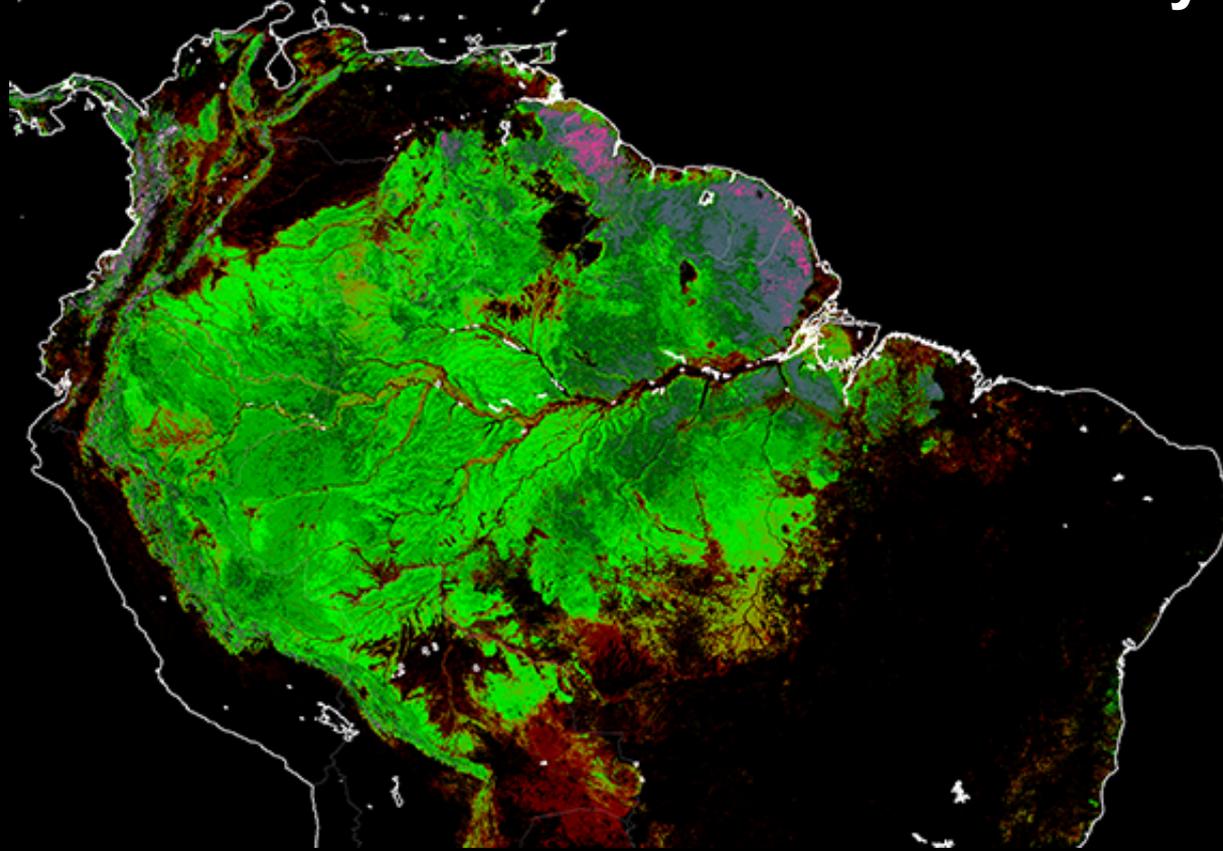


Diversity of forest structure and patterns of aboveground biomass in the Brazilian Amazon from national airborne lidar inventory



Sassan Saatchi

**NASA/Jet Propulsion Laboratory
California Institute of Technology
Pasadena, CA 91109**

**Santos, Brazil
April, 2019**

Carbon Emissions and Removals from Deforestation, Degradation, Regeneration



deforestation



degradation



Regeneration

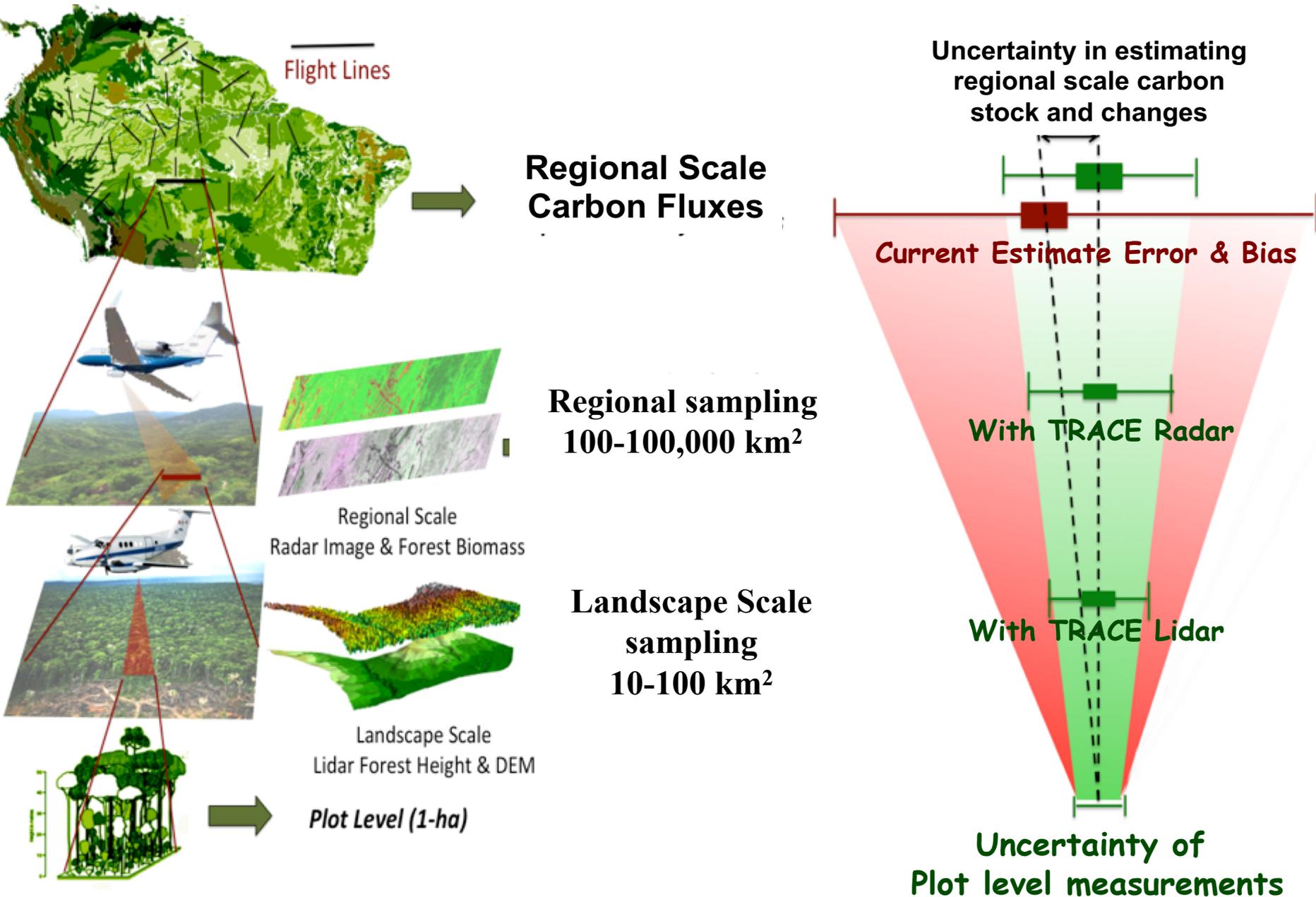
$$\Delta C = \sum \Delta A \cdot B \cdot E_{def} + \sum A \cdot \Delta B \cdot E_{deg} + \sum A \cdot \Delta B \cdot R_{reg}$$

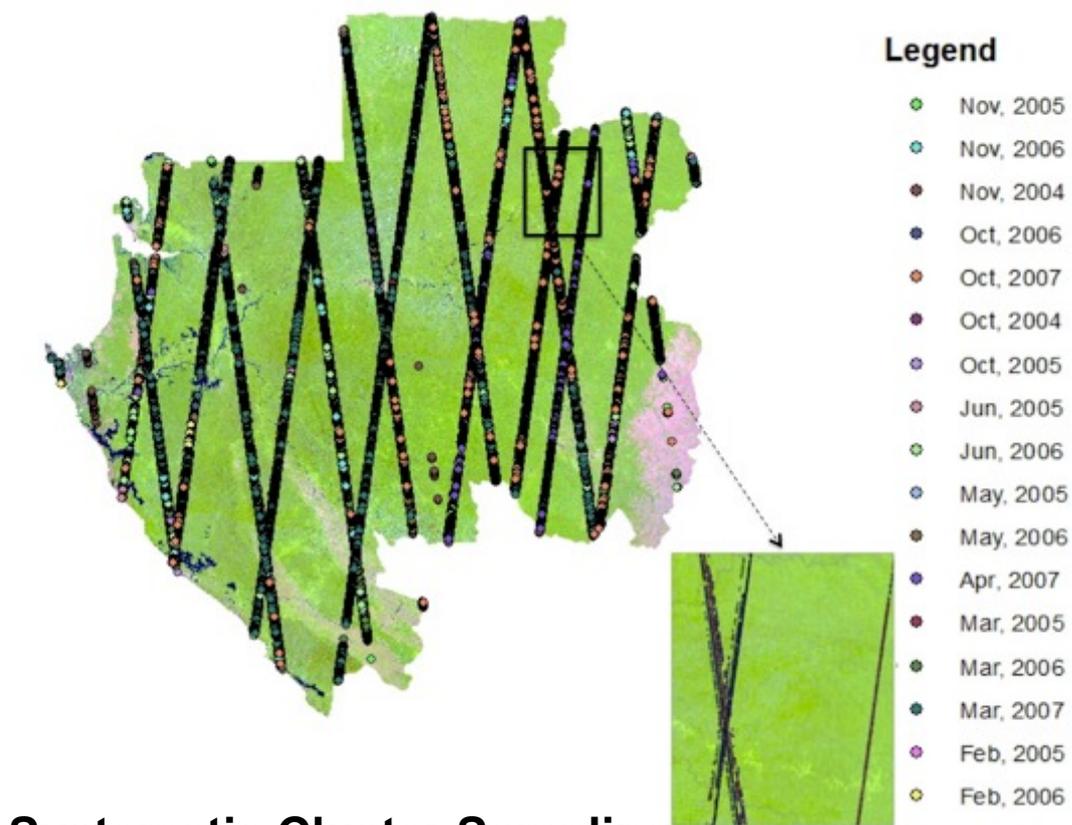
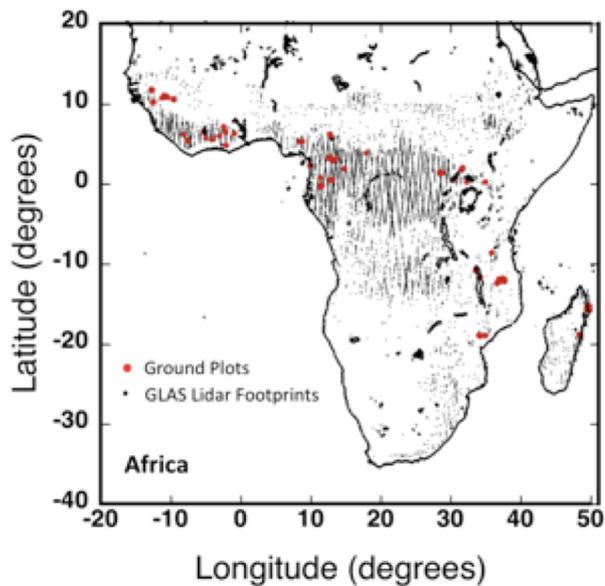
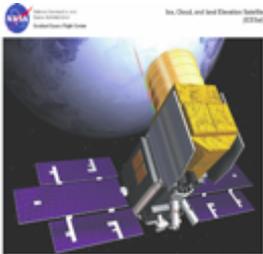
where A is the area of forest type, with biomass B, emission efficiency factor E, and removal efficiency R

How do we approach the problem?

1. Develop National Inventory Plots
2. Use Direct Remote Sensing Techniques from Space
3. Use a combination of remote sensing sampling and ground measurements

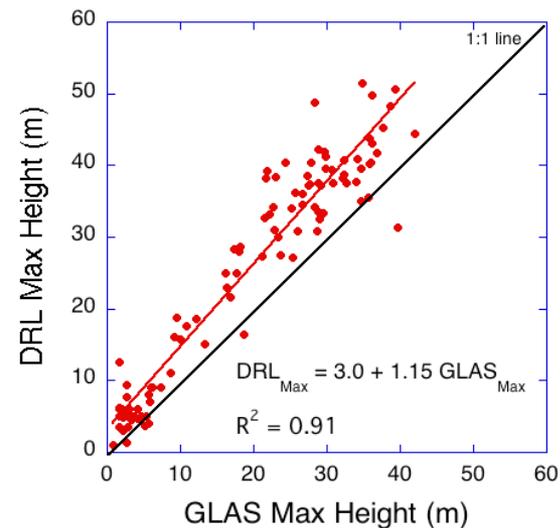
Forest Biomass Inventory and Mapping from Space





Systematic Cluster Sampling

Density of Lidar Samples Sample GLAS Shots Over Old Growth Forests (~0.25 ha)



Lidar/Plot Level Allometry

$$AGB = \sum_{i=1}^N 0.0509 \times \rho_i \times (D_i^2) \times H_i$$

$$AGB = \bar{\rho} \sum_{i=1}^N 0.0509 \times (D_i^2) \times H_i$$

$\bar{\rho}$: mean plot wood density is adequate for AGB estimation.

H-D allometry is regionally variables and may depend on

environmental variables (Temperature Seasonality, Rainfall Seasonality, MWD)

Plot Level Allometry

$$AGB = a \bar{\rho} B^\alpha h^\beta$$

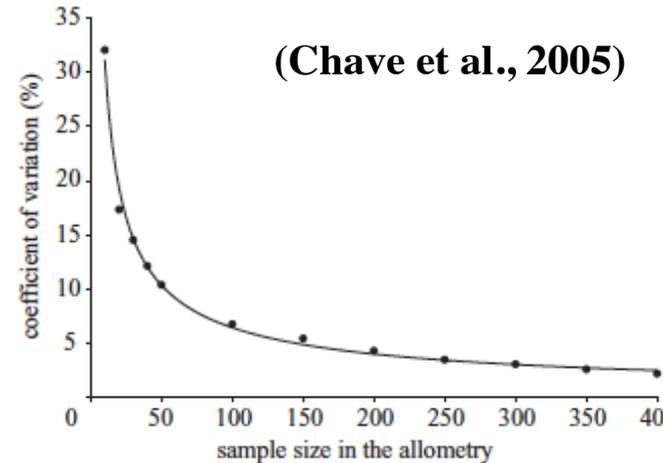
$$h_{lidar} = g(B, h)$$

Spatial pattern of AGB is controlled by spatial pattern of h and $\bar{\rho}$

$$h = \frac{\sum_{i=1}^N H_i \times BA_i}{\sum_{i=1}^N BA_i} \cong \frac{\sum_{i=1}^N H_i \times CA_i}{\sum_{i=1}^N CA_i},$$

$h = MCH,$

$h =$ other height metrics



Height Biomass Allometry

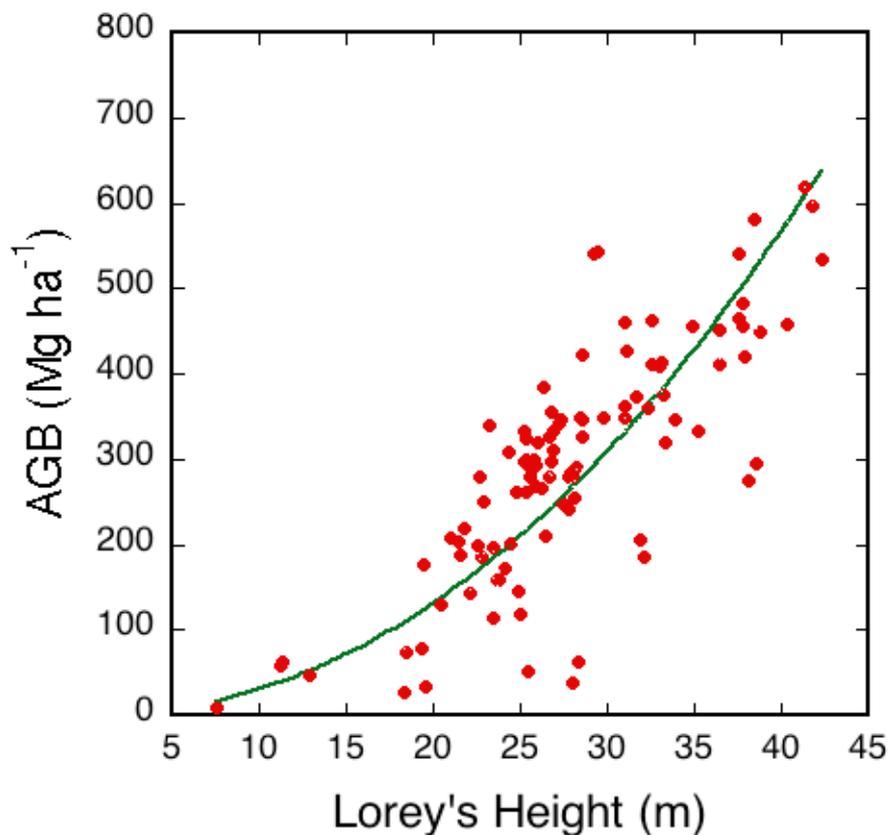
$$AGB = a\bar{\rho}h_{GLAS}^b$$

$$h_{GLAS} = f \times h_{Ground}$$

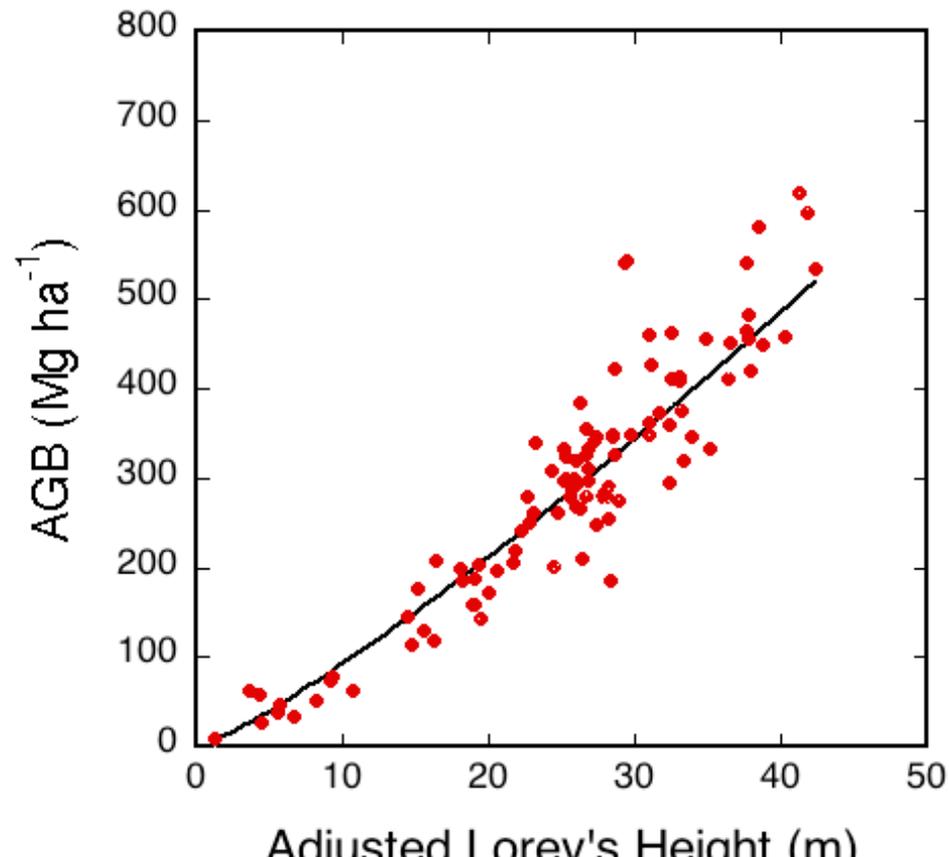
f : Canopy Cover



Ground Height Biomass Model

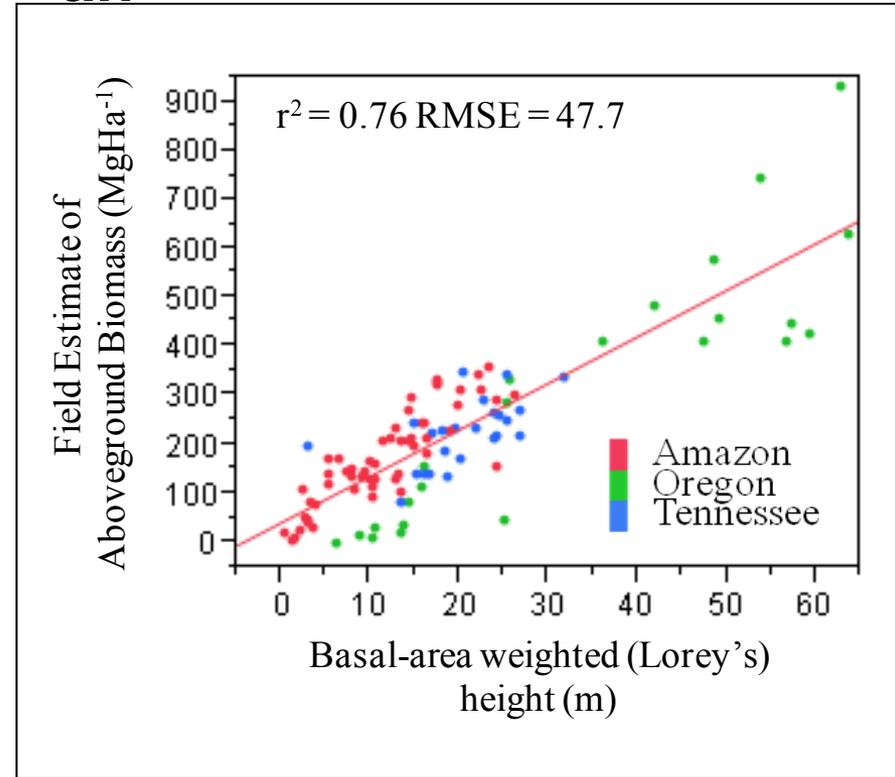
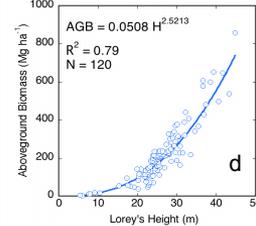
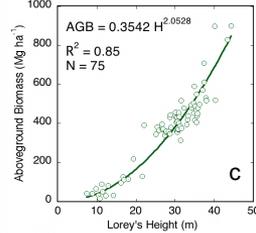
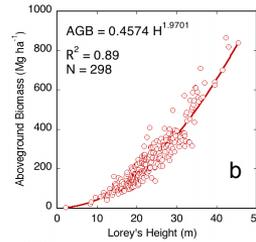
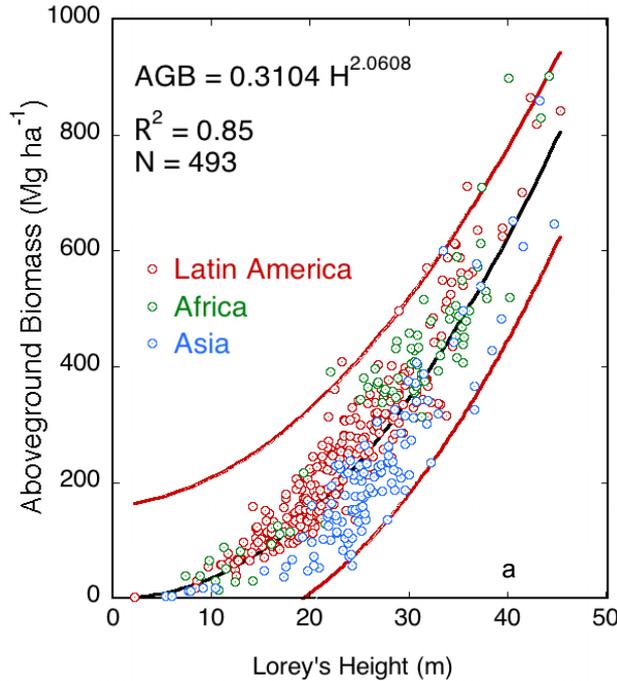


GLAS Height Biomass Model



Forest Height Bioamss Allometry

$$AGB = ah^b$$



$$AGB = 0.3H^{2.061}$$

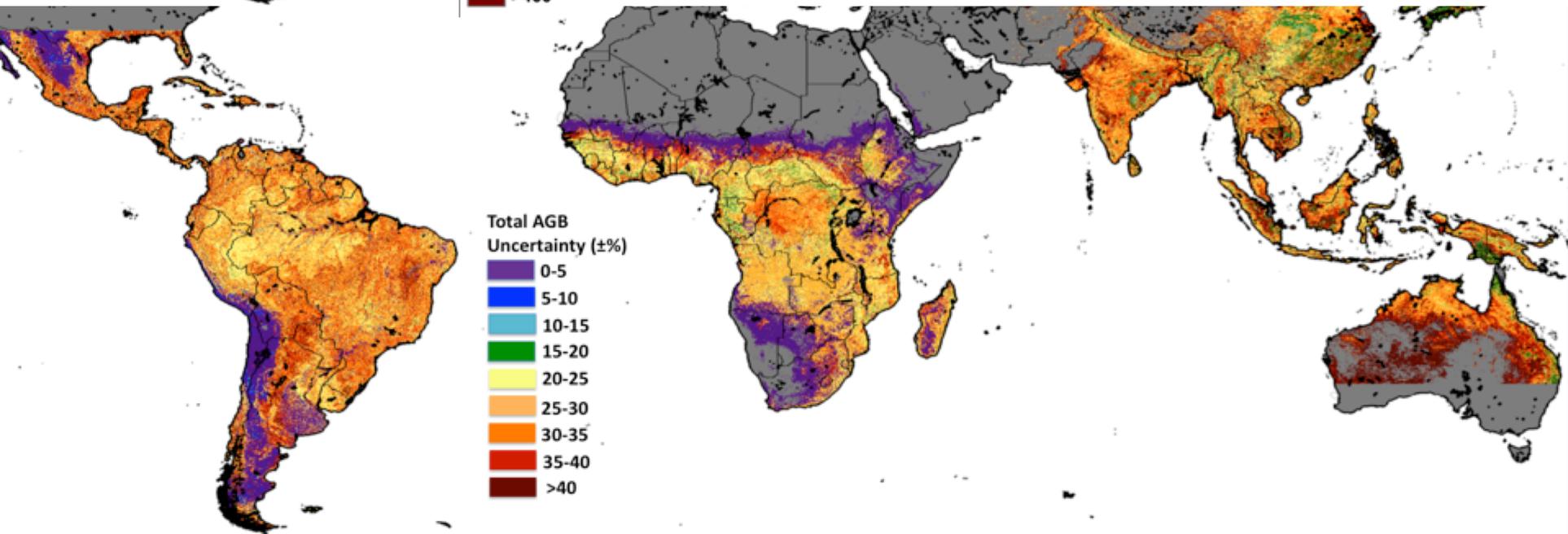
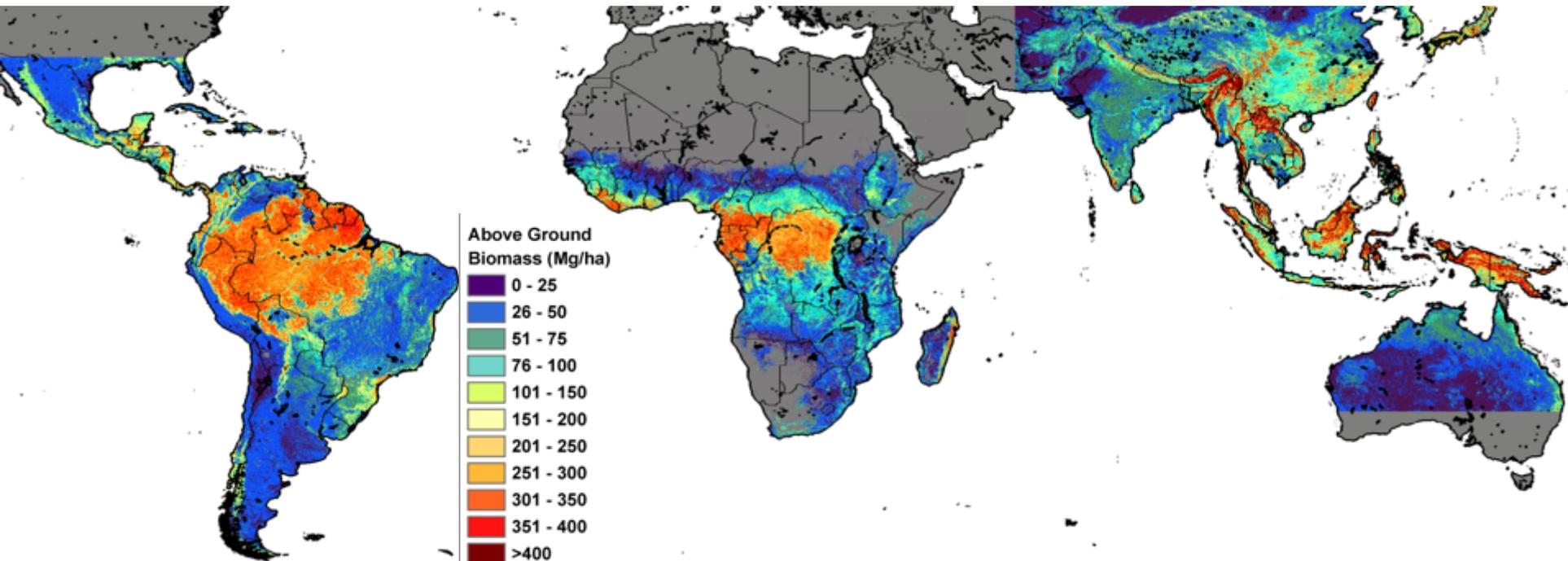
$$\varepsilon_{allometry} = 21.0\%$$

$$\varepsilon_{AGB} = [\varepsilon_{allometry}^2 + (2.061\varepsilon_H)^2]^{1/2} = 35.2\%$$

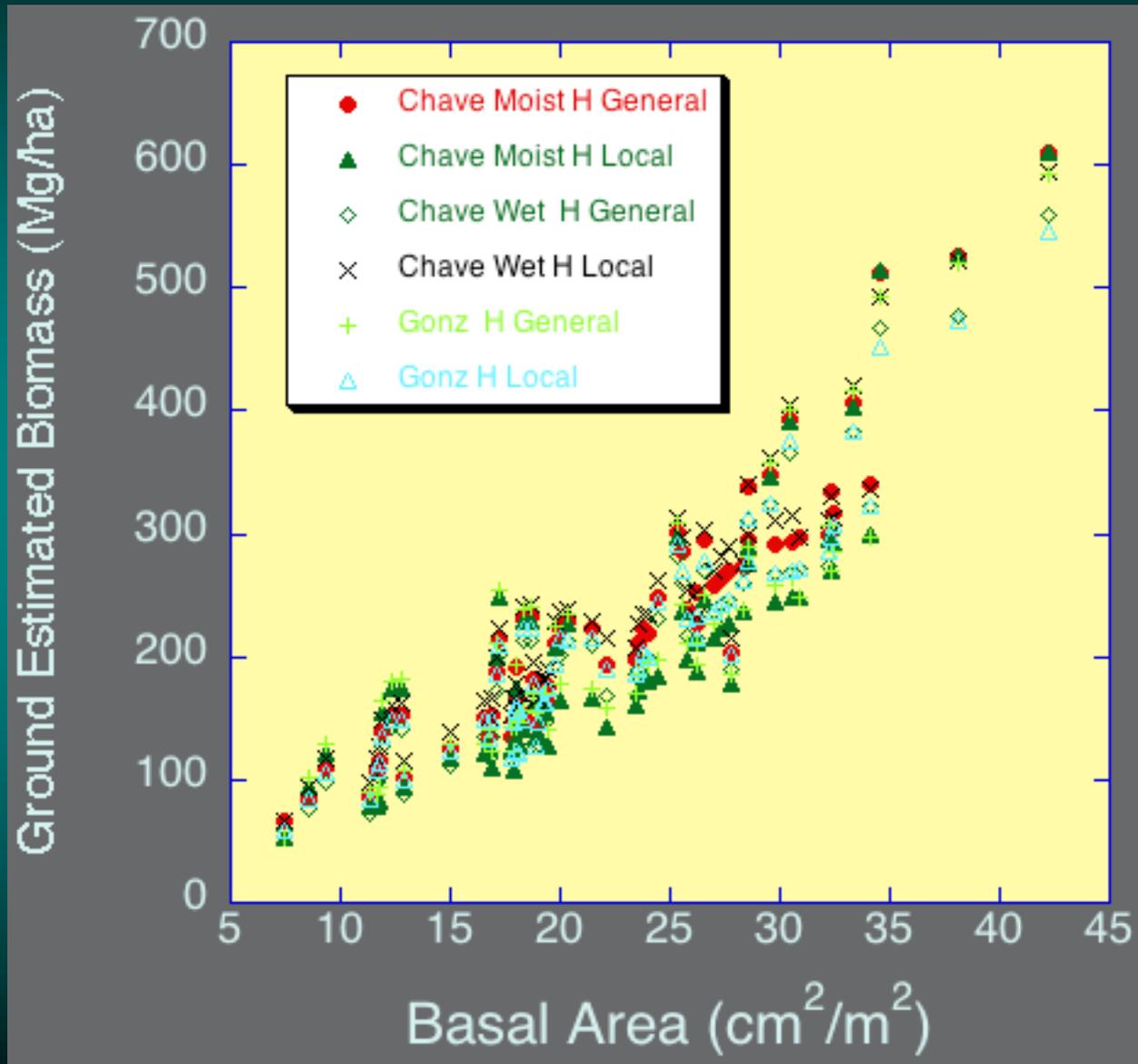
Lorey's Height Error: 3.3 m (13.7% Lefsky, 2010)

Assuming Errors are independent and there is no bias in any step of the process except allometry.

Pan Tropical Map



Available Allometry

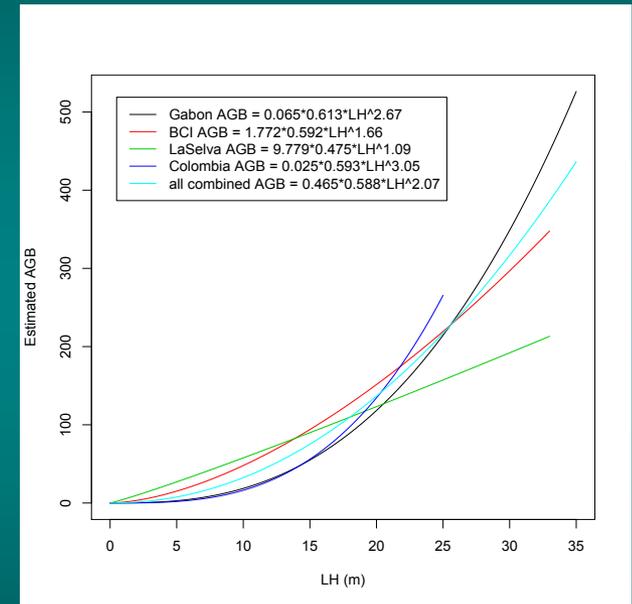


Lidar Biomass Allometry

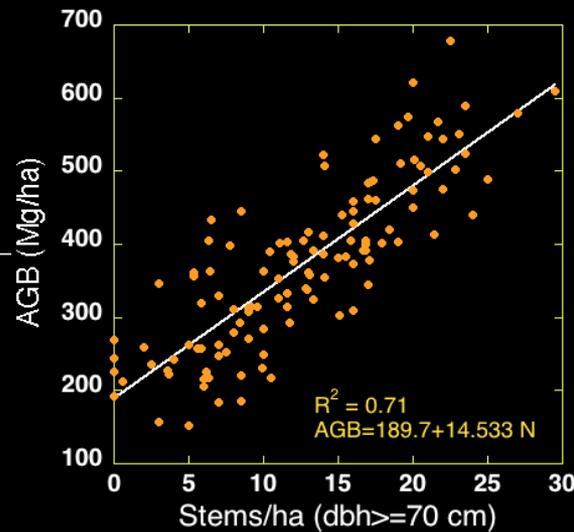
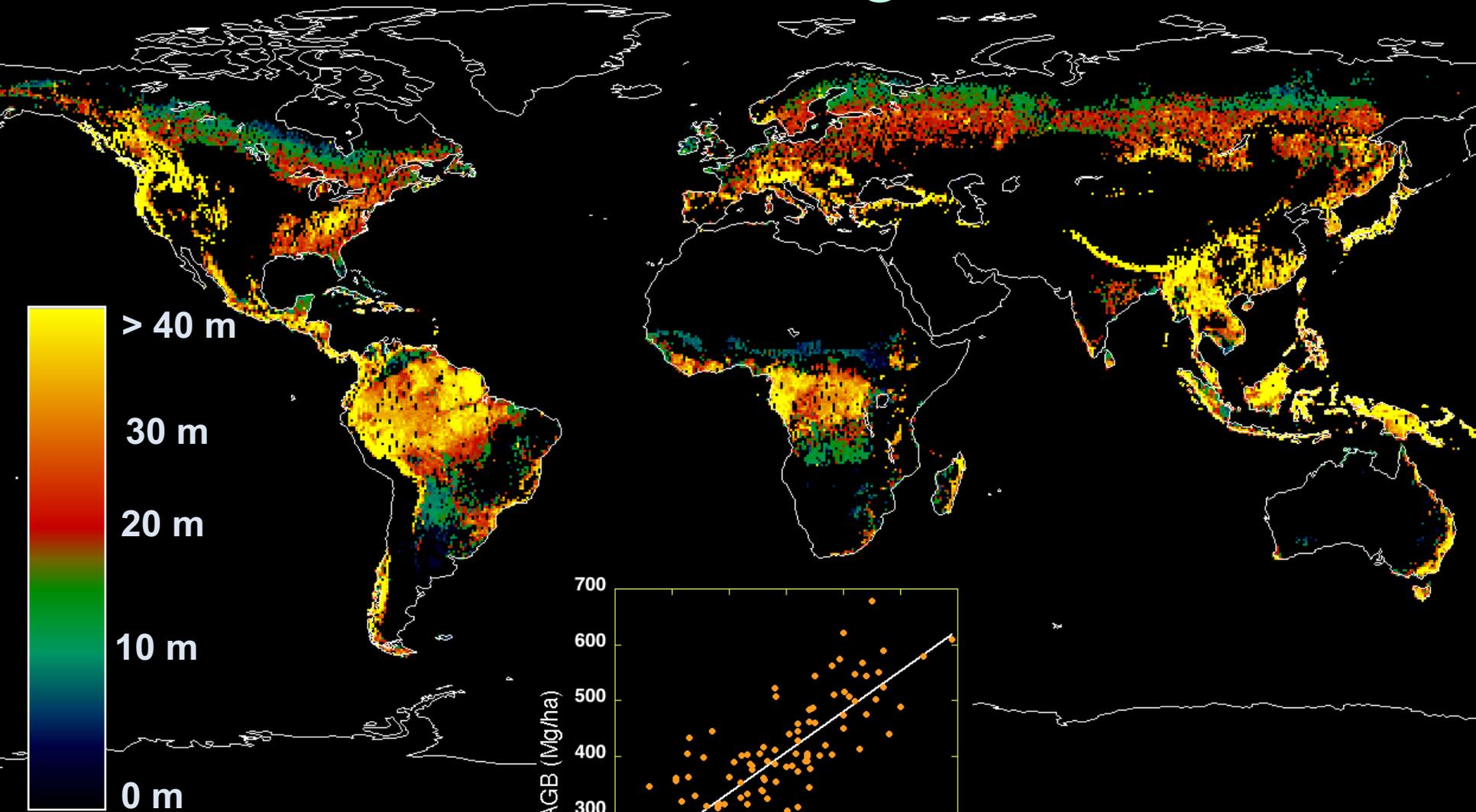
$$AGB = a \bar{\rho} h_{GLAS}^b$$

Pattern of AGB is defined by:

1. Pattern of large trees
2. Pattern of high wood density trees
3. a and b may be dependent on environmental variables

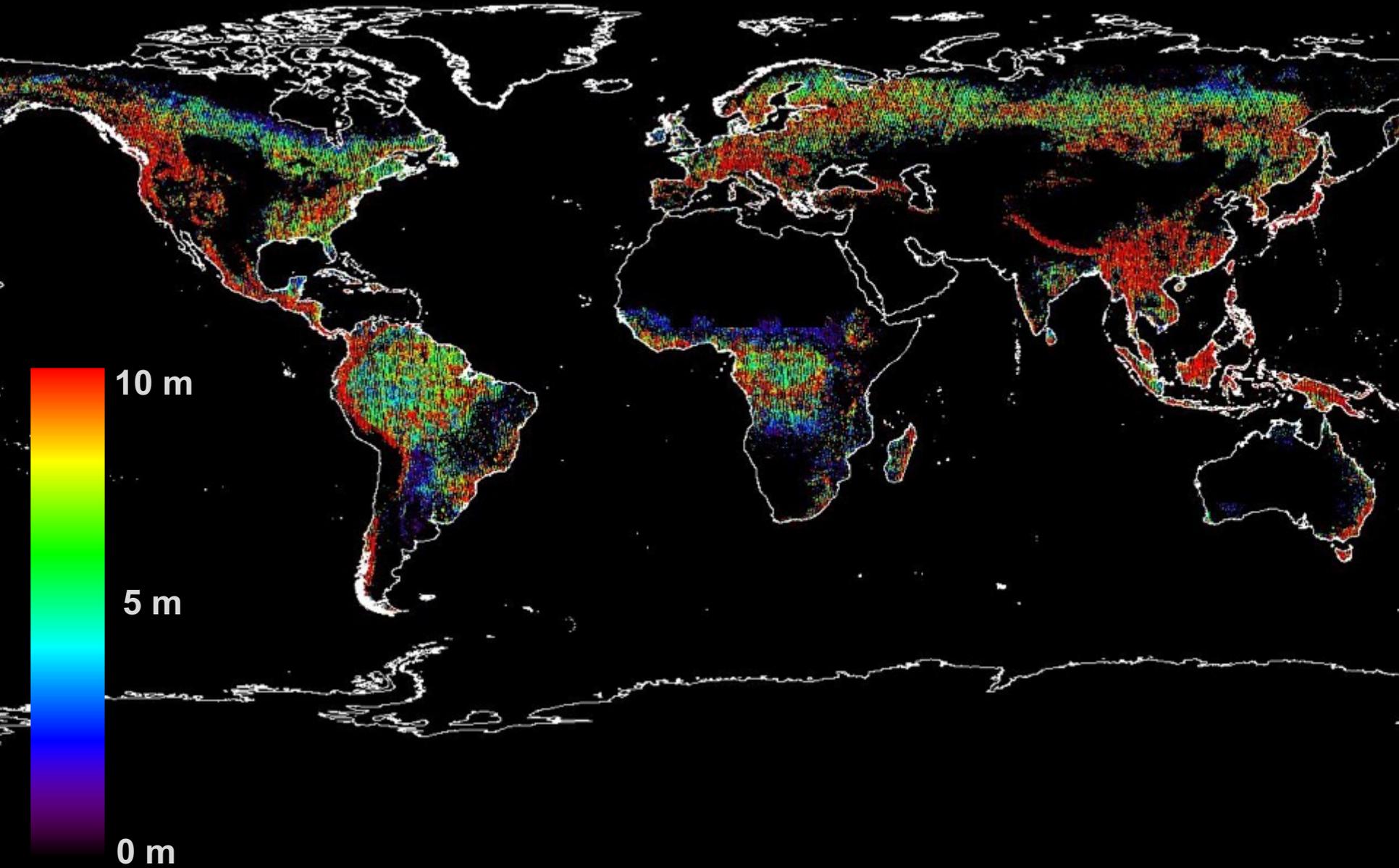


Where are the large trees?

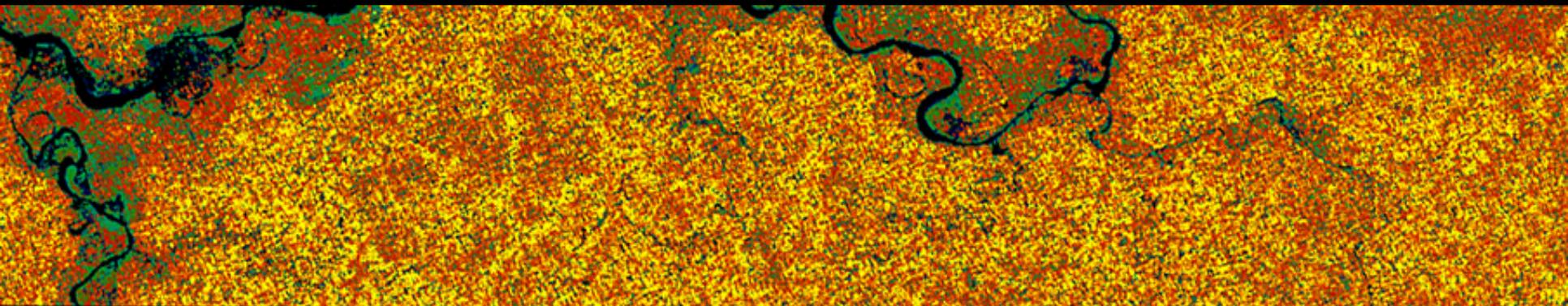
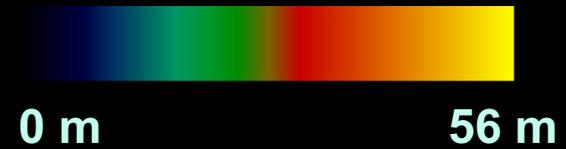
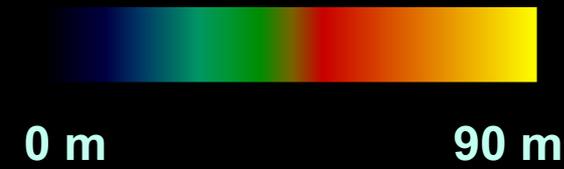
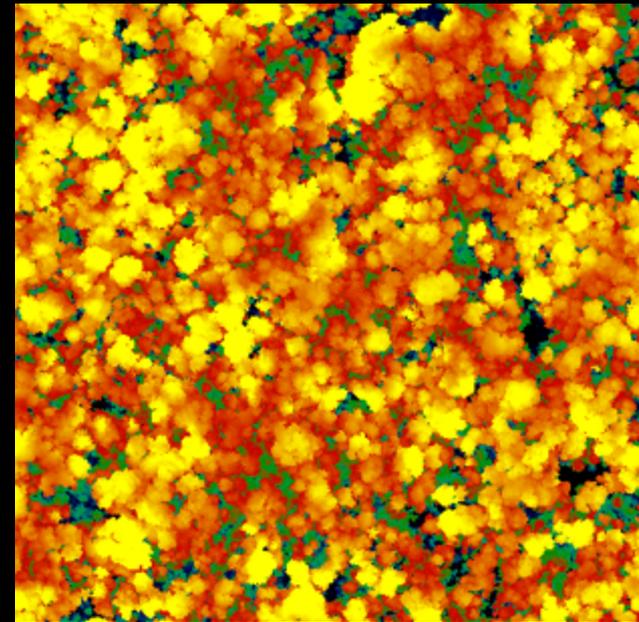
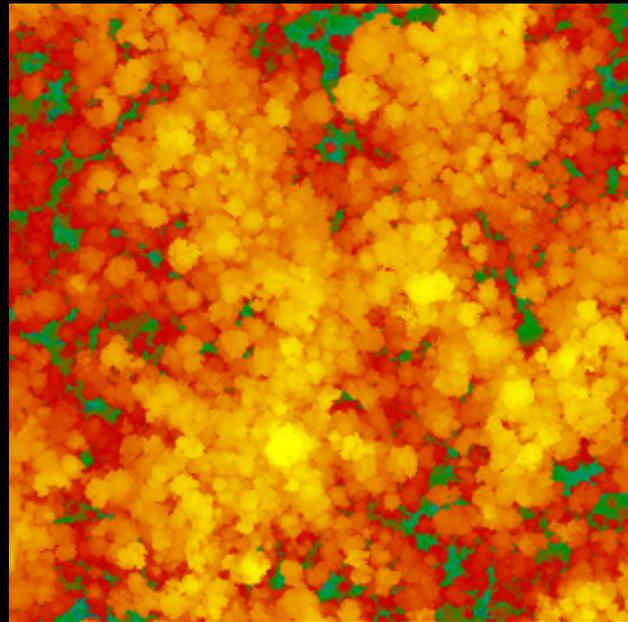
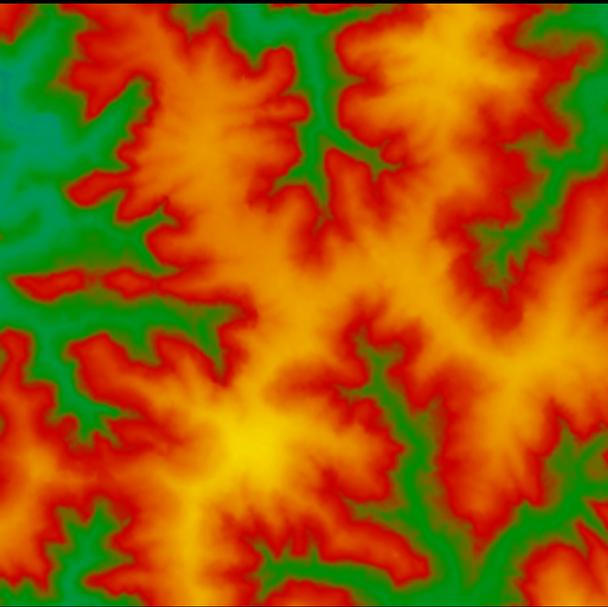


Slik et al., 2013

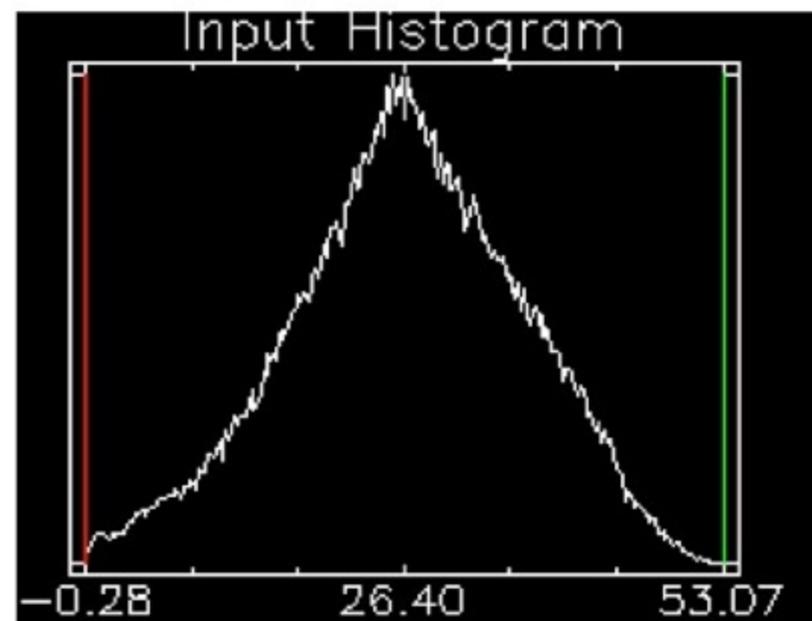
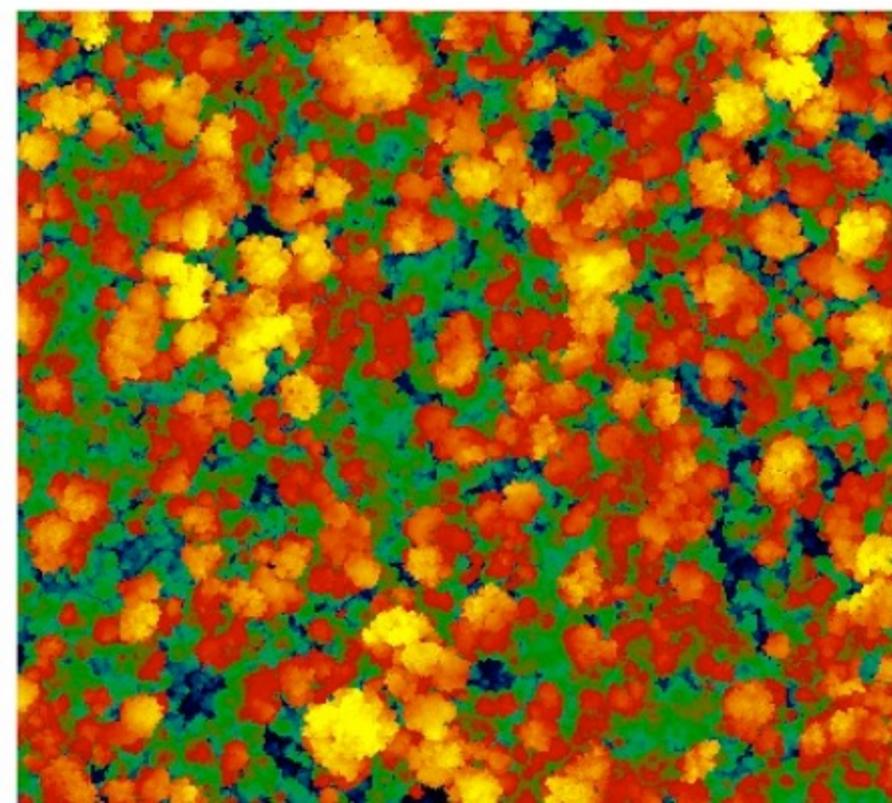
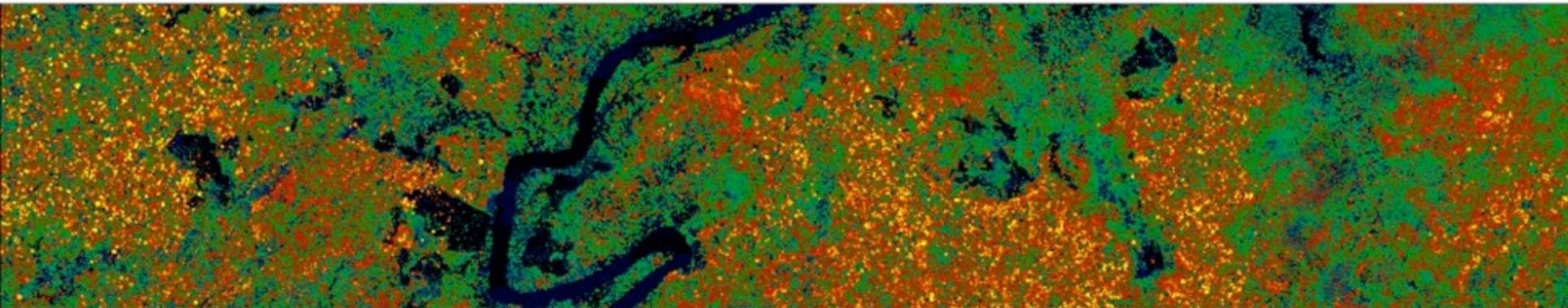
Global Variations of Forest Structure



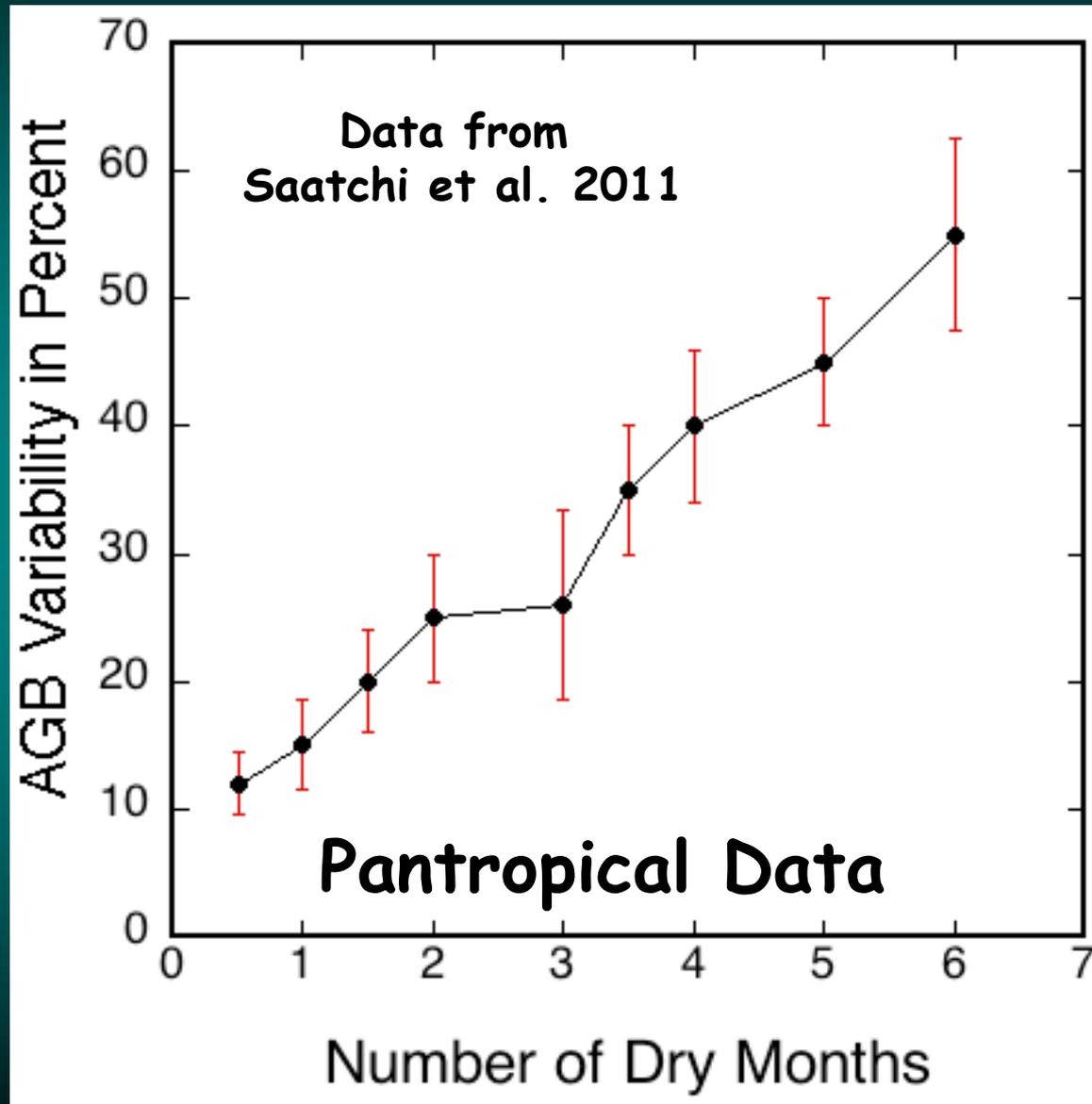
Landscape Scale Distribution of Forest Structure



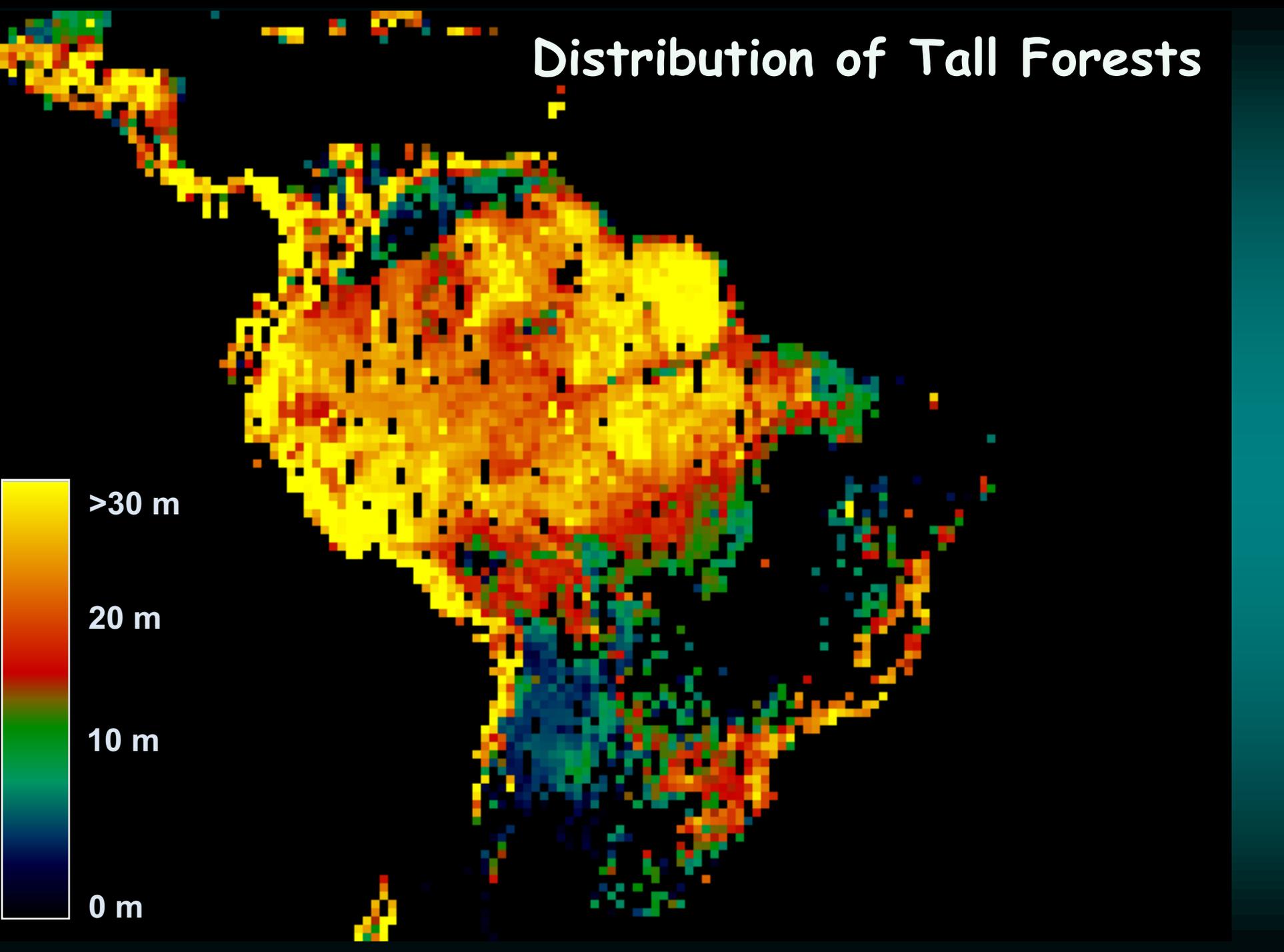
Lidar Transect (2000 ha)



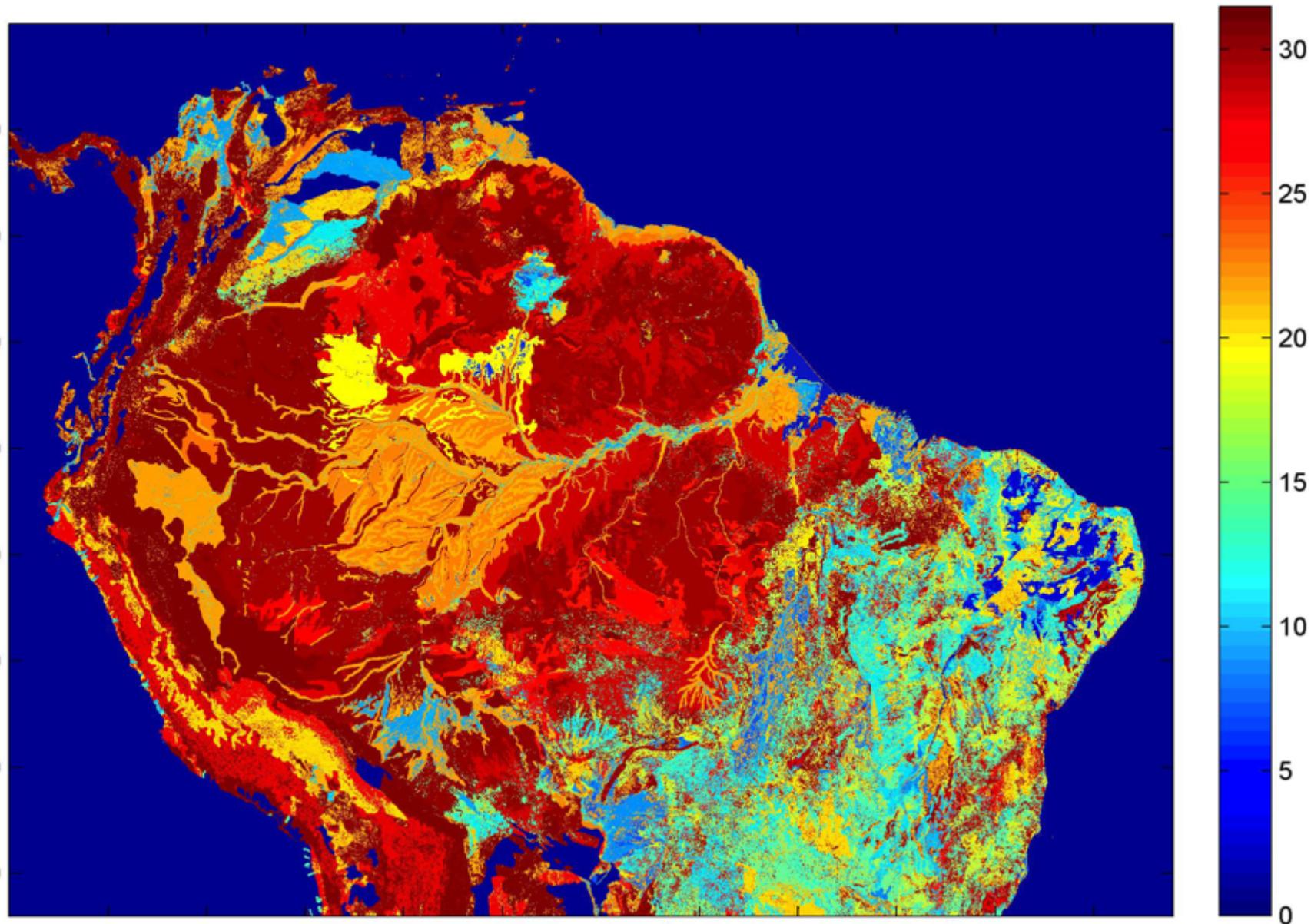
Environmental Variability



Distribution of Tall Forests



GLAS Lidar Mean Top Canopy Height Estimate of Amazon Basin

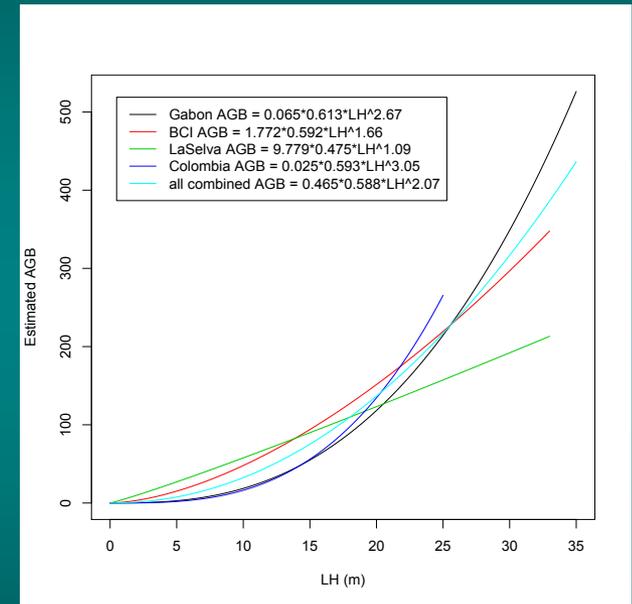


Lidar Biomass Allometry

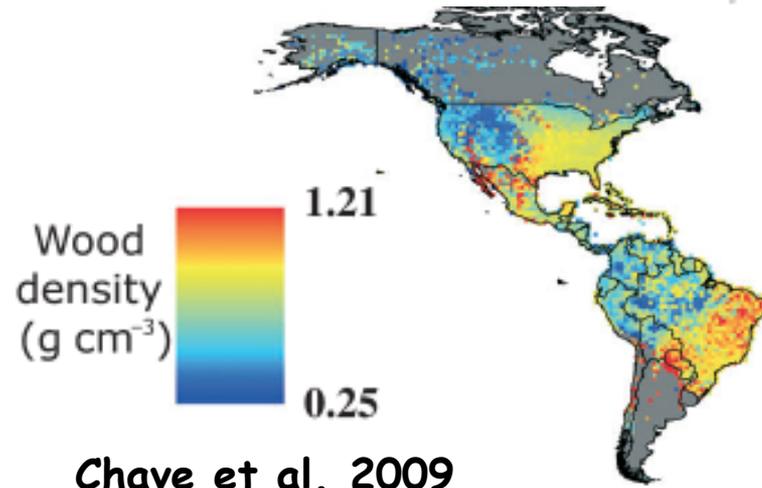
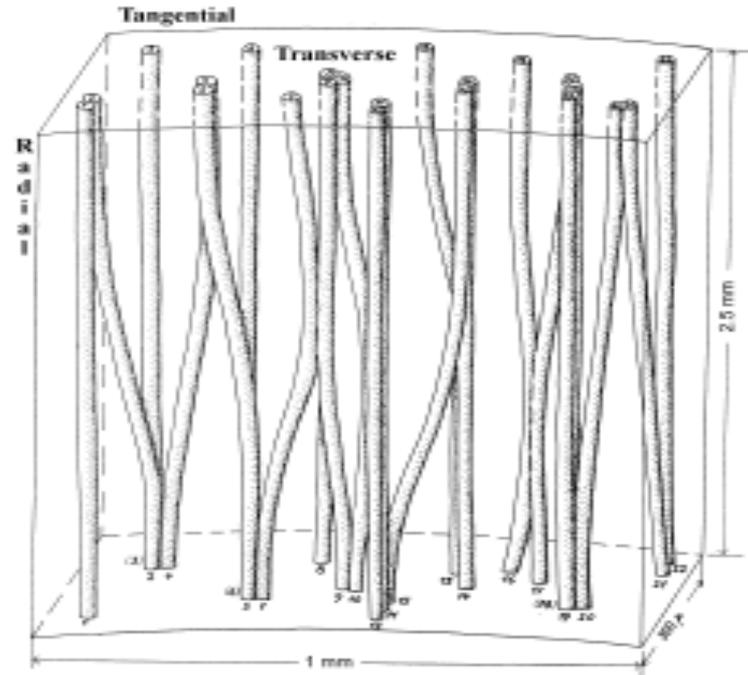
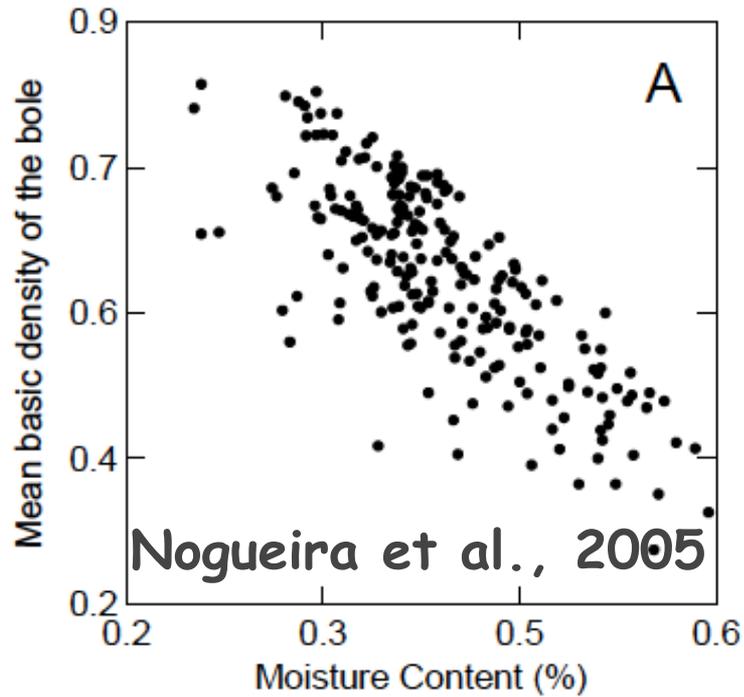
$$AGB = a \bar{\rho} h_{GLAS}^b$$

Pattern of AGB is defined by:

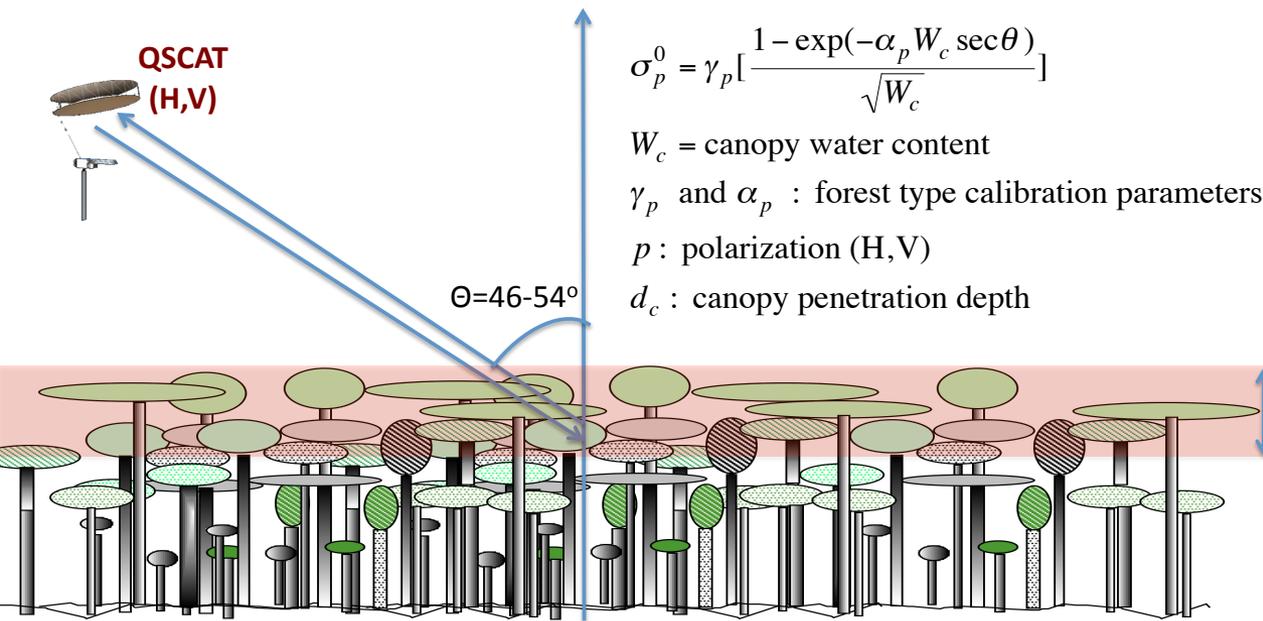
1. Pattern of large trees
2. Pattern of high wood density trees
3. a and b may be dependent on environmental variables



Wood Density



QSCAT Sensitivity to Canopy Water Content



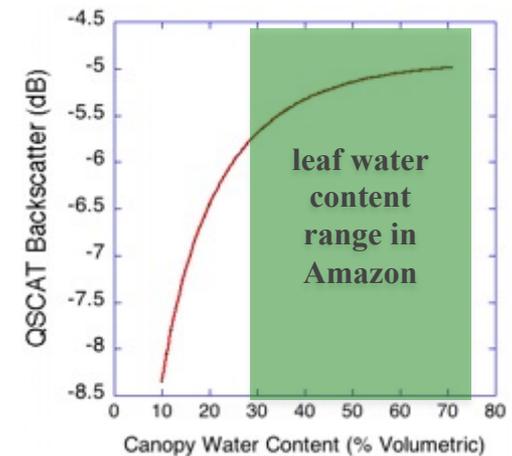
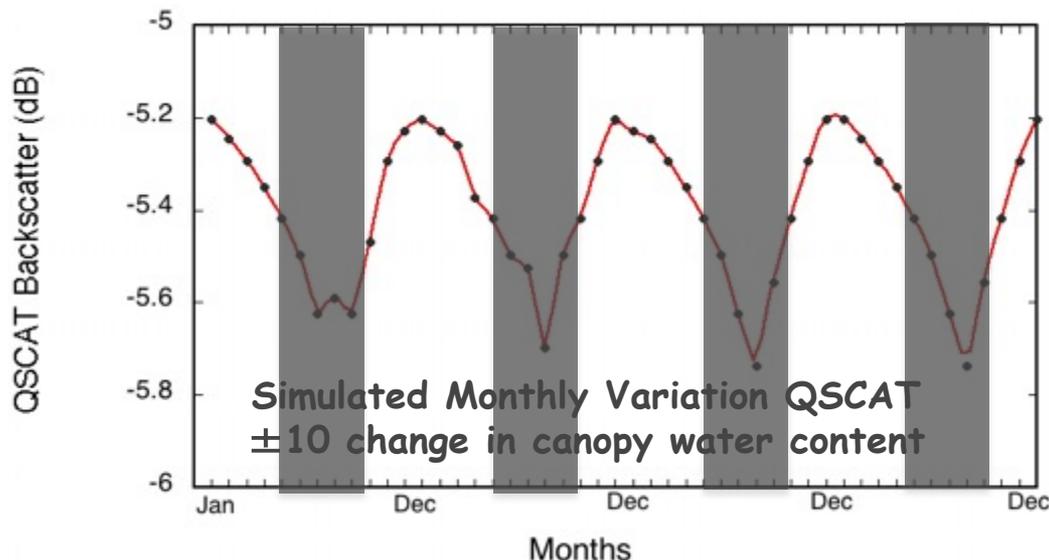
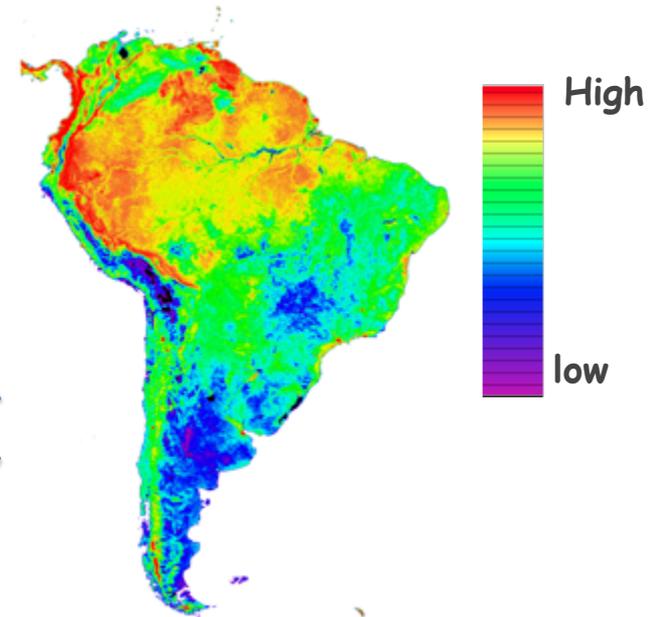
$$\sigma_p^0 = \gamma_p \left[\frac{1 - \exp(-\alpha_p W_c \sec \theta)}{\sqrt{W_c}} \right]$$

W_c = canopy water content

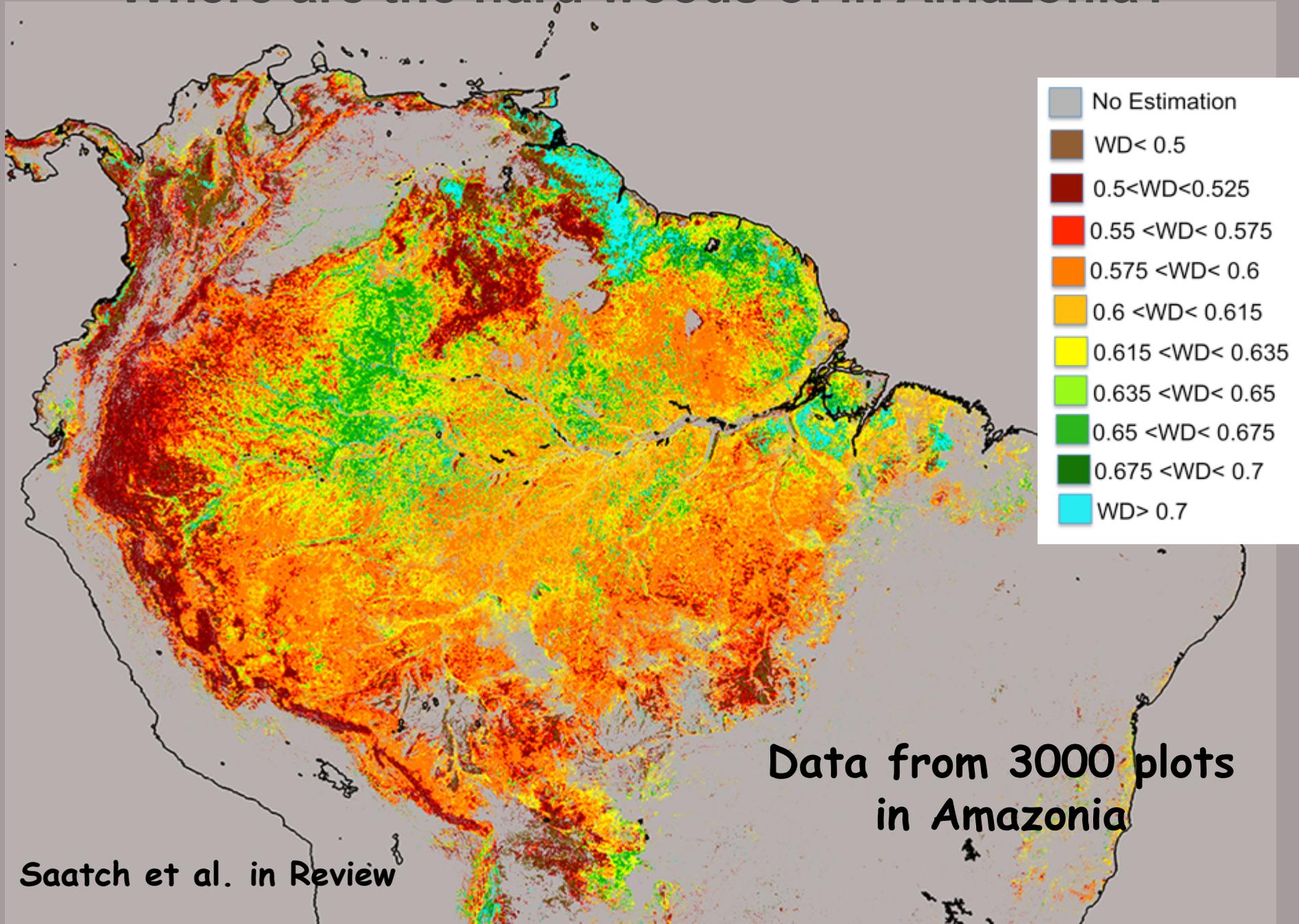
γ_p and α_p : forest type calibration parameters

p : polarization (H,V)

d_c : canopy penetration depth



Where are the hard woods of in Amazonia?



Aboveground Biomass Map at 100 m (1-ha) Resolution

