



Automated Spacecraft Conjunction Assessment at Mars and the Moon

David Berry, Joseph Guinn, Zahi Tarzi, Stuart Demcak

*California Institute of Technology
Jet Propulsion Laboratory (JPL)
4800 Oak Grove Drive
Pasadena, California, USA, 91109*

Copyright 2012 California Institute of Technology. US Government sponsorship acknowledged.

Introduction

- Conjunction assessment and collision avoidance are areas of current high interest in space operations
- Most current conjunction assessment activity focuses on the Earth orbital environment
- Several of the world's space agencies have satellites in orbit at Mars and the Moon, and avoiding collisions there is important too
- Smaller number of assets than Earth, and smaller number of organizations involved, but consequences similar to Earth scenarios
- This presentation will examine conjunction assessment processes implemented at JPL for spacecraft in orbit at Mars and the Moon

Agenda

- Conjunction assessment requirements at Mars
- Rationale for automation
- “MADCAP” automated utility
- Conjunction assessment requirements at the Moon
- MADCAP Inputs / Features / Algorithms / Outputs
- Future Work

Conjunction Assessment at Mars

- NASA and ESA have spacecraft in orbit/on approach
- NASA: Mars Odyssey, Mars Reconnaissance Orbiter (MRO), Mars Science Laboratory (MSL) on approach
- ESA: Mars Express (MEX) spacecraft
- Also defunct spacecraft (Viking 1/2, Mars Global Surveyor) and natural satellites (Phobos, Deimos)
- Since mid-2002, ad hoc collision avoidance studies
- Ad hoc collision avoidance studies increased when MEX arrived in late 2003
- MRO aerobraking campaign in 2006 was major driver
- India, Russia, China interested in Mars missions

Rationale for Automation

- Given planned longevity of Mars-orbiting spacecraft, ad hoc conjunction assessment was insufficient
- Spacecraft orbits relatively stable, but are modified periodically, e.g., for relay operations
- Spacecraft are also subject to standard perturbations (e.g., drag, gravity, solar radiation pressure)
- Due diligence: always be prepared to answer the question "how close are the orbits?"
- Result: "MADCAP" (MArs Deepspace Collision Avoidance Process) automation developed to study Mars spacecraft conjunctions

Conjunction Assessment at the Moon

- NASA has several spacecraft in orbit at the Moon: the Lunar Reconnaissance Orbiter (LRO), GRAIL-A, GRAIL-B, ARTEMIS-P1, and ARTEMIS-P2
- India and Japan have spacecraft at the Moon that are no longer being tracked: Chandrayaan-1, Ouna (SELENE sub-satellite)
- MADCAP can also be used for Moon orbital environment

MADCAP Methodology

- Each orbital environment has a unique parameter file
- Required: A list of at least 2 objects per environment
- User specifies the desired conjunction attribute and threshold that will trigger user notification
- Other key parameters set ephemeris files to use, data items to analyze and print/plot, parameters used to calculate collision probability, email addresses
- Currently activated by a Linux cron job twice weekly for Mars, and daily in the case of the Moon

Ephemeris Files

- Most recent ephemeris files for S/C in the MADCAP parameters are automatically downloaded from DSN
- MADCAP allows specification of one supplementary file per S/C in addition to the most recent trajectory
- Ephemeris files for non-operational S/C can be added by specifying an ephemeris file location
 - State uncertainty in such ephemerides is greater than that of current solutions, but better than nothing
- Natural body ephemerides may also be specified

Orbit Conjunction Attribute Options

- Pairwise comparisons for all combinations of 2 spacecraft
- Comparisons occur over overlap of 2 ephemerides

Conjunction Attribute	Description
closap_times	Times of closest approaches of the two bodies
closap_distance	Relative distance and speed at closest approach
closap_angles	Angles between velocity vectors and orbit planes with respect to central body
closap_state_diff	State of spacecraft 2 relative to spacecraft 1
closap_states	States of both spacecraft with respect to central body and coordinate system
xing_distance	Distance between orbits at orbit crossings
xing_distance_min	Smaller of orbit crossing distances
xing_times	Times of orbit crossings
xing_times_min	Times of minimum orbit crossing
xing_traj	Radius and true anomaly at orbit crossings
xing_traj_min	Radius and true anomaly at minimum orbit crossing
mod_distance	Minimum orbit distances (useful for nearly coplanar orbits)
mod_distance_min	Smaller of two minimum orbit distances
mod_times	Times of minimum orbit distances
mod_times_min	Times of smaller of two minimum orbit distances
mod_traj	Radial distance and true anomaly at minimum orbit distances
mod_traj_min	Radial distance and true anomaly at smaller of two minimum orbit distances
col_prob	Collision probability for specified covariance

Collision Probability

- Intuitive collision probability at Mars/Moon is zero
- Collision consequences catastrophically high: lost tax investment, loss of science data, debris environment, repercussions if spacecraft from two nations collide
- Other faults with intuitive notions: science orbits with similar characteristics, surface S/C using relay services
- Analytic approaches yield better collision probability
- After considering several approaches, an advisory group selected a technique based upon a paper by Sal Alfano of Center for Space Standards & Innovation:

$$P = \frac{1}{2 \cdot \pi \cdot \sigma_x \cdot \sigma_y} \cdot \int_{-OBJ}^{OBJ} \int_{-\sqrt{OBJ^2 - y^2}}^{\sqrt{OBJ^2 - y^2}} \exp \left\{ \left(\frac{-1}{2} \right) \cdot \left[\left(\frac{x + x_m}{\sigma_x} \right)^2 + \left(\frac{y + y_m}{\sigma_y} \right)^2 \right] \right\} dx dy$$

Output Reports

- MADCAP prepares three types of reports: detail, summary, and plots
- Detail reports contain the results of analysis of the conjunction attributes for each pair of spacecraft, sorted by the conjunction attribute desired by user
- Summary report focuses on the "close approach distance" attribute, and categorizes the close approaches as green, yellow, or red
- Thresholds for green, yellow, red categorizations are established by the user
- MADCAP will also generate plots of several of the conjunction attributes if requested by the user

Sample MADCAP Detail Report

Table of closest approach events for 'SC01' and 'SC02'

Begin Time: 27-APR-2012 00:55:27.0000 TAI

End Time: 10-MAY-2012 00:01:06.1840 ET

Central Body: Moon

Coordinate System: IAU Moon Pole

Output Time System: UTC (UTC-ET = -66.1855 sec [at begin time])

Ephemeris files supplied by user:

/home/common/scripts/inputs/ephemerides/de421.boa

/home/moon/scripts/inputs/ephemerides/de421_Lunar.boa

#

ome/moon/scripts/inputs/ephemerides/spk_sc1_120424_120510_120425_od123v1.bsp

#

ome/moon/scripts/inputs/ephemerides/spk_sc2_120423_120510_120425_od234v1.bsp

/home/moon/scripts/inputs/ephemerides/spk_sc2_14day_20120426_01.bsp

#

#	Calendar	Julian	RELATIVE		Collision
#	Date	Date (days)	Distance (km)	Speed (km/s)	Probability
	06-MAY-2012 11:31:03.547	2456053.97990	14.05064	2.89753	0.00587
	01-MAY-2012 10:23:40.970	2456048.93311	28.22475	2.90483	0.00229
	03-MAY-2012 02:07:21.064	2456050.58844	55.77511	2.89525	
0.00007					
	08-MAY-2012 03:14:48.459	2456055.63528	98.52263	2.89337	
0.00000					
	04-MAY-2012 19:47:24.982	2456052.32459	101.18978	2.89296	
0.00000					
	09-MAY-2012 20:54:47.876	2456057.37139	106.70121	2.89202	
0.00000					
06/13/2012	04-MAY-2012 18:48:55.329	2456052.28397	117.16007	2.78184	0.00000
	09-MAY-2012 19:55:59.805	2456057.33055	123.63937	2.77510	0.00000

Sample MADCAP Summary Report

Collision Analysis was performed between SC04, SC05, and SC06 using the following ephemerides:

spk_SC04_noburn.bsp	21-FEB-2012 08:00:00 UTC - 29-FEB-2012 23:59:59 UTC
spk_SC05_od108v1.bsp	26-FEB-2012 13:00:00 UTC - 07-MAR-2012 23:59:59 UTC
spk_SC05_reference_traj.bsp (Ref)	24-FEB-2012 17:15:00 UTC - 05-JUN-2012 07:11:50 UTC
SC06-short_01.bsp	28-FEB-2012 00:00:00 UTC - 13-MAR-2012 00:00:00 UTC

The following body pairs have a status RED close approach event in less than 14 days:

SC04-SC05	19.76 km	01-MAR-2012 00:49:18 UTC
SC04-SC05	10.26 km	01-MAR-2012 02:43:52 UTC
SC04-SC05	0.80 km	01-MAR-2012 04:40:43 UTC
SC04-SC06	11.63 km	03-MAR-2012 14:37:48 UTC
SC05-SC06 (SC05 Ref)	11.83 km	10-MAR-2012 07:27:40 UTC

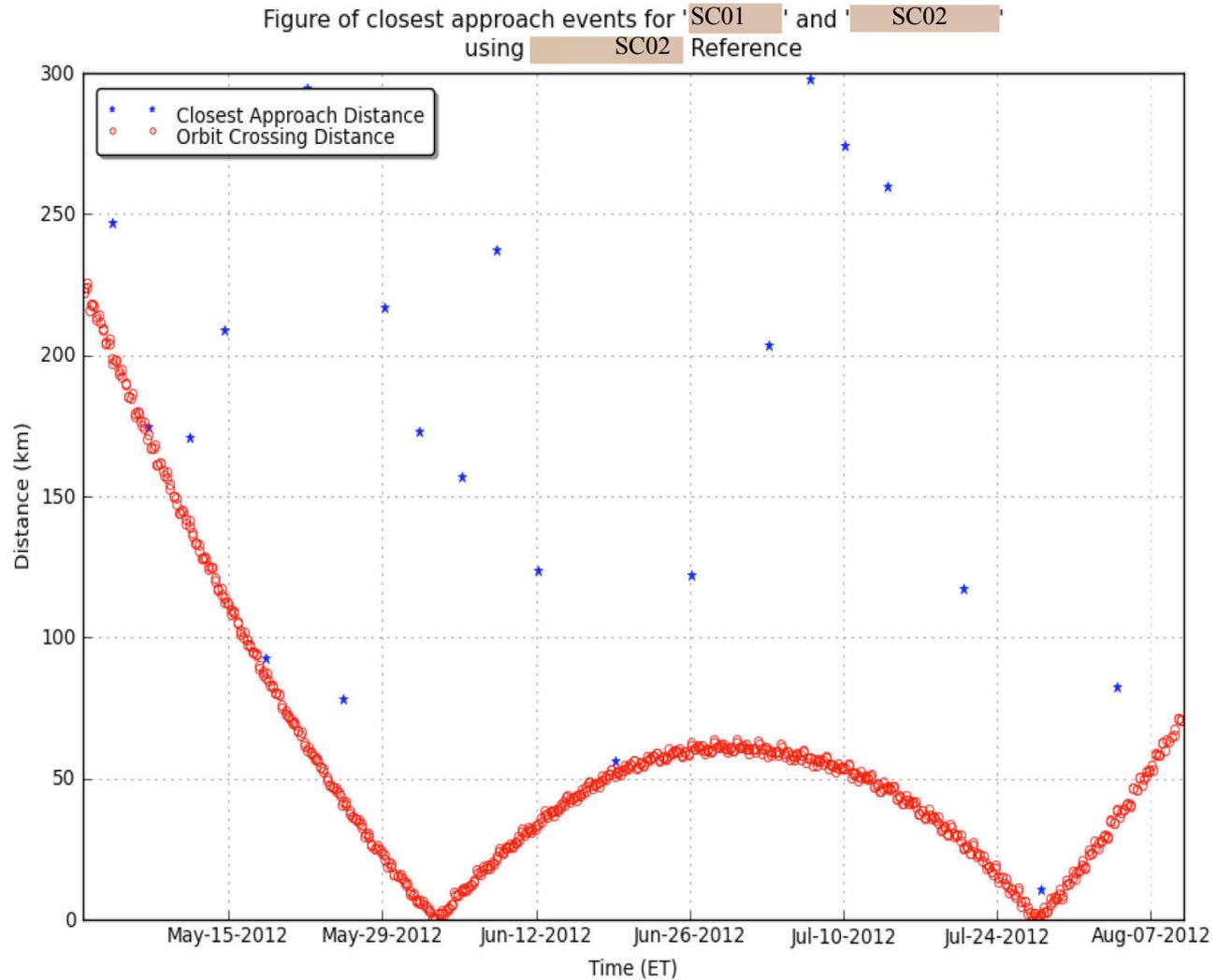
The following body pairs are status RED (closap_distance <= 20 km):

SC04-SC05	0.80 km	01-MAR-2012 04:40:43 UTC
SC04-SC06	11.63 km	03-MAR-2012 14:37:48 UTC
SC05-SC06 (SC05 Ref)	11.83 km	10-MAR-2012 07:27:40 UTC

The following body pairs are status YELLOW (20 km < closap_distance <= 200 km):

SC04-SC06	137.29 km	29-FEB-2012 07:10:33 UTC
SC04-SC06	136.78 km	29-FEB-2012 07:10:33 UTC
SC04-SC05	28.57 km	29-FEB-2012 22:55:07 UTC
SC05-SC06	23.99 km	01-MAR-2012 22:54:45 UTC
SC04-SC05 (SC05 Ref)	45.17 km	05-JUN-2012 06:18:10 UTC

Sample MADCAP Plot



Communicating Results

- The MADCAP parameter file contains a list of email addresses to which the output reports will be sent
- Accommodations are made for normal engineering reporting and for management escalation reporting
- Current spacecraft in the Mars and Moon environments normally maintain a safe separation
- Occasional close approaches with low miss distance have warranted some discussion as to whether any action was necessary
- At present no official decision-making process has been established for handling these events

Future Work

- Formalize process when approaches are “too close”
- Refine uncertainty modeling to improve collision probability calculation
- Collaboration with NASA/GSFC and ESA's Space Situational Awareness program will be explored
- Incorporate more sophisticated automation than Linux “cron”
- Include other shared orbital environments of potential interest (Earth-Sun L1/L2, Earth-Moon L1/L2)
- Provide option to output a CCSDS Conjunction Data Message (CDM), an emerging international standard

Conclusion

- The techniques used at JPL for automated conjunction assessment at Mars and the Moon have been presented
- Processes not unique to any specific orbit environment
- Potential future work to enhance the current baseline operation has been outlined
- Future spacecraft at Mars, the Moon, Earth-Sun L1/L2, and Earth-Moon L1/L2 are likely
- MADCAP techniques can be used in all of these multi-spacecraft environments to ensure a safer orbital environment for all