

# **Earth Remote Sensing using Surface-Reflected GNSS Signals (Part II)**

Stephen T. Lowe

Jet Propulsion Laboratory /  
California Institute of Technology

Presented at:

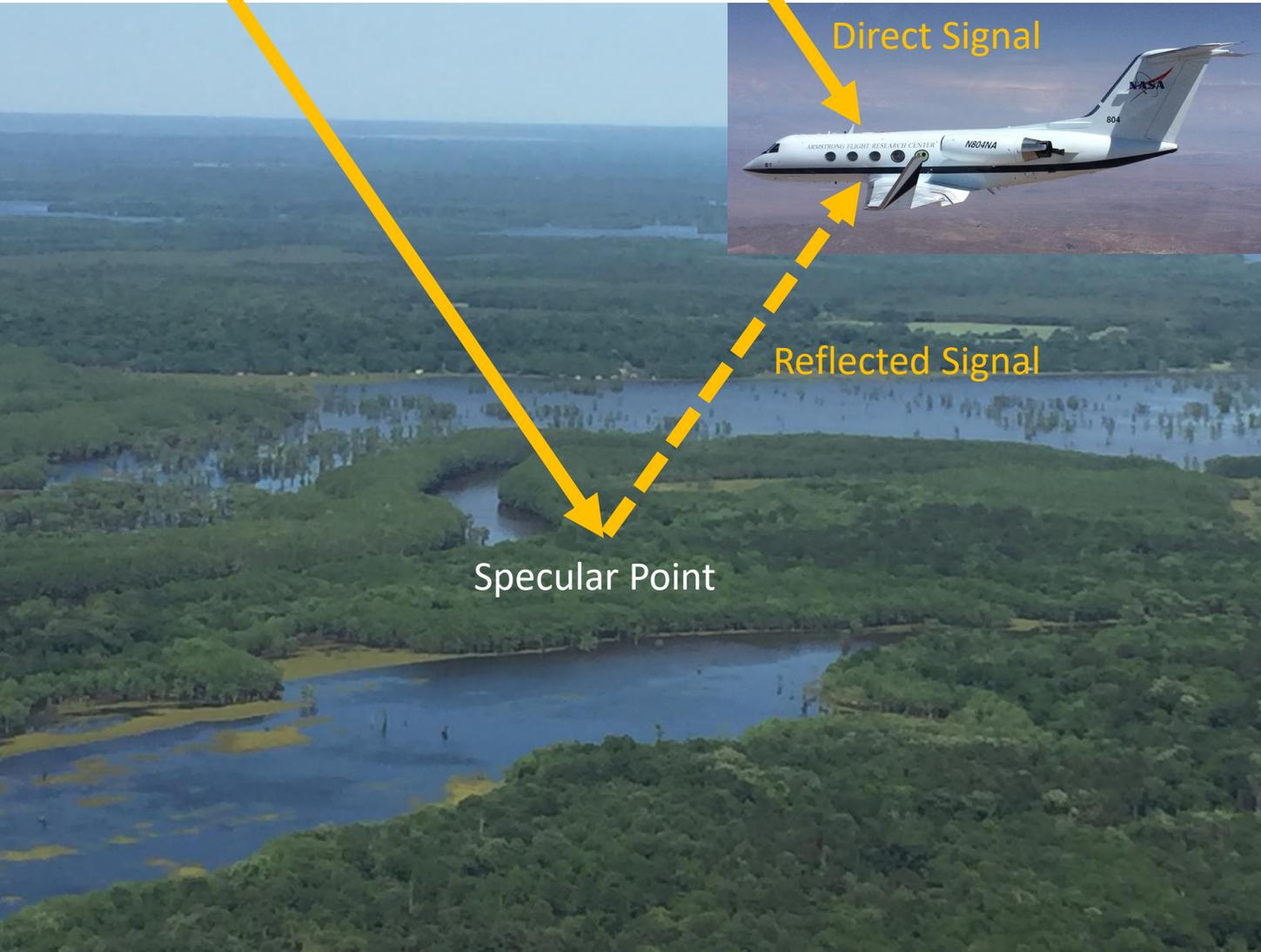
12<sup>th</sup> Meeting of the International Committee

On Global Navigation Satellite Systems

Kyoto, Japan Dec 2-7, 2017

# What is GNSS-Reflectometry (GNSS-R)?

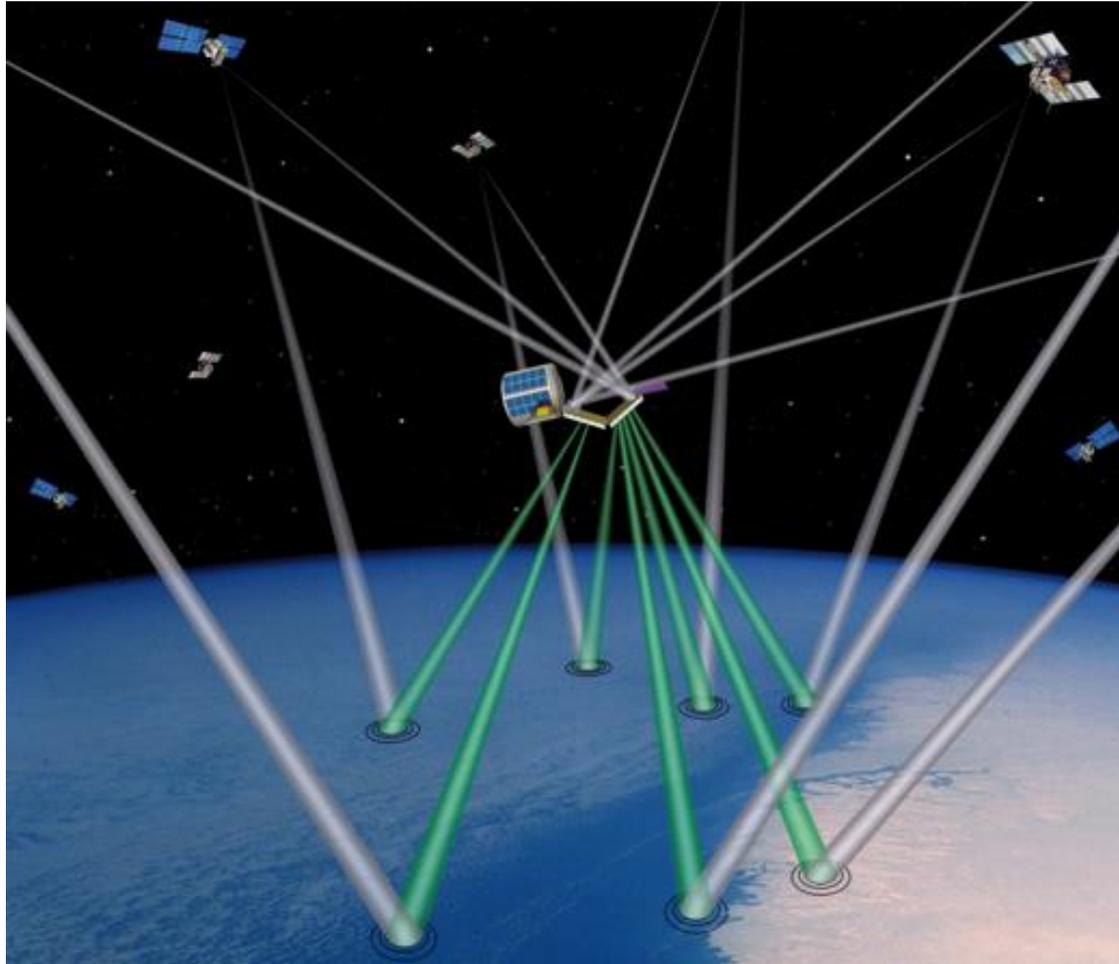
From GNSS Transmitter



## GNSS-R

- Radar with separate transmitter and receiver (bistatic radar)
- Forward-scattering
- Specular Point: Earliest arrival at receiver

# Space-Based GNSS-R System



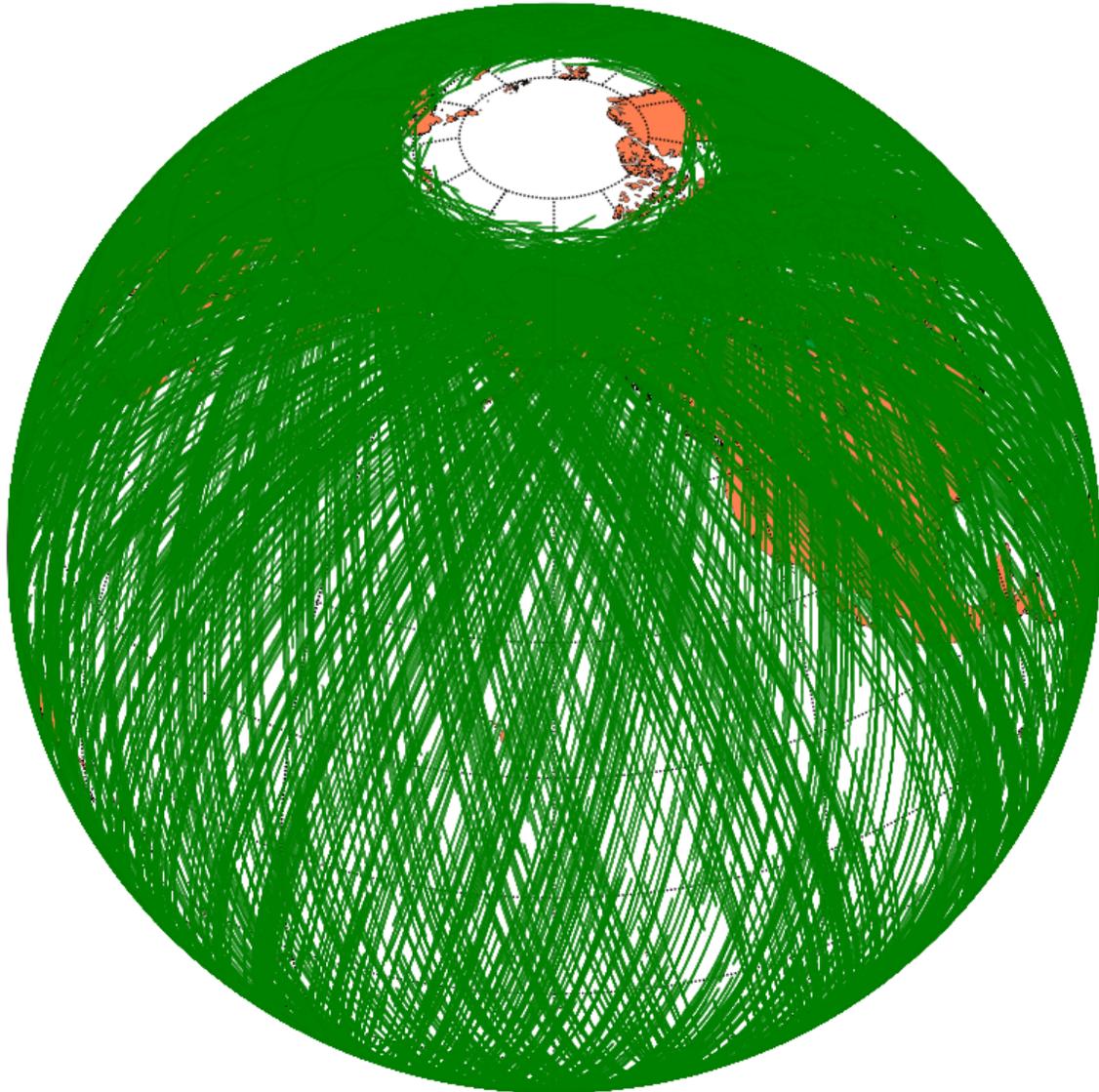
## GNSS-R

- Multi-bistatic
- Next few years: >100 GNSS transmitters
- Dense surface coverage

## Many Advantages

- Multiple, simultaneous observations
  - High spatial / temporal resolution
- Free high-quality signals
- Leveraging huge global infrastructure
- No transmitter
  - Relatively low cost, low power
  - Constellation possibilities (CyGNSS)
- Forward scattering (where the power goes)
- ~Same hardware as Radio-Occultations'

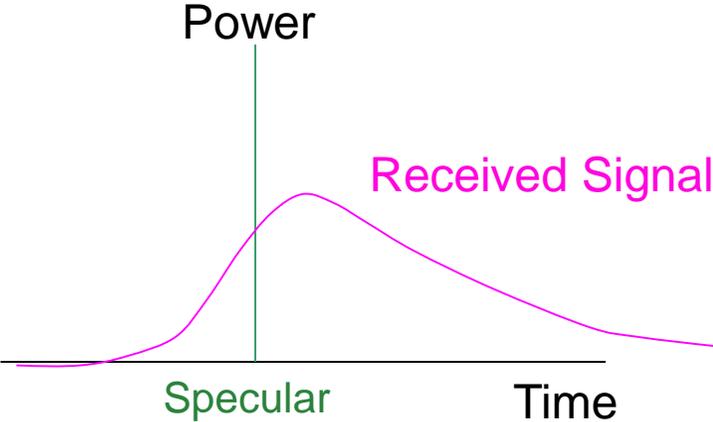
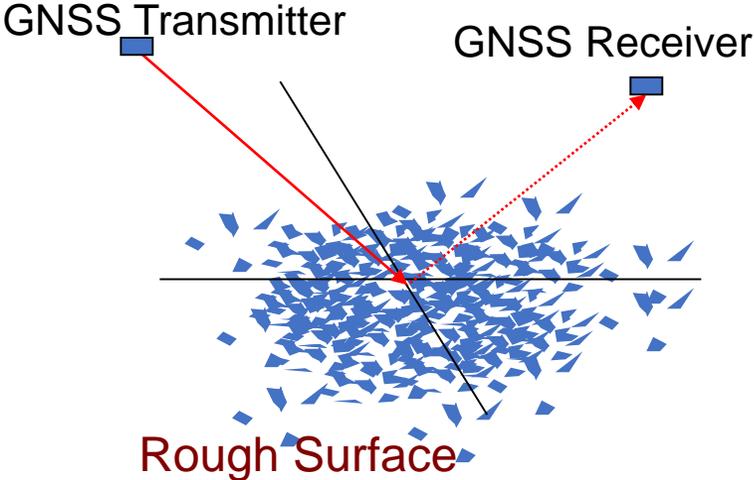
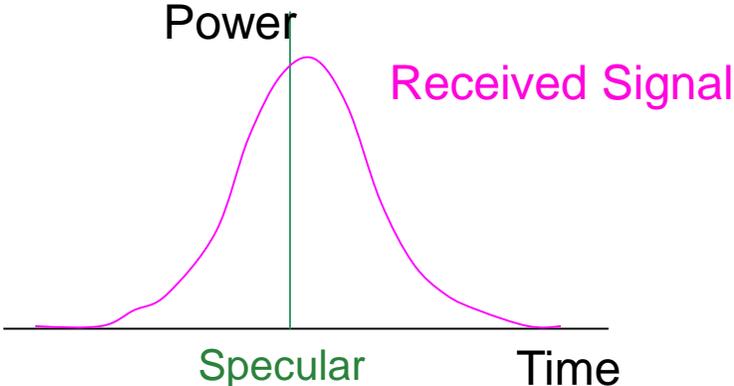
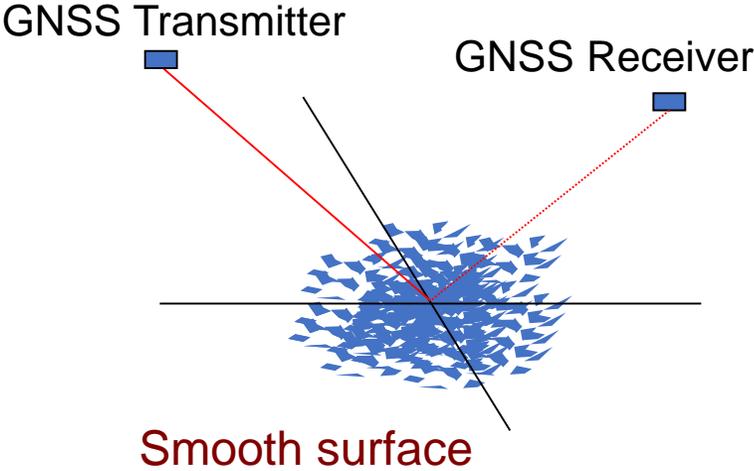
# Surface Coverage



## Coverage Simulation:

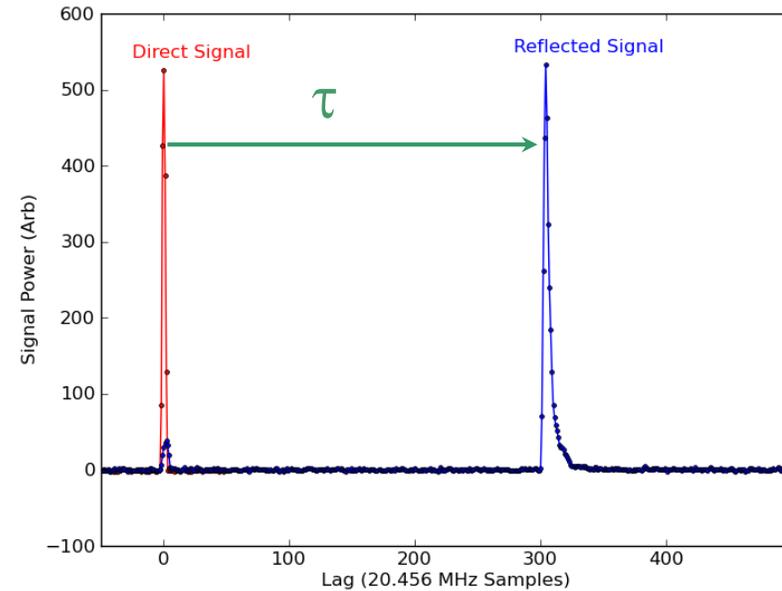
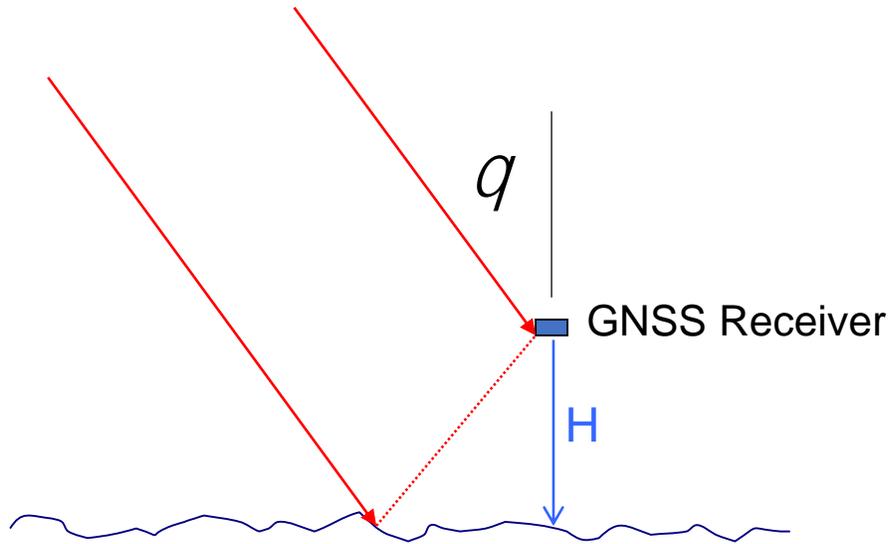
- 6-satellite constellation
- High inclination orbit (72 deg)
- 1 day
- GPS + Glonass + Galileo

# GNSS-R Scatterometry



Smooth surface: Higher peak, faster rise  
Rough surface: Lower peak, slower rise

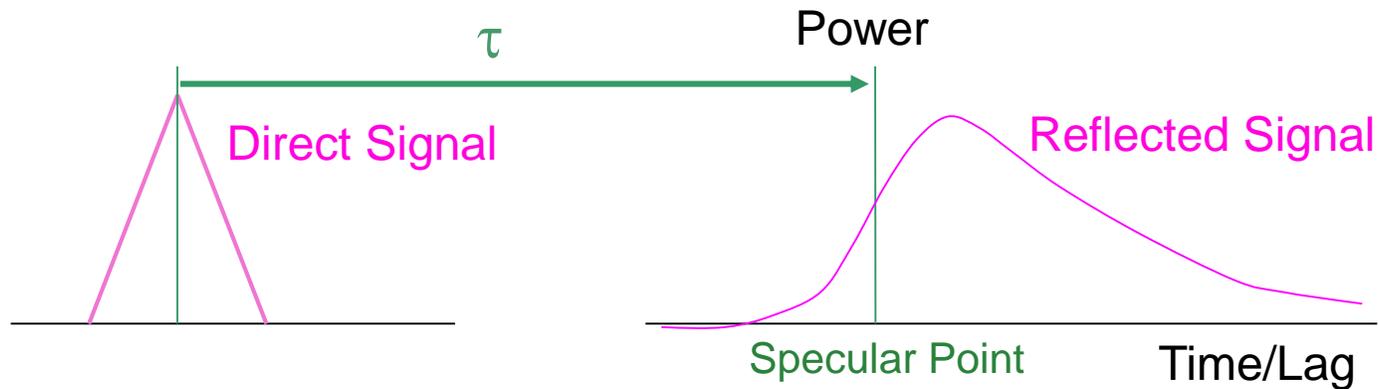
# GNSS-R Altimetry



JPL 2003 Monterey-Bay aircraft test

Time delay ( $\tau$ ) between direct and ocean-reflected signal gives information on receiver height over surface

$$t = 2H \cos q$$



# GNSS-R Bistatic Radar Equation

$$W(t) = c_0 \int_s \frac{G(\rho) \Lambda^2(t - t_{spec}) \text{sinc}^2(T_I \Delta f(\rho))}{4\pi R_t^2 R_r^2} \sigma_o^p(\rho) ds$$

The equation is annotated with several terms and arrows:
 

- Antenna pattern on surface**: Points to  $G(\rho)$ .
- Autocorrelation Fcn**: Points to  $\Lambda^2(t - t_{spec})$ .
- Receiver Integration**: Points to  $\text{sinc}^2(T_I \Delta f(\rho))$ .
- Scattering Related to PDF of surface slopes**: Points to  $\sigma_o^p(\rho)$ .
- Altimetry**: Points to the denominator  $4\pi R_t^2 R_r^2$ .
- Geometry**: Points to the denominator  $4\pi R_t^2 R_r^2$ .
- Scatterometry**: Points to  $\sigma_o^p(\rho)$ .

Zavorotny, V. U. and A. G. Voronovich, Scattering of GPS Signals from the Ocean with Wind Remote Sensing Application, *IEEE Transactions on Geoscience and Remote Sensing*, Vol. 38, No. 2, 951-964, 2000.

## Scatterometry (oceans)

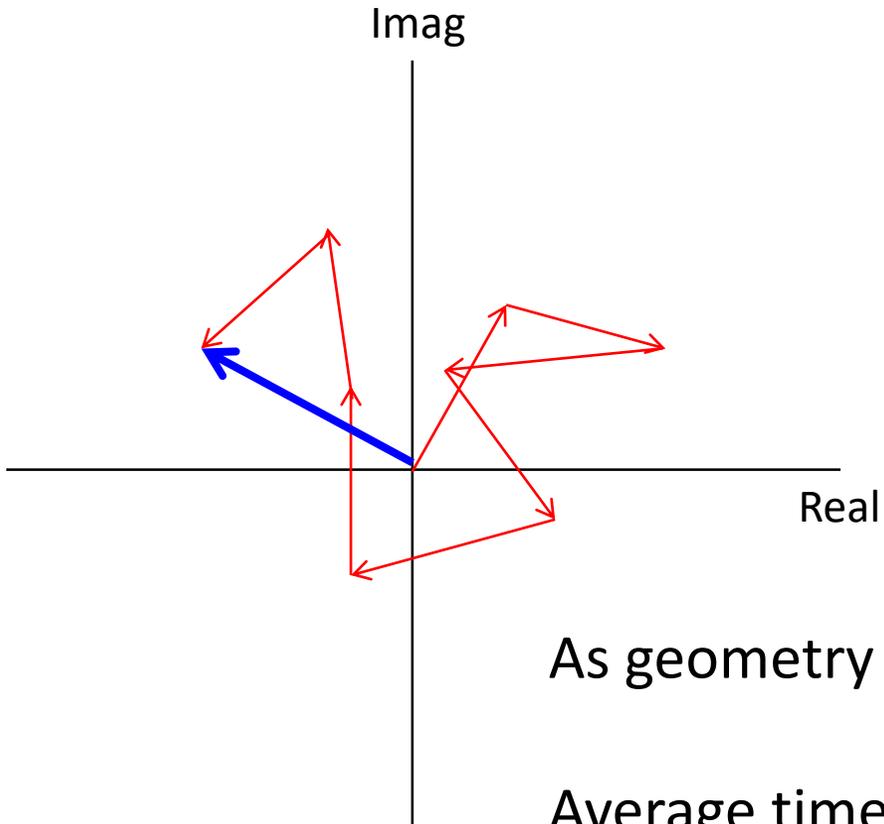
- This technique measures surface Mean-Squared Slopes (MSS)
- MSS related to wind speed through empirical model

## Altimetry

- Specular timing relative to direct-signal reception

## Signal Incoherence

- Received signal is sum over all surface facets
- Rough surface: resulting phasor has random phase
- Resulting power is exponentially distributed  
=> Power SNR = 1 (speckle)



As geometry changes (receiver movement) the phasor sum changes.

Average time for phasor sum to be uncorrelated to previous sum is the signal's correlation time.

Aircraft: ~10 msec

Spacecraft: ~1 msec

# What Measurements Can GNSS-R Make?

## Oceanography

- Surface winds (CyGNSS Mission: Cyclones)
- Mesoscale topology
- Tsunami science/warning
- Geoid / Mean Sea Surface

*Red: Demonstrated from space*

*Green: Ground, aircraft experiments*

## Land

- Soil Moisture
- Wetland Extent
- Freeze/Thaw State
- Vegetation Characteristics

## Cryosphere (assuming high-inclination orbit)

- Sea-Ice Extent
- Ice freeboard
- snow depth
- Ice roughness / age

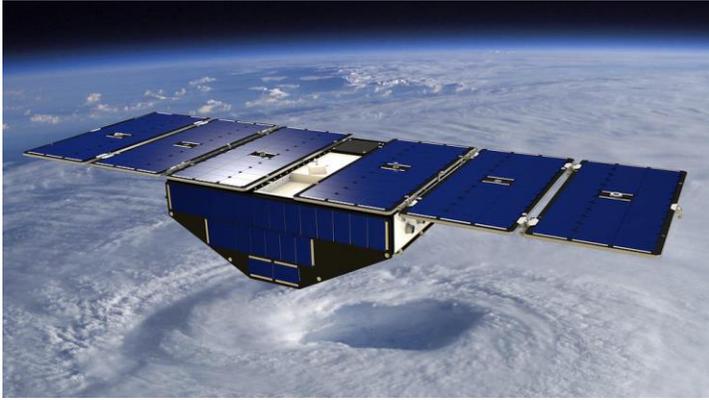
## What's Happening in the GNSS-R Field?

<u>Mission/Satellite</u>	<u>Year</u>	<u># Space GNSS Reflections</u>
SIR-C	2003 (obtained)	2
SAC-C	2003	~6
UK-DMC	2007	22
TechDemoSat1	2015-2017	~100M
SMAP (GNSS-R)	2015-present	>2.3M + 2900/day
CyGNSS (8 sats)	2017-present	>125M + 0.5M/day

Explosion of data in last 2 years

# What's Happening in the GNSS-R Field?

CyGNSS Satellite

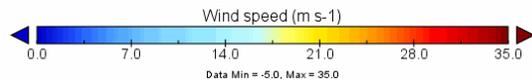
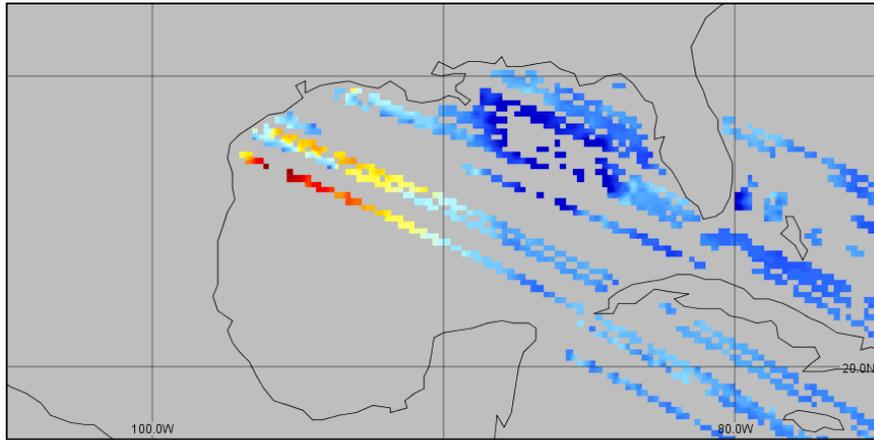


## CyGNSS: NASA Earth Venture Mission

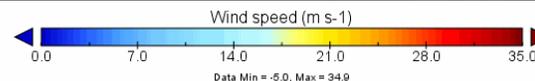
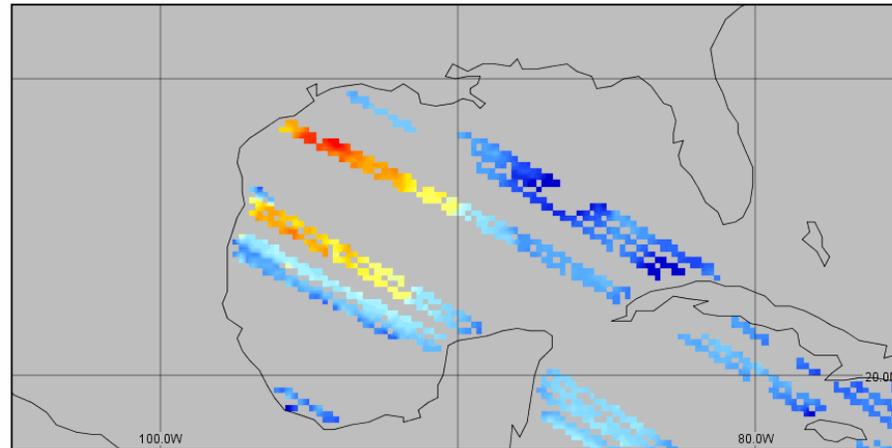
- \$157M to study Cyclone Science
- Goal: Improved cyclone intensity forecast
- 8 small-sats
- Observe GPS L1 C/A signals after reflecting from the ocean

## Observations of Hurricane Harvey Prior to Landfall on August 25, 2017

CyGNSS Ocean Surface Wind speed  
2017-08-25T1330 UTC



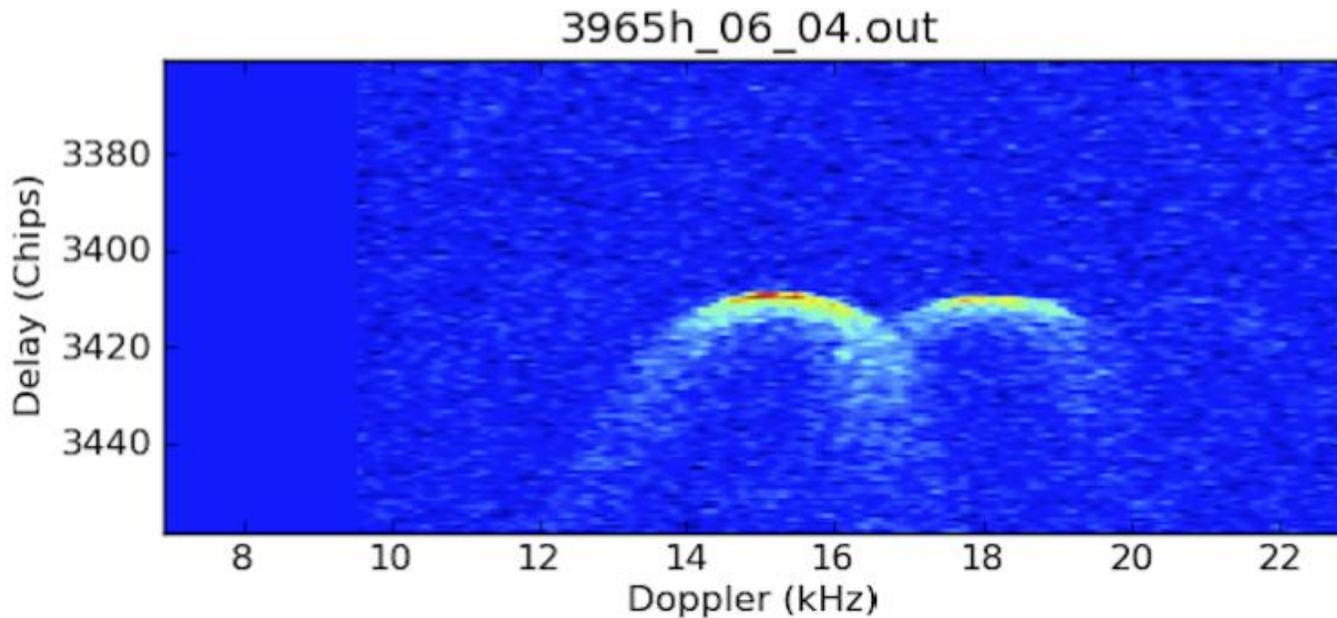
CyGNSS Ocean Surface Wind speed  
2017-08-25T1430 UTC



*Courtesy Chris Ruf (PI)*

CyGNSS Level 3 gridded surface wind speed data product (v1.1) at 1300-1400 and 1400-1500 UTC on 25 Aug 2017, prior to landfall at ~0300 UTC on 26 Aug 2017

# What's Happening in the GNSS-R Field?



Delay-Doppler Map (DDM) has aliased images due to data blanking

## NASA's Soil Moisture: Active & Passive (SMAP)

- Dedicated soil-moisture mission
- Active L-band radar + passive radiometer
- Radar transmitter failed 7/7/15
- On 8/20/15, radar receiver moved to collect GPS L2

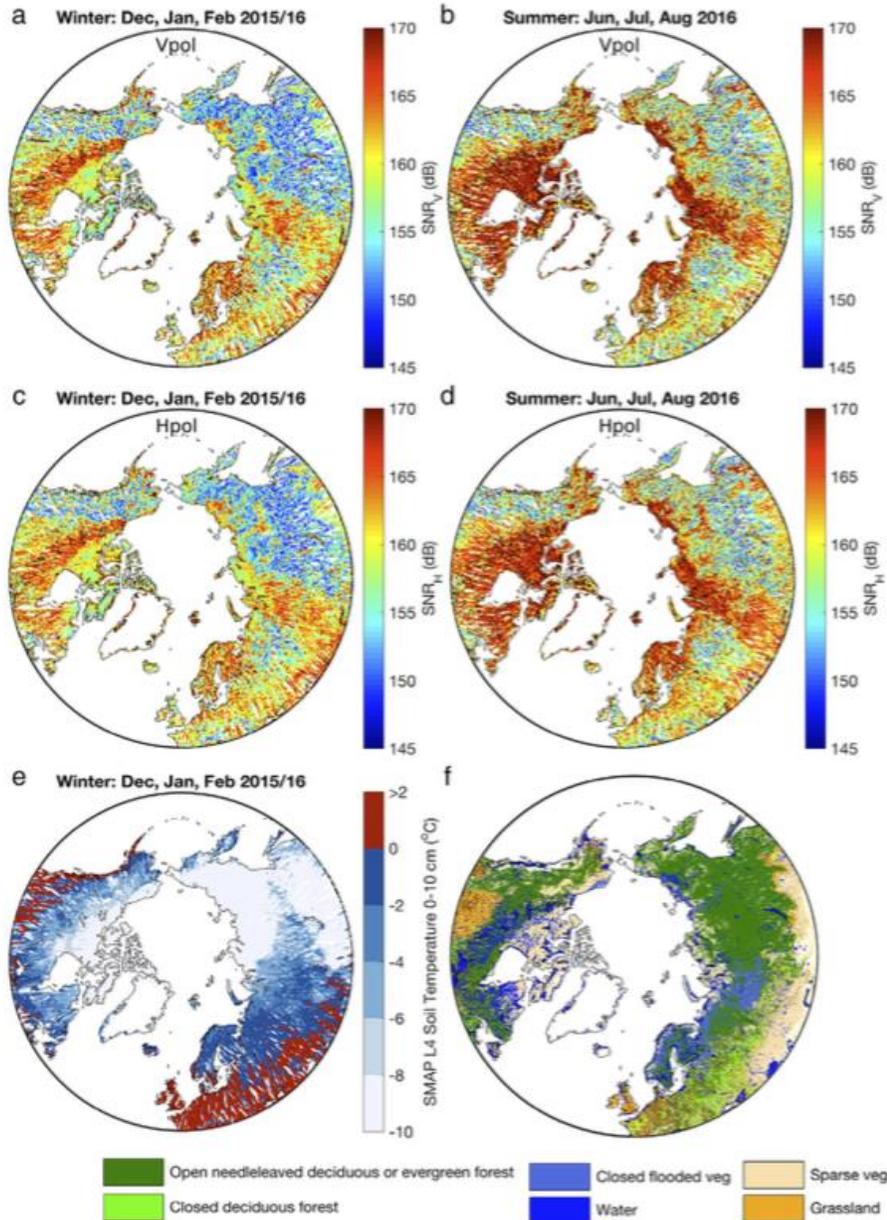
## Unique GNSS-R data set

- High gain antenna (~30 dB)
- Dual polarization (H/V)
- Raw sampled data downloaded
  - Look at phase, coherence, integration times, etc
- Hope to make DDM + metadata public soon

Created unique GNSS-R data set from failed radar system

# What's Happening in the GNSS-R Field?

C. Chew et al. / Remote Sensing of Environment 198 (2017) 333-344



SMAP GNSS-R Observes Freeze/Thaw

Vertical Polarization

Winter

Summer

Horizontal Polarization

Winter

Summer

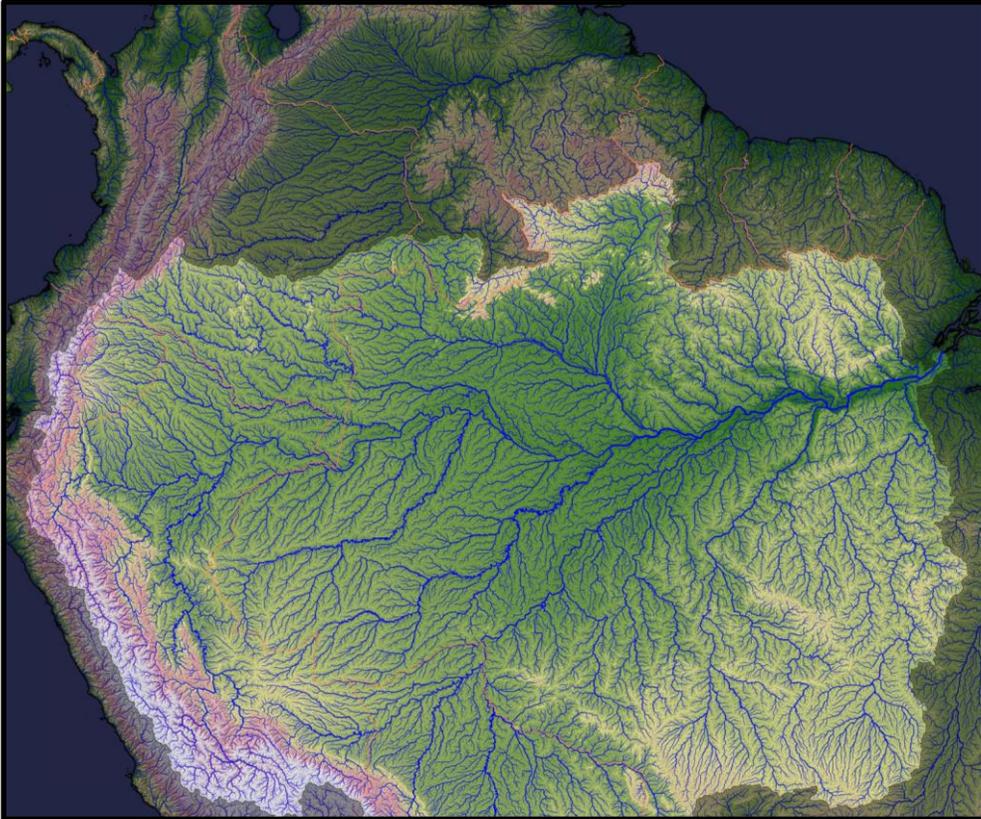
Winter Temp  
(blue frozen)

Vegetation Type

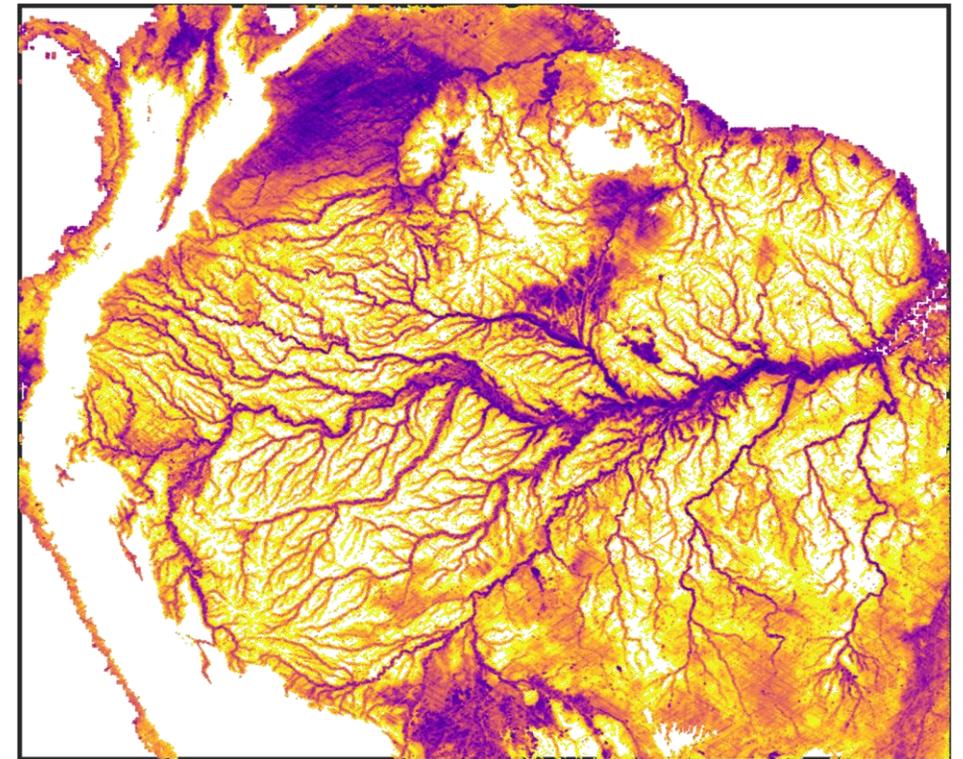
From Chew et al, Remote Sen Env 198, 2017

# What's Happening in the GNSS-R Field?

HydroSheds Database



CyGNSS Data: SNR vs location



White: Outside CyGNSS delay window

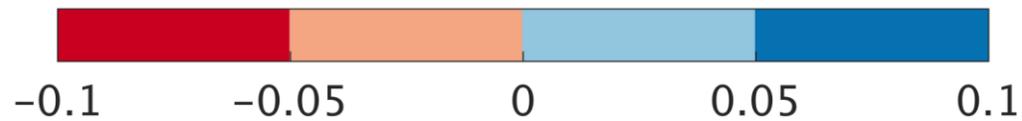
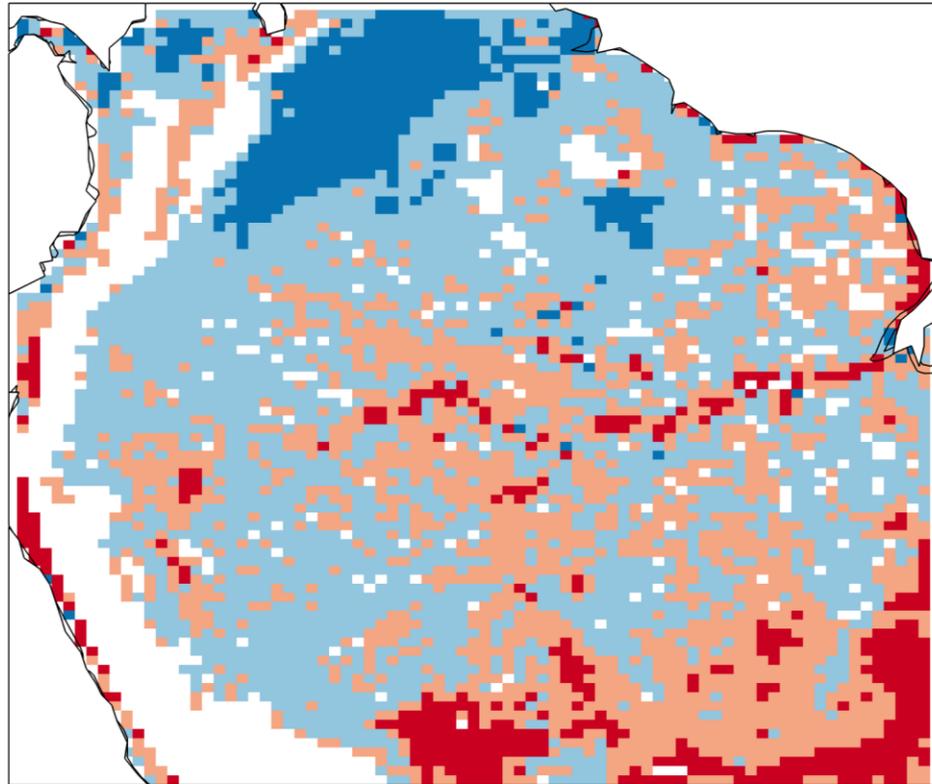
Amazon Rainforest

*Courtesy Clara Chew (UCAR)*

# What's Happening in the GNSS-R Field?

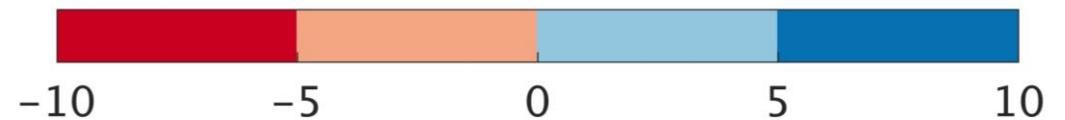
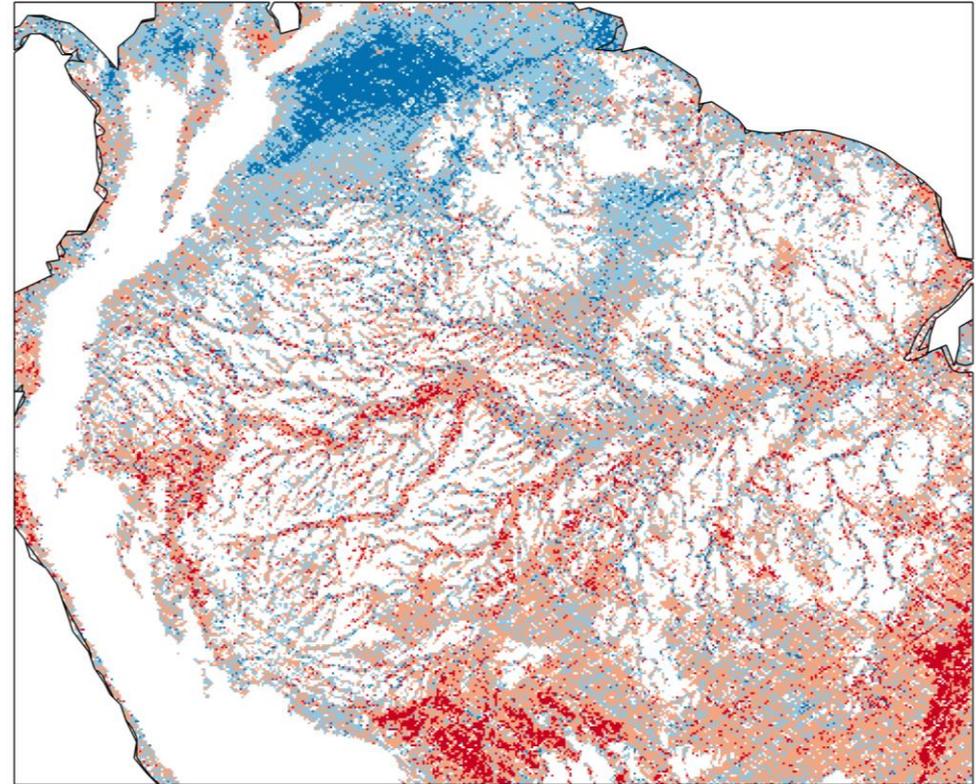
Change in SNR: Aug - Mar

SMAP Radiometer (J. Du, et al)



$\Delta$ Inundation

CyGNSS Data



$\Delta$ SNR (dB)

Amazon Rainforest

*Courtesy Clara Chew (UCAR)*

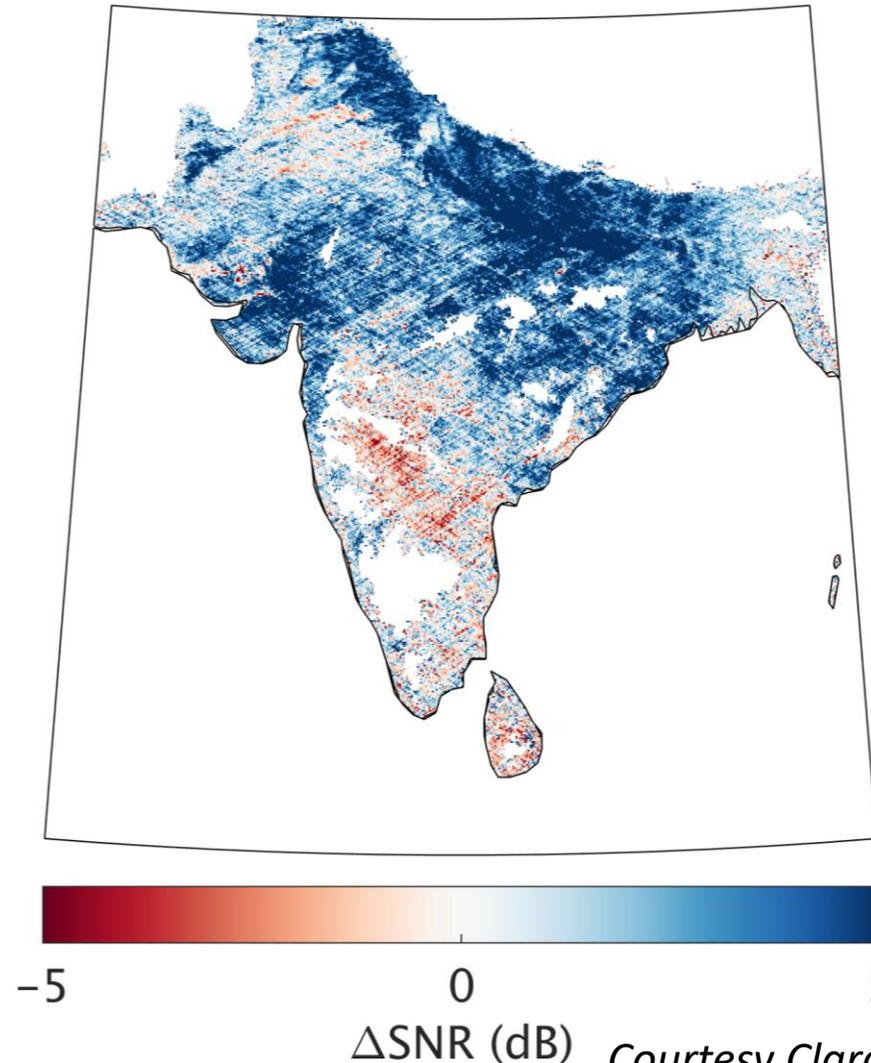
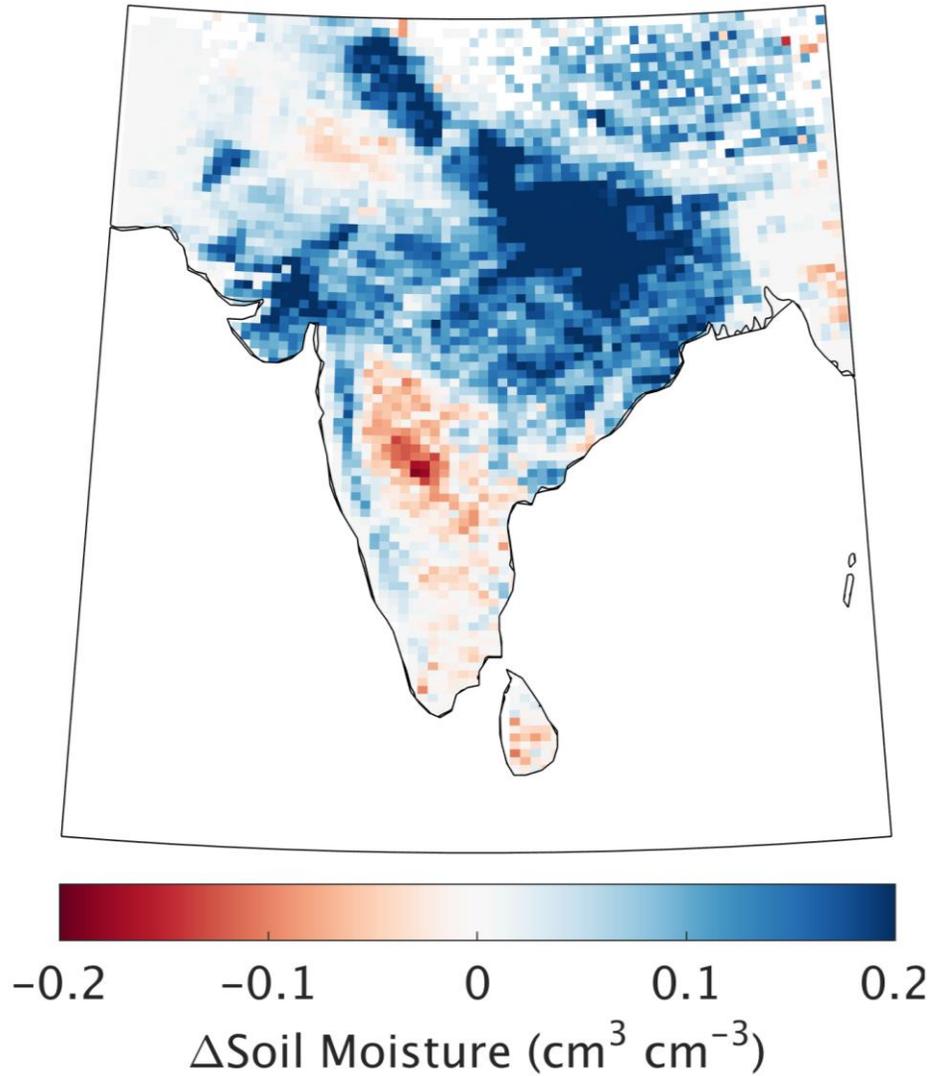
# What's Happening in the GNSS-R Field?

Change in SNR: Apr - Mar

SMAP Radiometer: Level 3

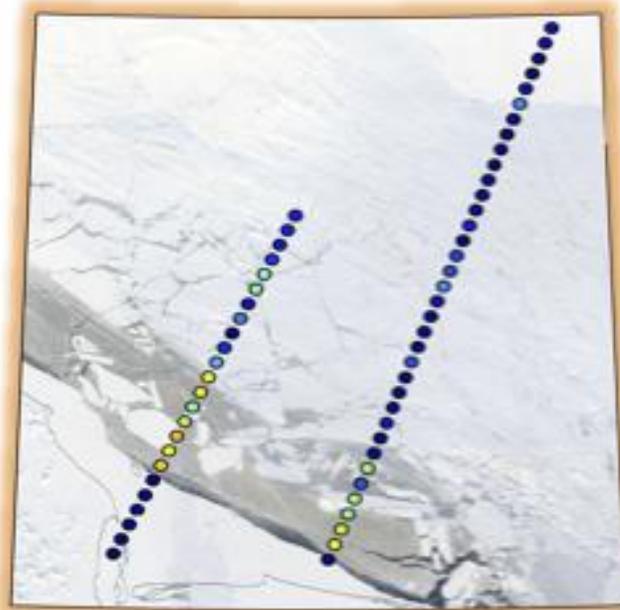
CyGNSS Data: SNR Change

India



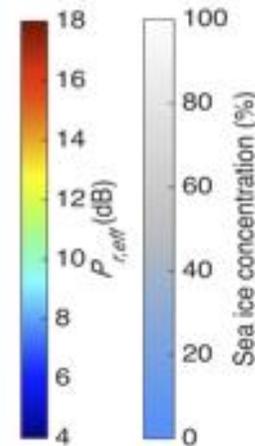
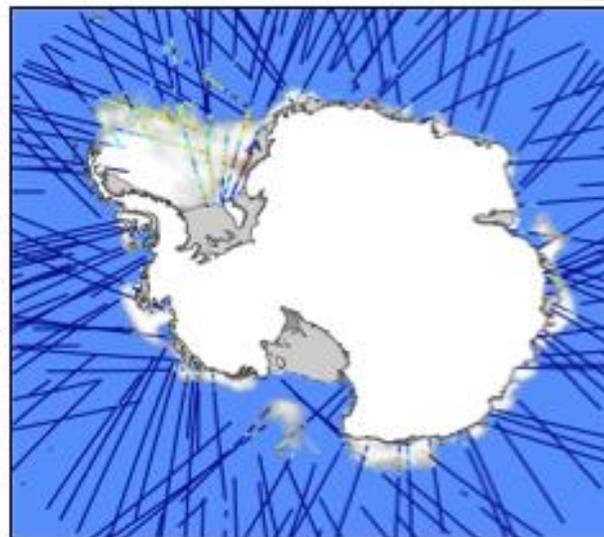
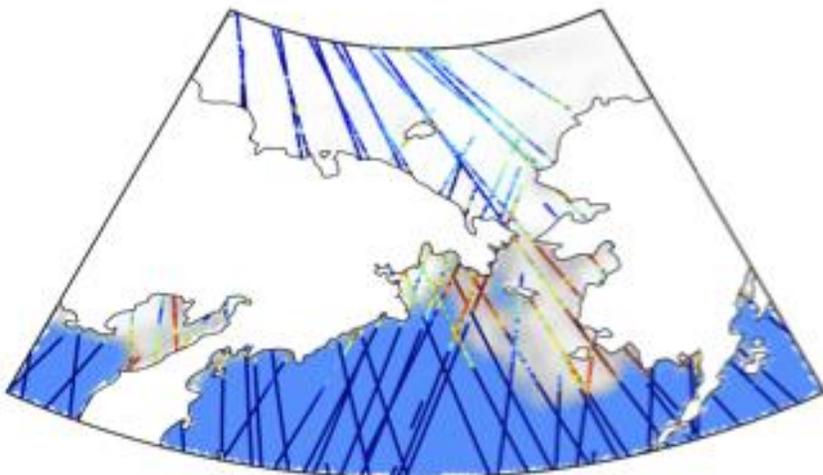
*Courtesy Clara Chew (UCAR)*

# What's Happening in the GNSS-R Field?



## TechDemoSat-1 Data

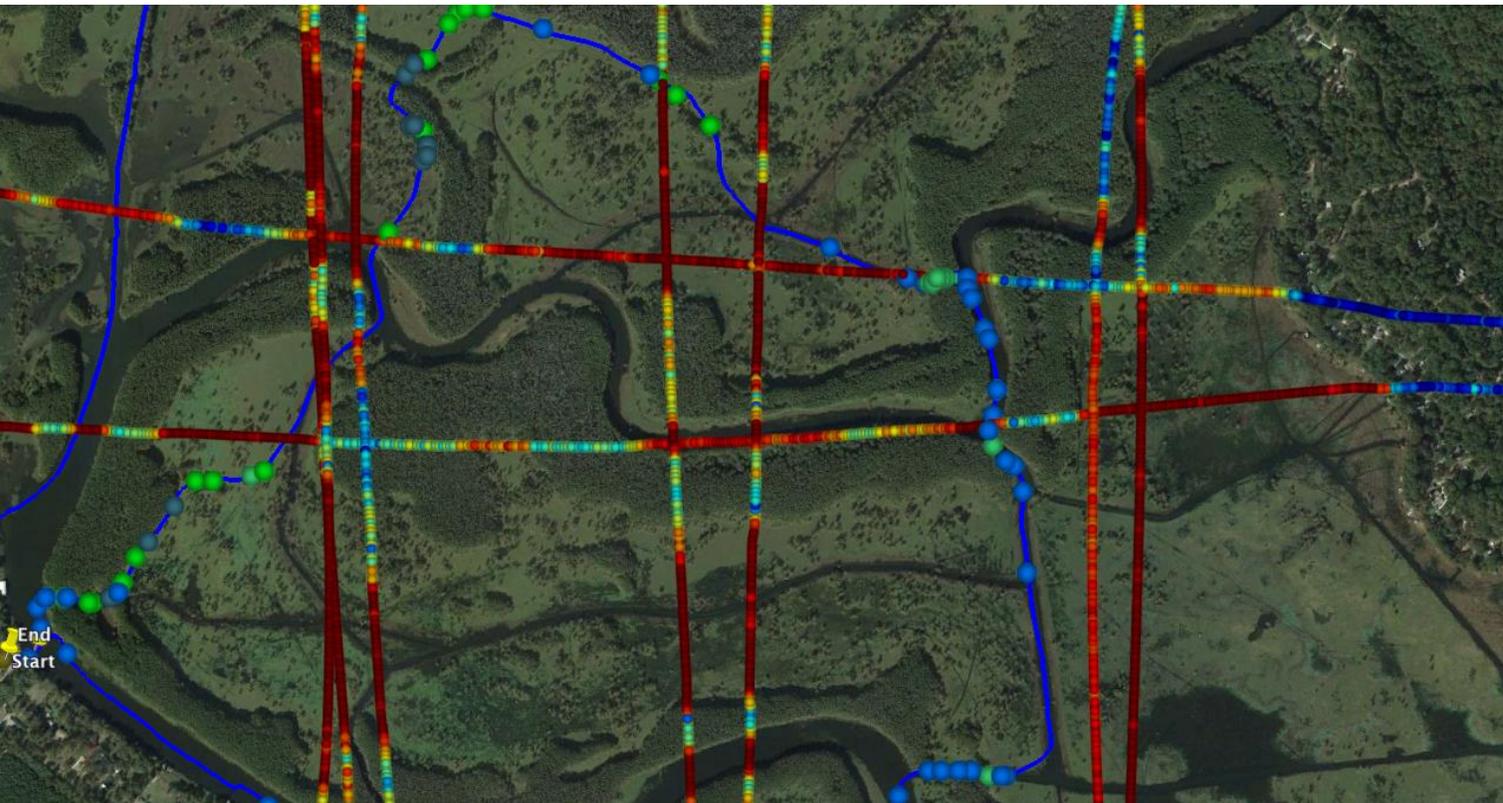
- Higher power over ice leads and polynyas
- Up to 10 dB increase
- Not seen in passive microwave



- Increased P on ice edges
- Highest P intermediate sea ice conditions

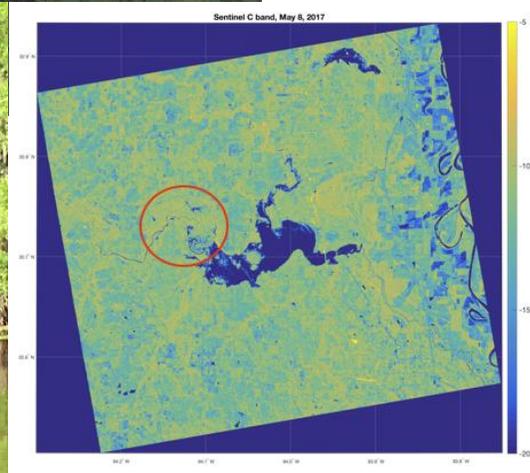
*Courtesy Clara Chew (UCAR)*

# What's Happening in the GNSS-R Field?



## Wetland Inundation Extent

- Connection to methane production
  - Potent greenhouse gas
- Can forward-scattered GNSS-R signals penetrate vegetation to sense underlying inundation?
- May 2017 aircraft experiment: Caddo Lake LA
  - 20 dB blue to red scale
  - Light green: Giant Salvia
  - Dark green: Cypress
  - Backscatter radar shows little water

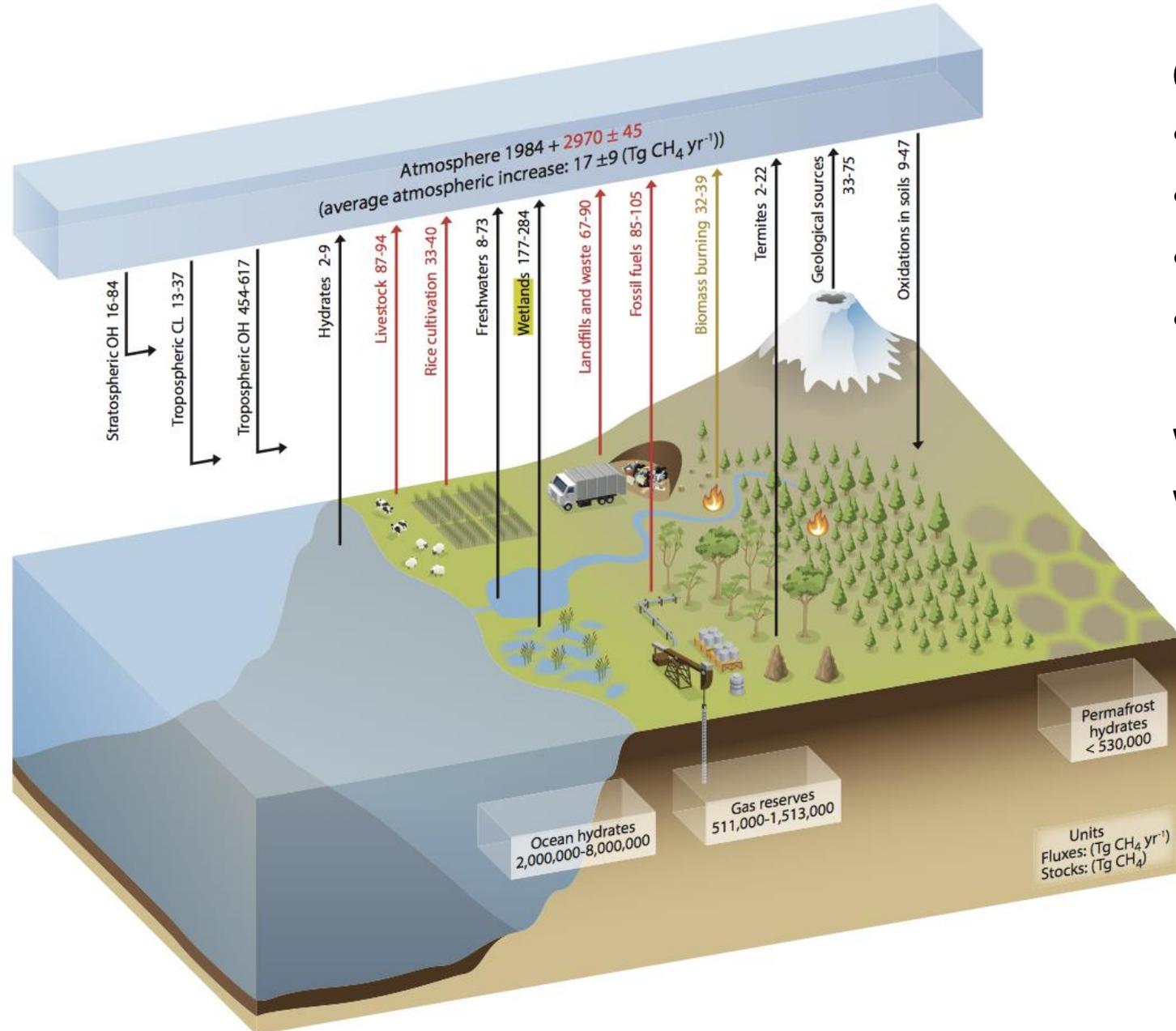


# Summary

- GNSS-Reflectometry is a new Earth-remote sensing technique
- Explosive growth since 2015: TDS-1, SMAP, CyGNSS
- Many unique advantages compared to other remote sensing techniques
  - High spatial/temporal coverage, forward scattering, GNSS-RO-compatible, long-term SI-traceable signals
- Active research underway:
  - Ocean winds, soil moisture, wetland extent, freeze-thaw state, sea ice extent, ocean altimetry

Backup Slides

# Global Methane Cycle



## Contributions to Atmospheric Methane

- Wetlands (177-284 Tg/yr)
- Fossil Fuels (85-105 Tg/yr)
- Livestock (87-94 Tg/yr)
- Landfills (67-90 Tg/yr)

Wetlands has largest contribution  
Wetlands has largest uncertainty range

IPCC (2013), Climate Change 2013: *The Physical Science Basis*, Contribution of Working Group I to the Fifth Assessment Report of the Intergovernmental Panel on Climate Change