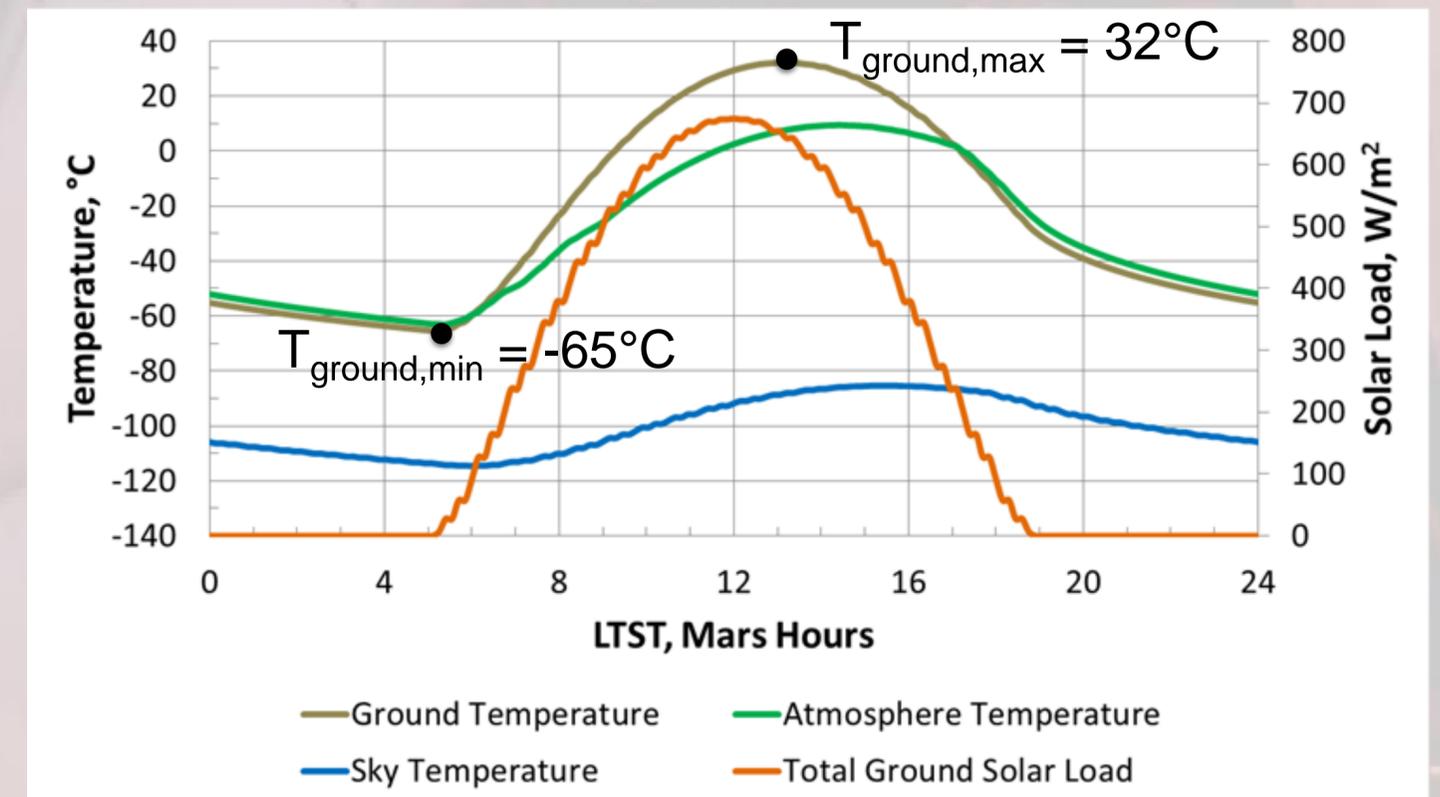
# WCC and WCH Environments

- A detailed Mars Weather Research and Forecasting General Circulation Model (MarsWRF GCM) is used to generate environment predictions at a given latitude
  - Ground Temperature, Atmosphere Temperature, Sky Temperature, Solar Load
- Bounding Worst Case Cold (WCC) and Worst Case Hot (WCH) environments generated from potential Mars 2020 landing sites. Results (Holden Crater, 26° S) used in thermal analysis as far-field boundary conditions

## WCC

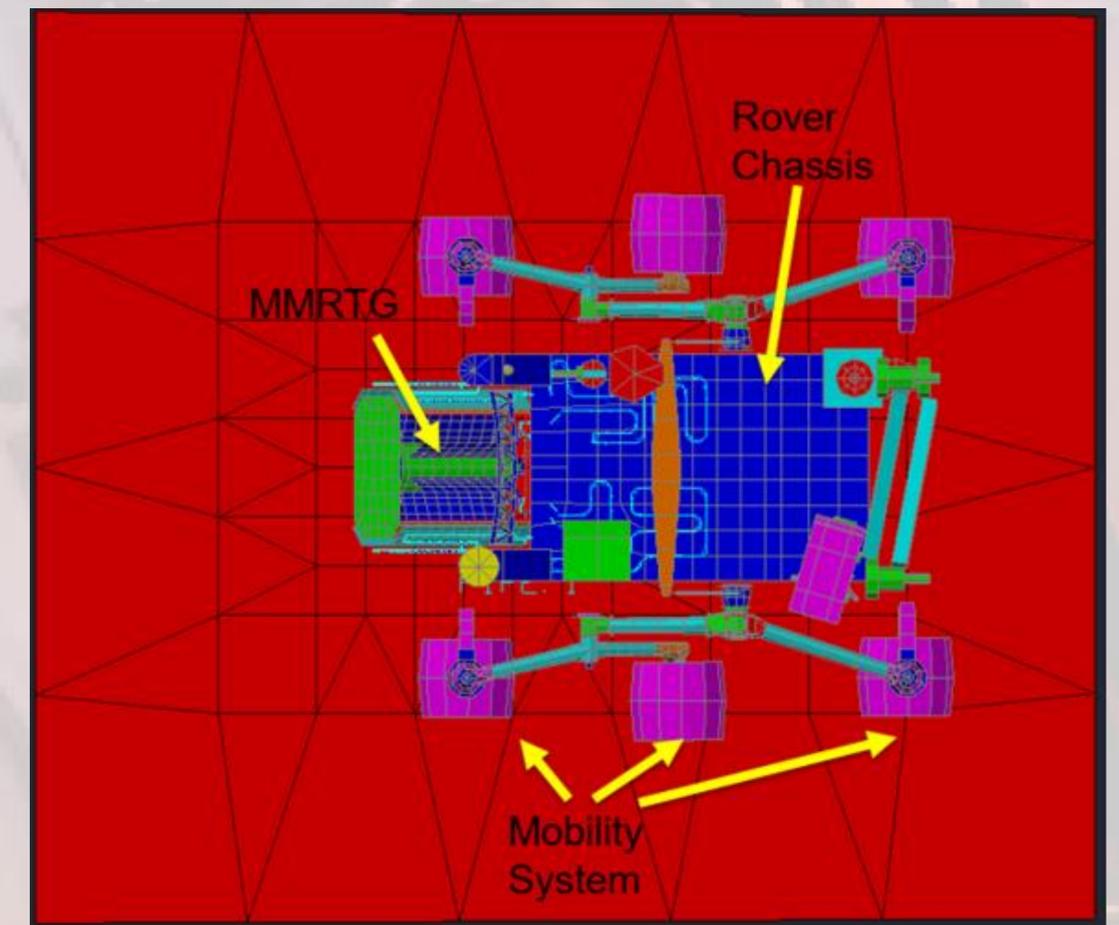
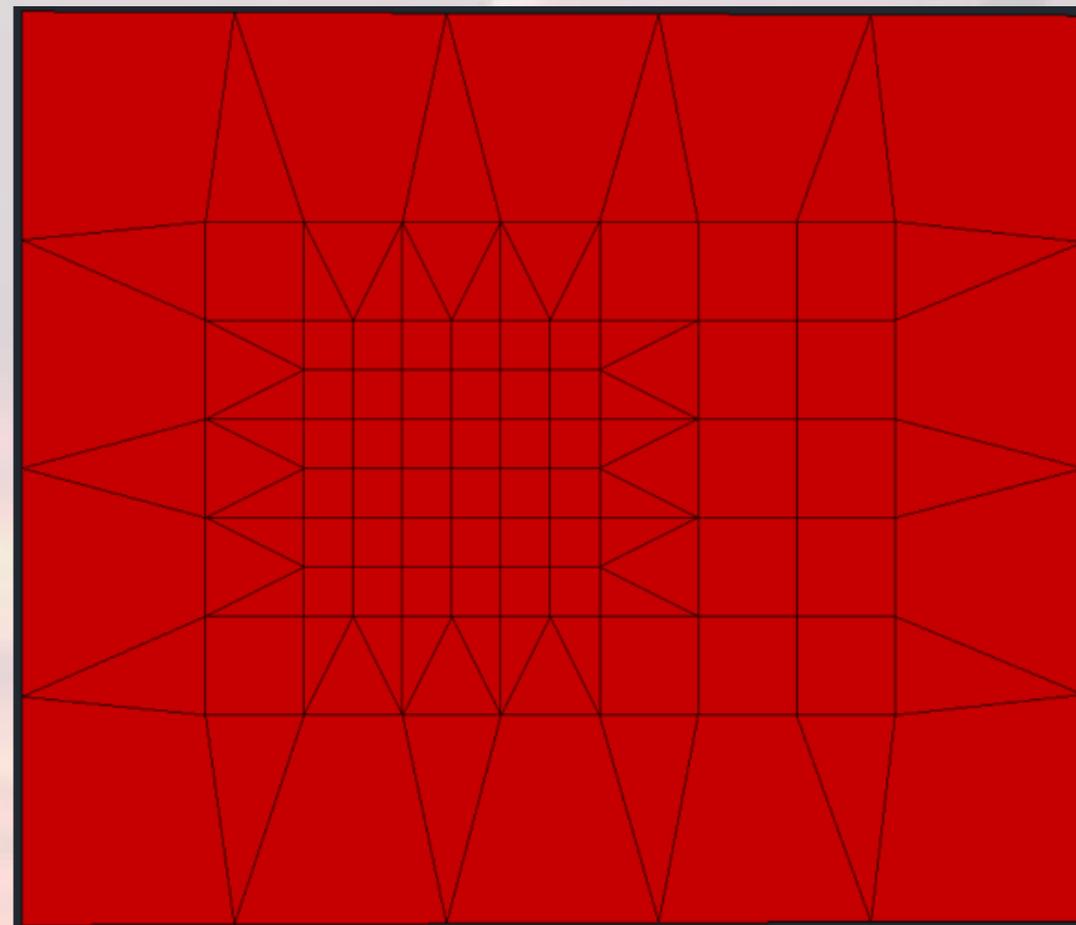
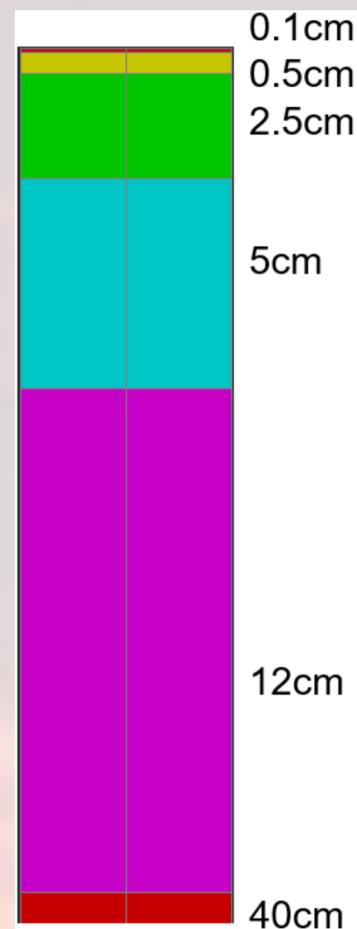


## WCH



# Ground Modeling

- Use of MarsWRF GCM environments is appropriate for far-field boundary conditions, but are not accurate for local regions that interact with hardware of interest
- A 5.4m x 4.6m patch of ground is modeled to depth of 60cm (7 node discretization)
- Rover model placed above ground surface



# Ground Modeling

- Ground thermophysical and thermoptical properties are obtained from Thermal Emission Spectrometer (TES) measurements, onboard the Mars Global Surveyor

<b>Thermal Inertia, <math>I</math></b>	<b>362 <math>\text{Jm}^{-2}\text{K}^{-1}\text{s}^{-1/2}</math></b>
<b>Thermal Conductivity, <math>k</math></b>	<b>0.1092 <math>\text{Wm}^{-1}\text{K}^{-1}</math></b>
<b>Density, <math>\rho</math></b>	<b>1500 <math>\text{kgm}^{-3}</math></b>
<b>Heat Capacity, <math>c_p</math></b>	<b>800 <math>\text{Jkg}^{-1}\text{K}^{-1}</math></b>
<b>Solar Absorptivity, <math>abs</math></b>	<b>0.868</b>
<b>IR Emissivity, <math>\epsilon</math></b>	<b>0.95</b>

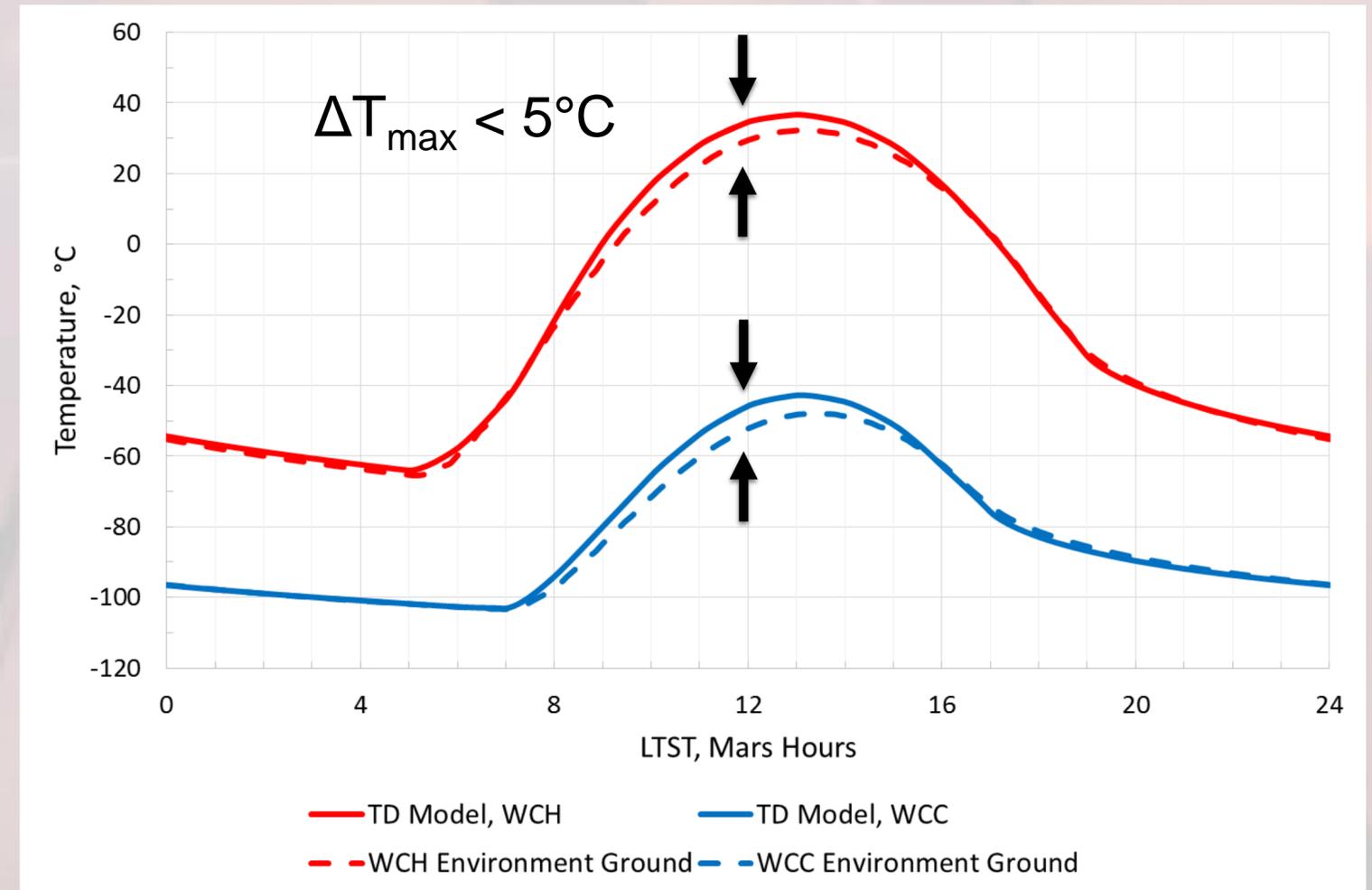
- Ground is modeled to 0.6m to account for full thermal penetration depth
  - Closed form solution of semi-infinite body with a sinusoidal varying wall temperature ( $T=24.6$  hours):

$$d = 4.61 \sqrt{\frac{2\alpha}{\omega}}$$

$$d = 6.52 \sqrt{\frac{kT}{\rho c_p}} = 0.6m$$

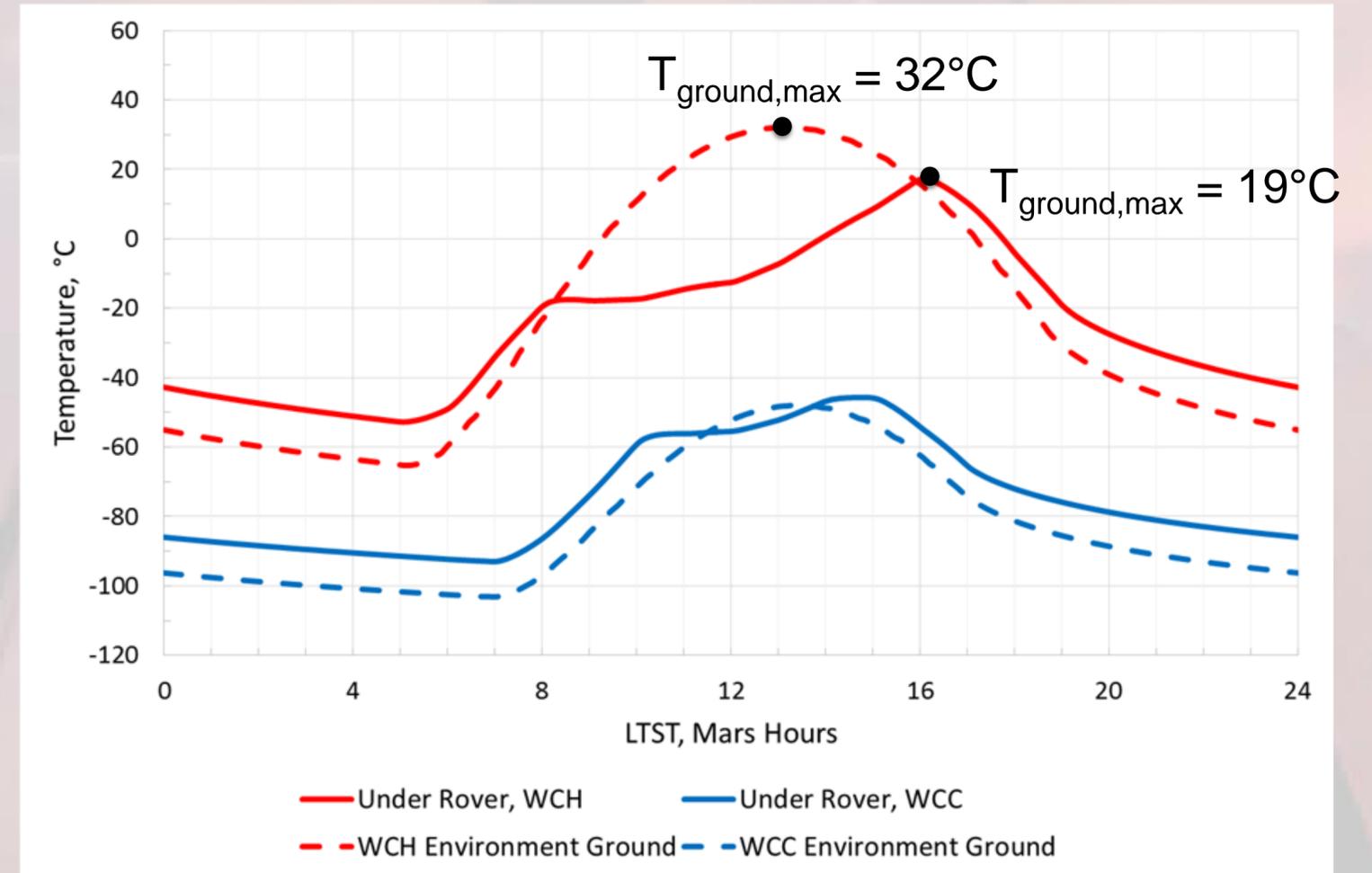
# Ground Temperature Comparison

- Ground model first run without rover. Atmosphere-Ground convection was added in order to match ground temperature results to the MarsWRF GCM results.
  - $h=1.0 \text{ W/m}^2\text{K}$  for WCC
  - $h=1.5 \text{ W/m}^2\text{K}$  for WCH
- Explicitly modeled ground is within  $5^\circ\text{C}$  of the MarsWRF GCM environment results



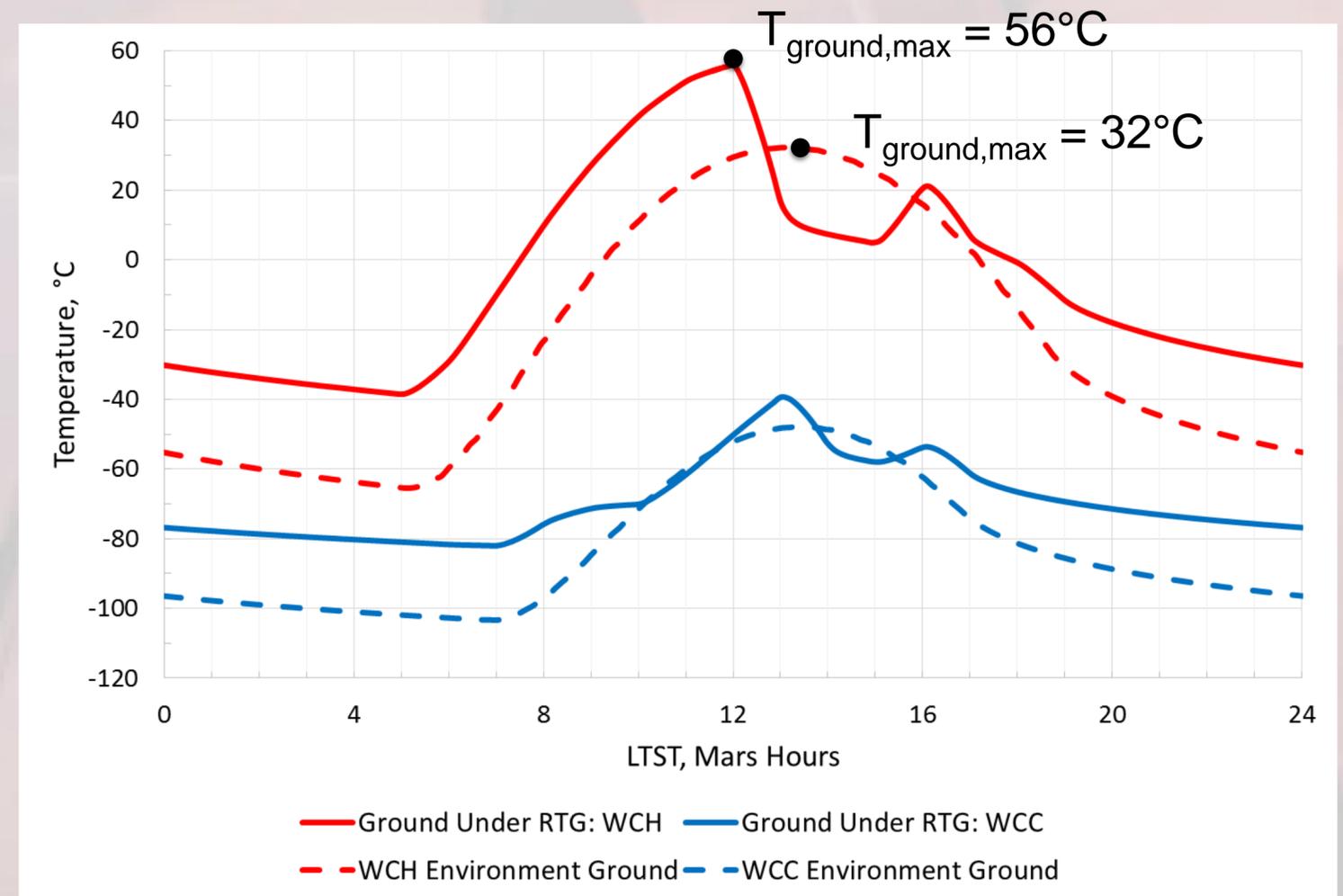
# Shadowing from Rover Chassis

- The rover chassis shadows the ground resulting in:
  - Colder daytime temperatures as the chassis blocks incoming solar flux
  - Warmer nighttime temperatures as the chassis blocks radiation heat loss to the sky



# MMRTG Heat Dissipation

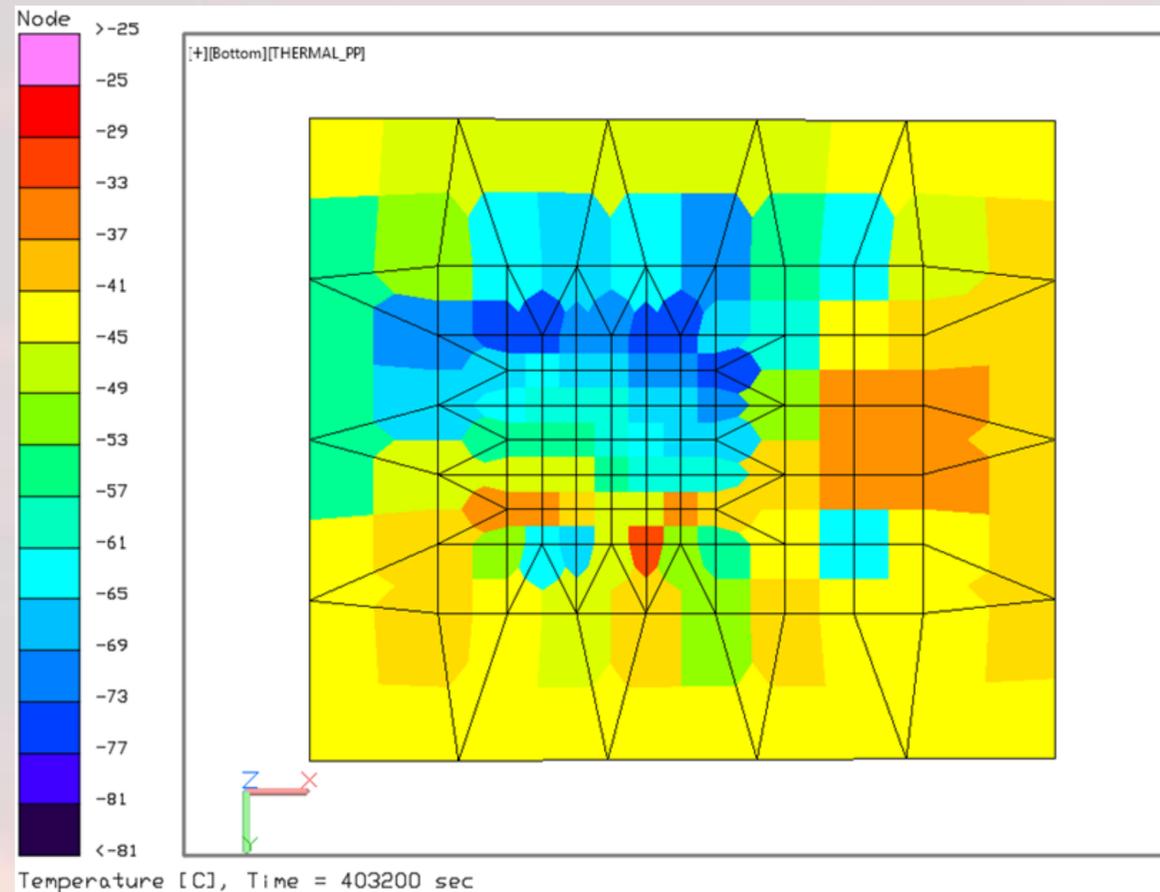
- The MMRTG operates as hot as  $200^{\circ}\text{C}$  and dissipates  $\sim 2000\text{W}$  of heat, resulting in a local ground temperature rise over the course of the entire day
- Effects of shadowing are still present



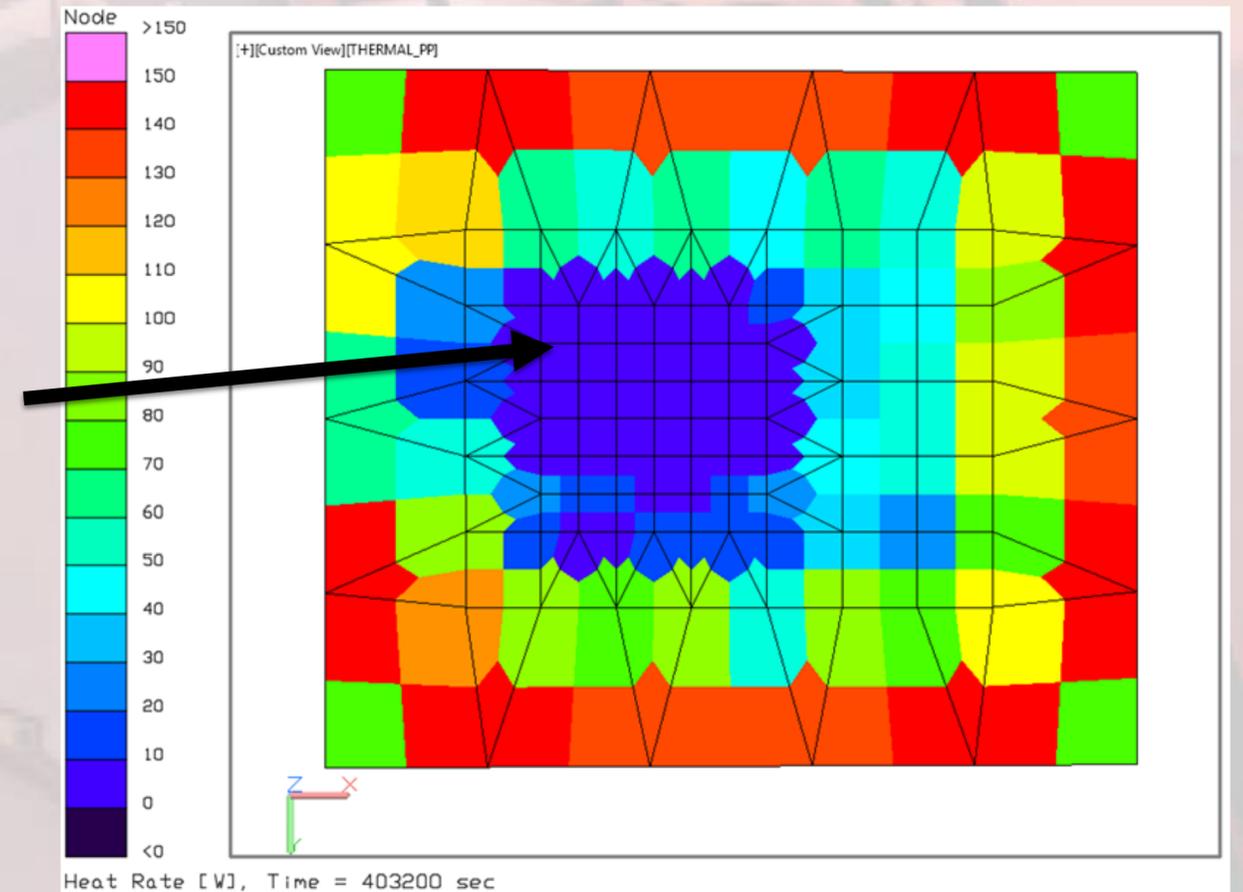
# WCC Contour Plots

- Plots for warmest time of day (13:00 LTST)

## Temperature (C)



## Heat Rate (W)

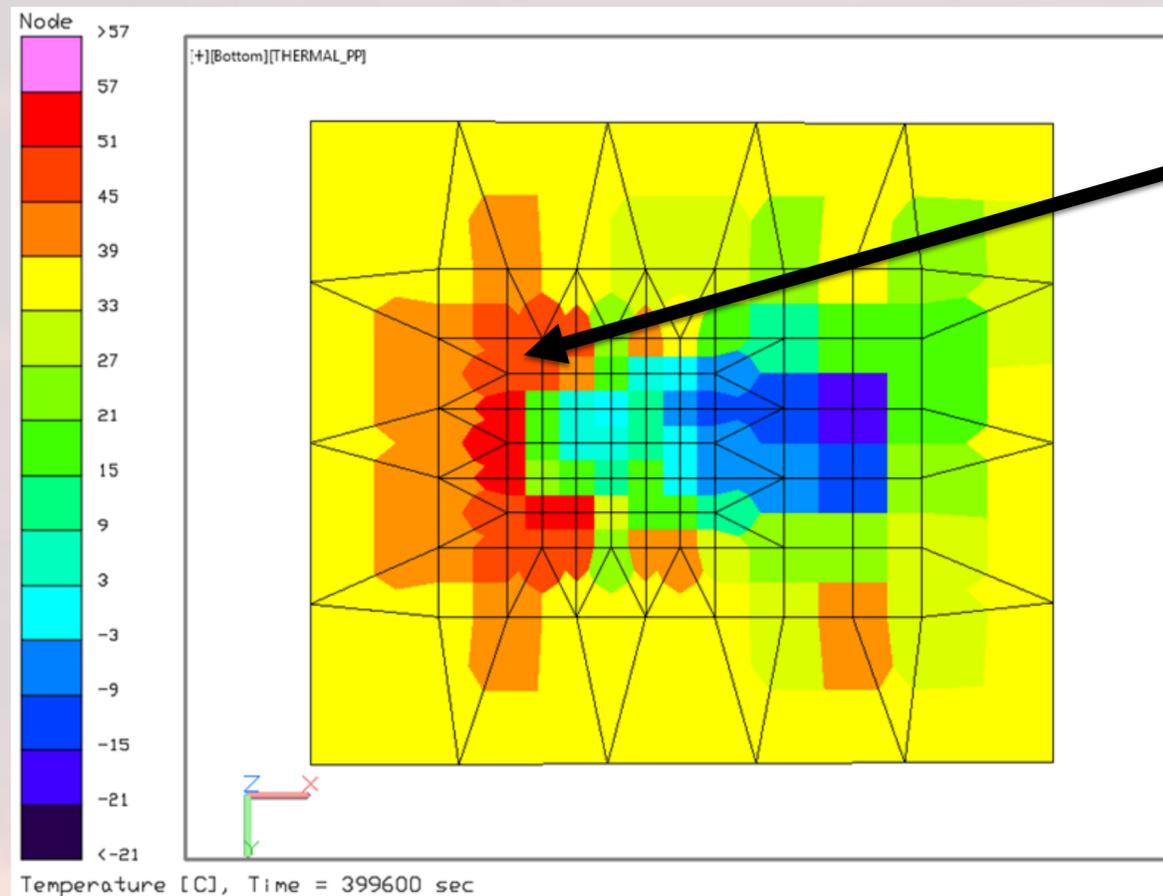


Effect of  
shadowing  
visible

# WCH Contour Plots

- Plots for warmest time of day (12:00 LTST)

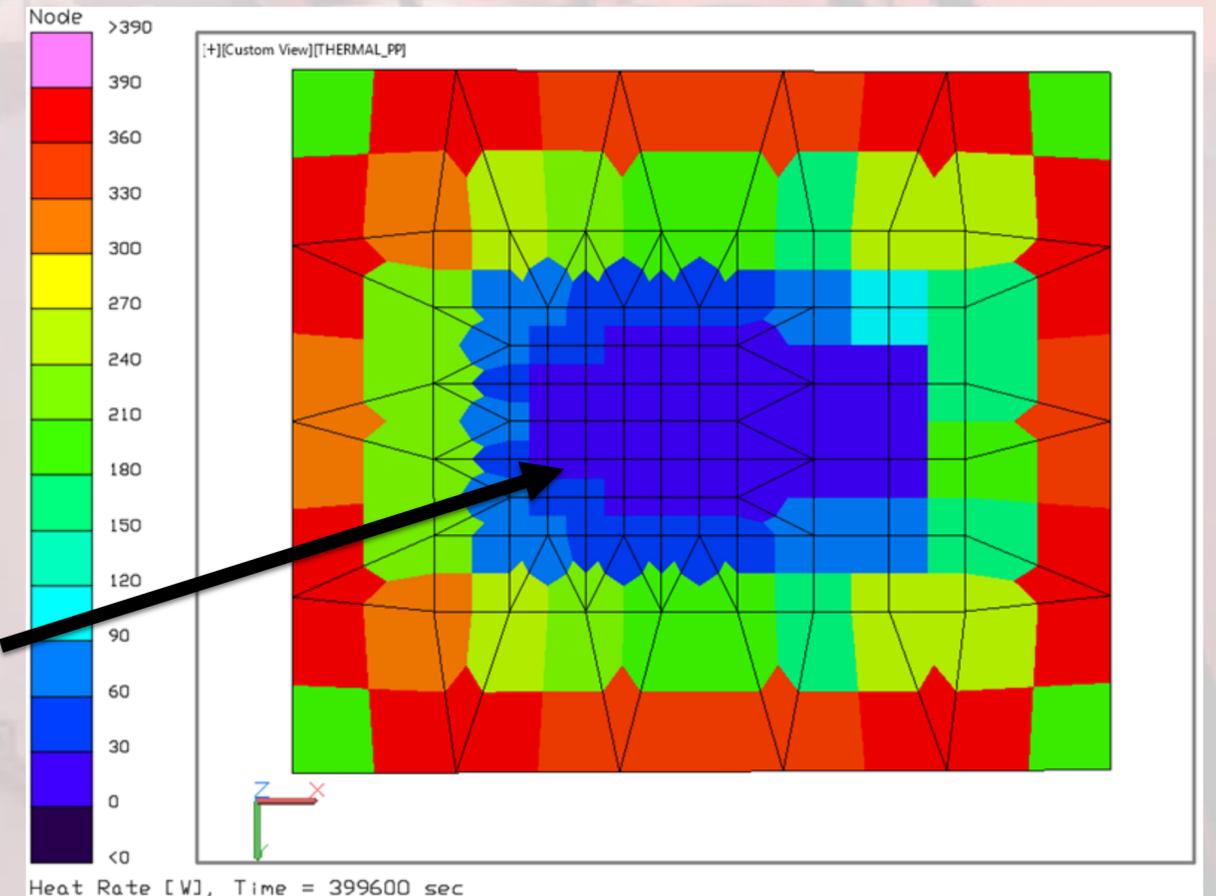
## Temperature (C)



Effect of  
MMRTG  
visible

Effect of  
shadowing  
visible

## Heat Rate (W)



# Subsurface Ground

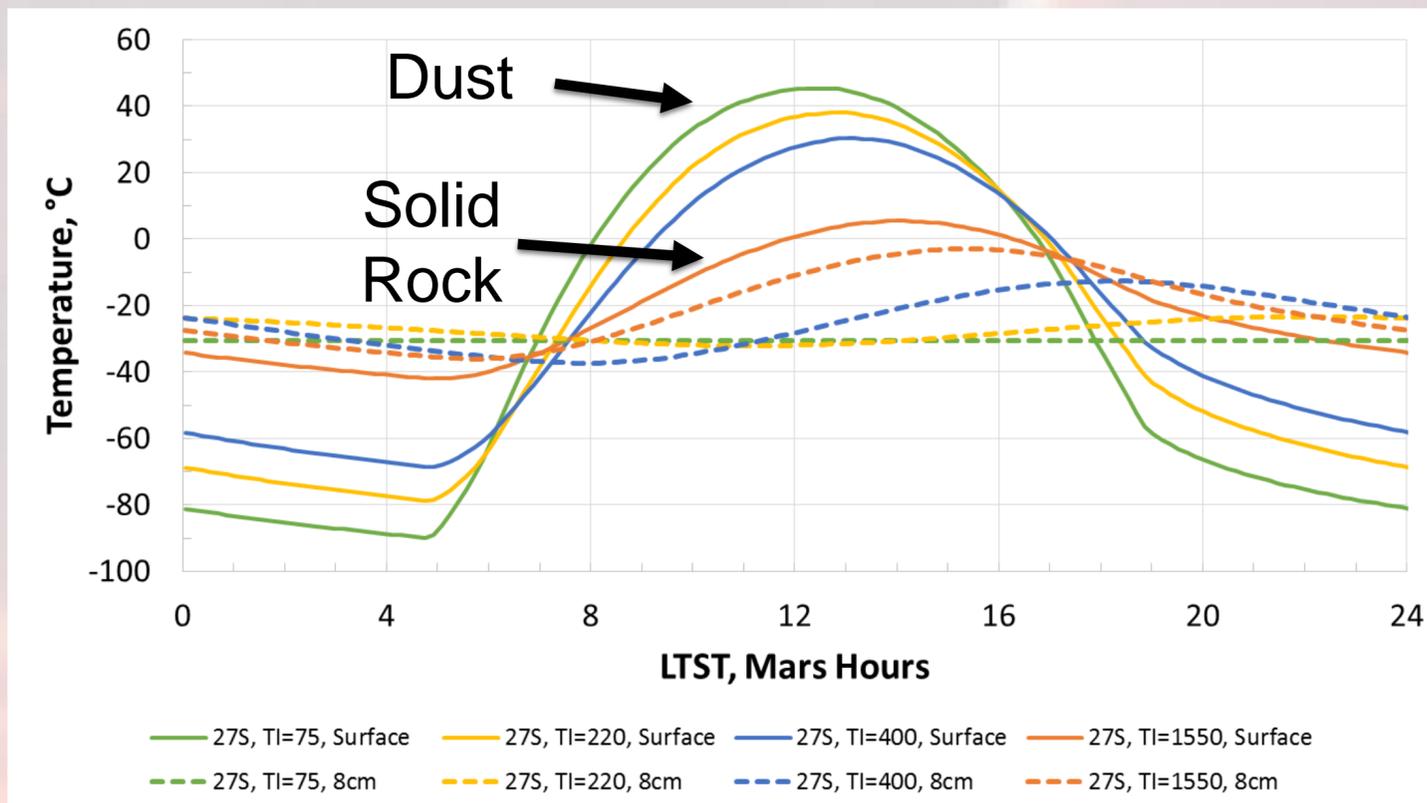
- One of the goals for the Mars 2020 mission is collect rock and regolith samples from a depth of up to 8cm
- The temperature at 8cm depth is different than on the surface, so knowing the temperature history of the sample may be useful during science measurements
- Collected samples will vary from loose dust to solid rock, resulting in a wide range of expected ground thermal conductivities and penetration depths:

	<b>Thermal Inertia, <math>I</math> <math>\text{Jm}^{-2}\text{K}^{-1}\text{s}^{-1/2}</math></b>	<b>Thermal Conductivity, <math>k</math> <math>\text{Wm}^{-1}\text{K}^{-1}</math></b>	<b>Penetration Depth, <math>d</math> m</b>
<b>Dust</b>	<b>75</b>	<b>0.0047</b>	<b>0.121</b>
<b>Loose (Sandier) Regolith</b>	<b>220</b>	<b>0.04</b>	<b>0.356</b>
<b>Consolidated (Rockier) Regolith</b>	<b>400</b>	<b>0.1333</b>	<b>0.648</b>
<b>Solid Rock</b>	<b>1550</b>	<b>2.0</b>	<b>2.509</b>

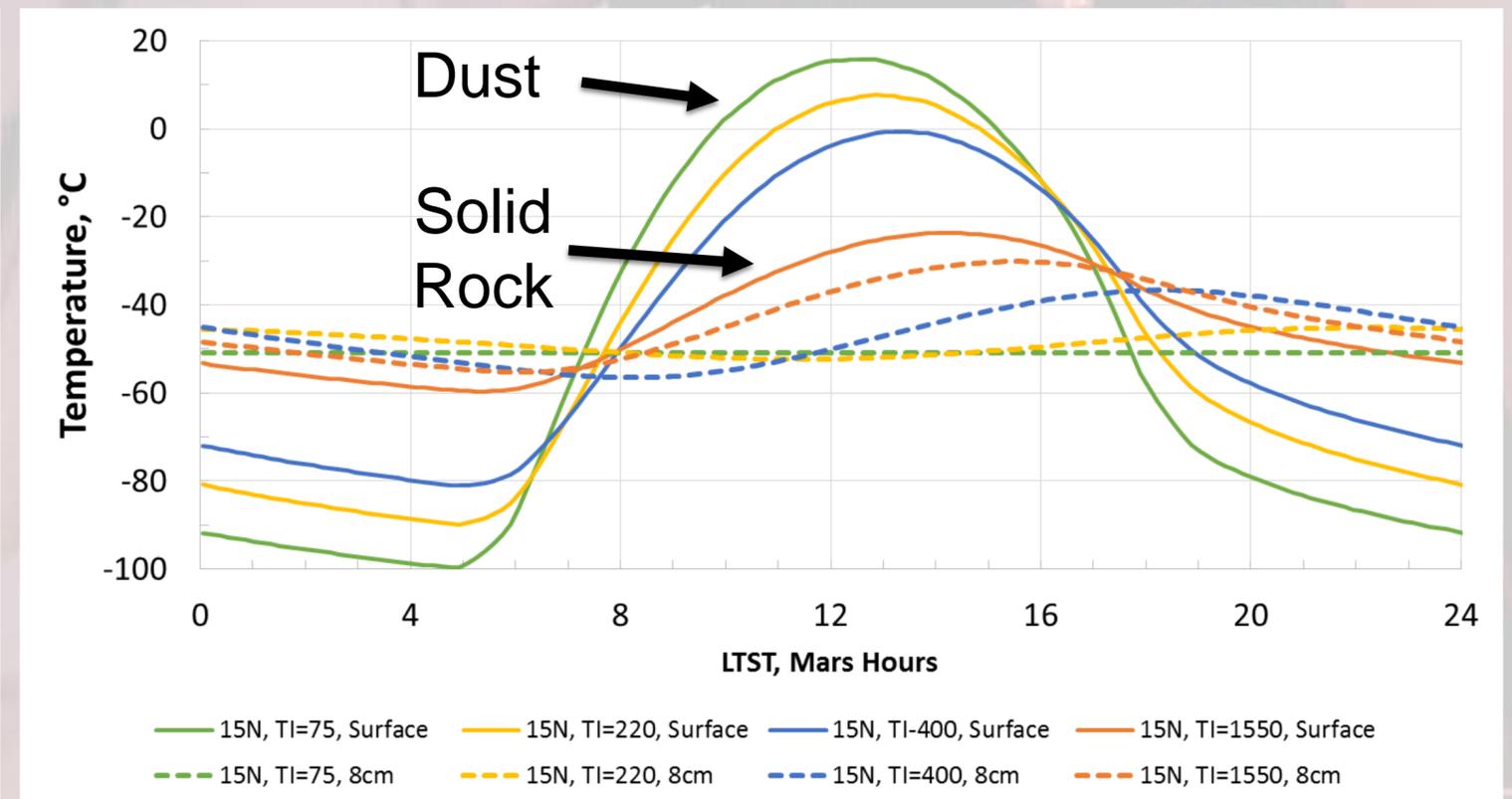
# Subsurface Ground

- Diurnal temperature variation at 8cm depth is less than at the surface
- Low thermal inertia ground types result in more extreme surface variation and less extreme subsurface variations
- High thermal inertia ground types result in less extreme surface variation and more extreme subsurface variations

## Temperatures at 27°S Summer

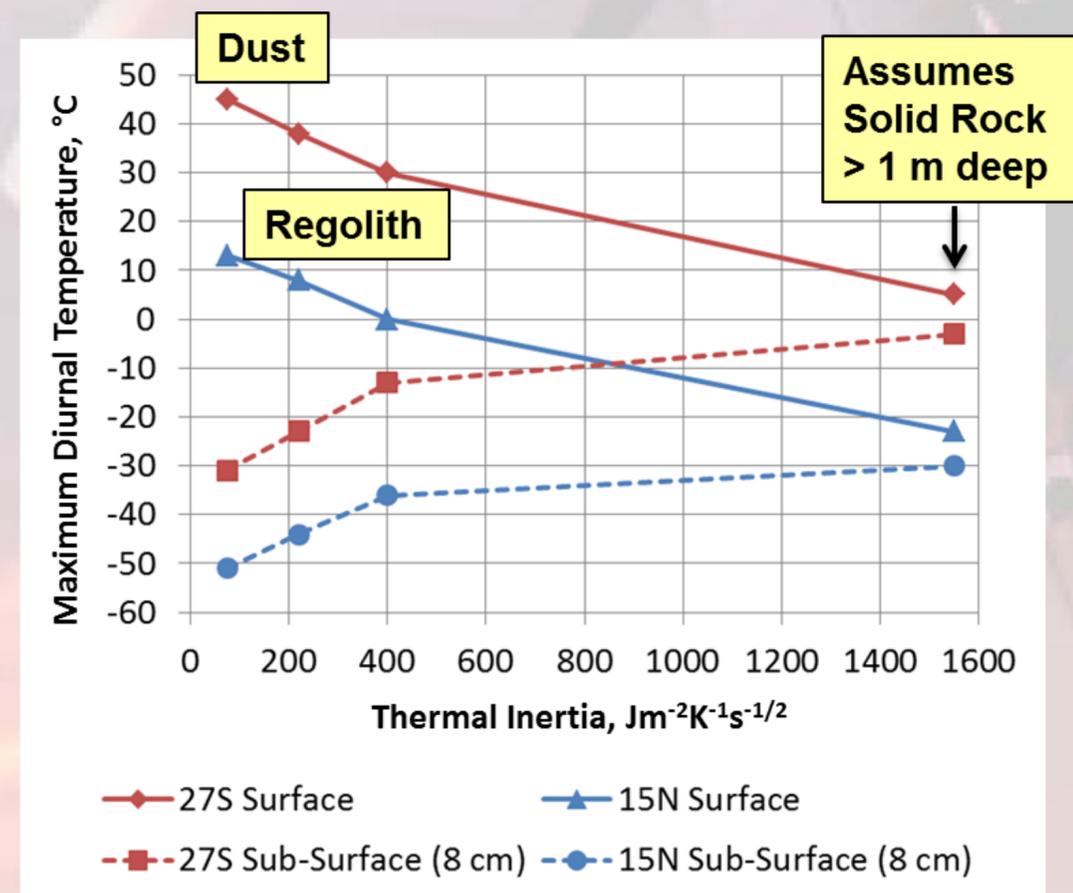


## Temperatures at 15°N Summer



# Subsurface Ground

- Low thermal inertia ground types have warmer peak surface temperatures, cooler subsurface temperatures, and larger gradients
- High thermal inertia ground types have cooler peak surface temperatures, warmer subsurface temperatures, and smaller gradients



# Conclusions

- A simple method of modeling Mars ground has been demonstrated that accurately match the more complex MarsWRF GCM predictions
- Effects of Mars 2020 rover shadowing and MMRTG dissipation on local ground have been analyzed
- Surface and subsurface ground temperatures have been analyzed for a wide range of ground types and allows for estimating temperature history of collected Mars samples

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