

# A Multi-Mission Solution for Rapid Telemetry Query and Display

Chelsea Dutenhoffer

Brian Chafin

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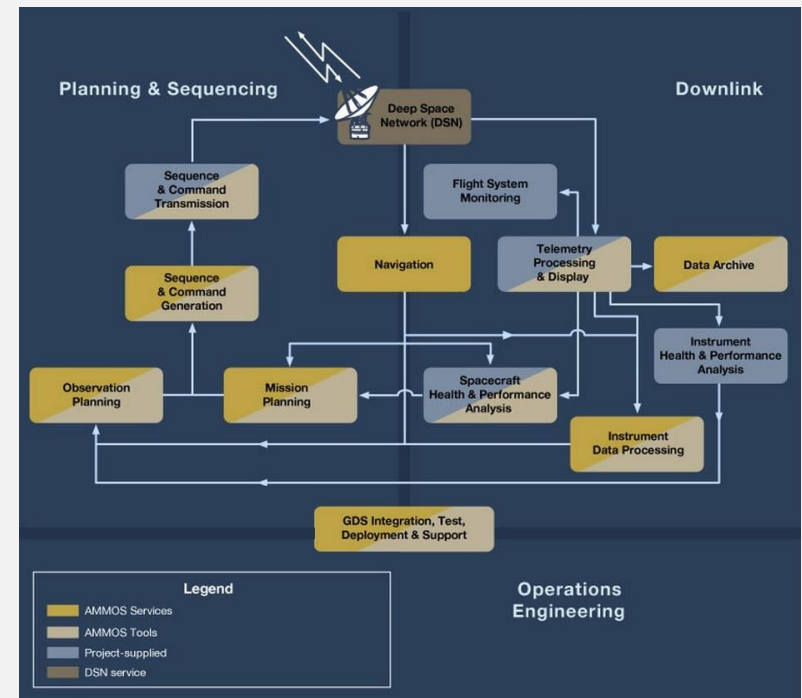
# Purpose of AltiMOS

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- ◆ JPL instruments contributed to a continuous record of ocean surface topography for the past 25 years
- ◆ Three missions under development will continue similar measurements into the 2030s
- ◆ Goal: using Jason-3 as a pilot mission, architect and set up a modernized MOS/GDS system
  - ◆ New system should have at a minimum all the features of the existing Jason-3 GDS
    - ◆ New system does not need to handle realtime telemetry viewing for Jason-3, but may need to for future missions
  - ◆ Take advantage of existing multi-mission and JPL heritage GDS components
  - ◆ Utilize shared or common hardware and software across AltiMOS missions where appropriate

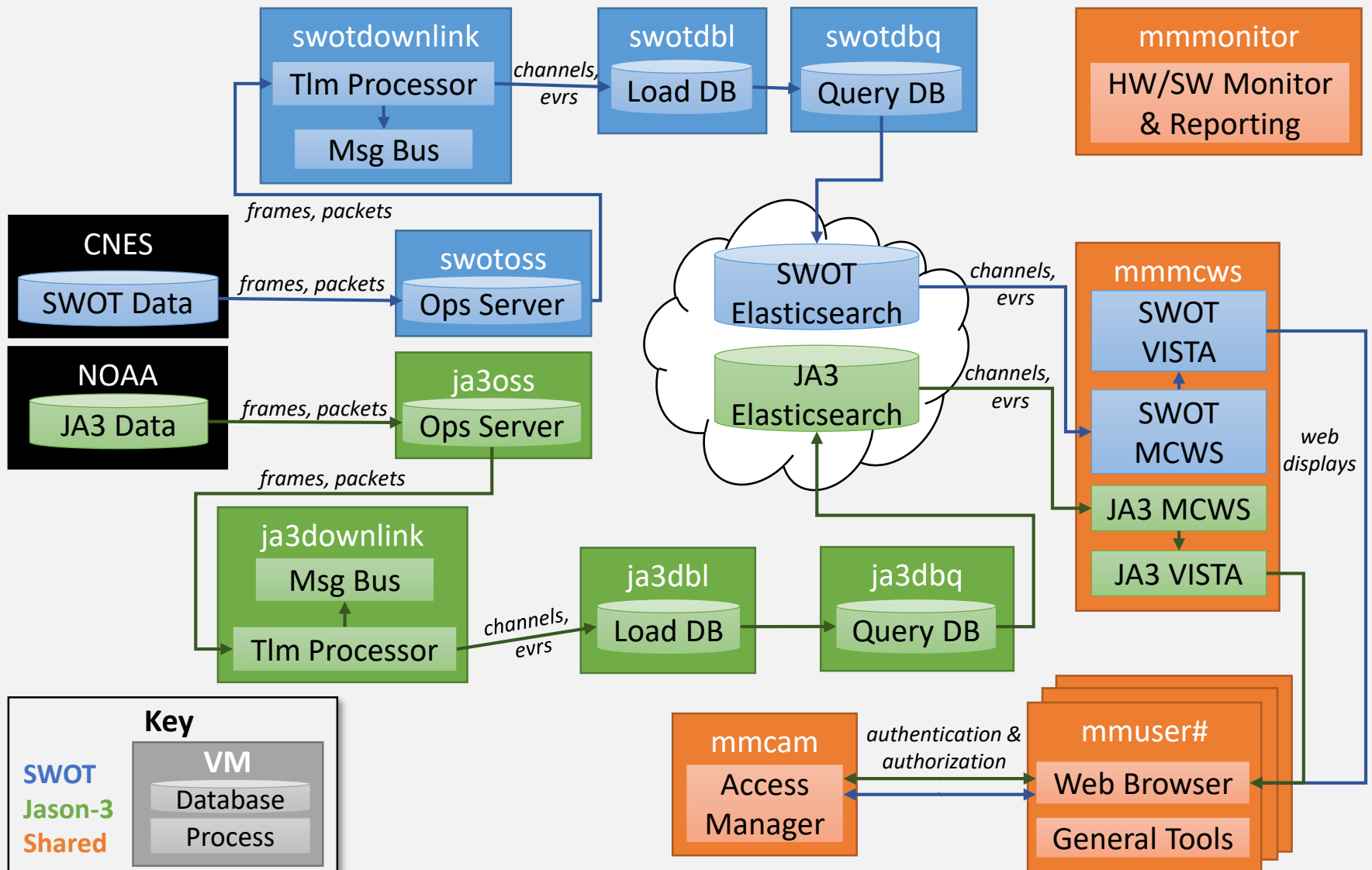
# Multi-Mission Software

- ◆ The Advanced Multi-Mission Operations System (AMMOS) reduces mission costs by providing Mission Operations System (MOS) products and services common to multiple missions.
- ◆ AMMOS reduces mission development cost and schedule with functions that missions would otherwise develop and maintain themselves.
- ◆ AMMOS is available to NASA and partner organizations.
- ◆ Website: [ammos.jpl.nasa.gov](http://ammos.jpl.nasa.gov)
- ◆ Contact: [ammos\\_info@jpl.nasa.gov](mailto:ammos_info@jpl.nasa.gov)



- ◆ Example: AMMOS Mission Processing and Control System (AMPCS) is a product that provides the following functions
  - ◆ Sequence & Command Transmission
  - ◆ Telemetry Processing & Display
  - ◆ Telemetry Archive

# GDS Architecture for Two Missions

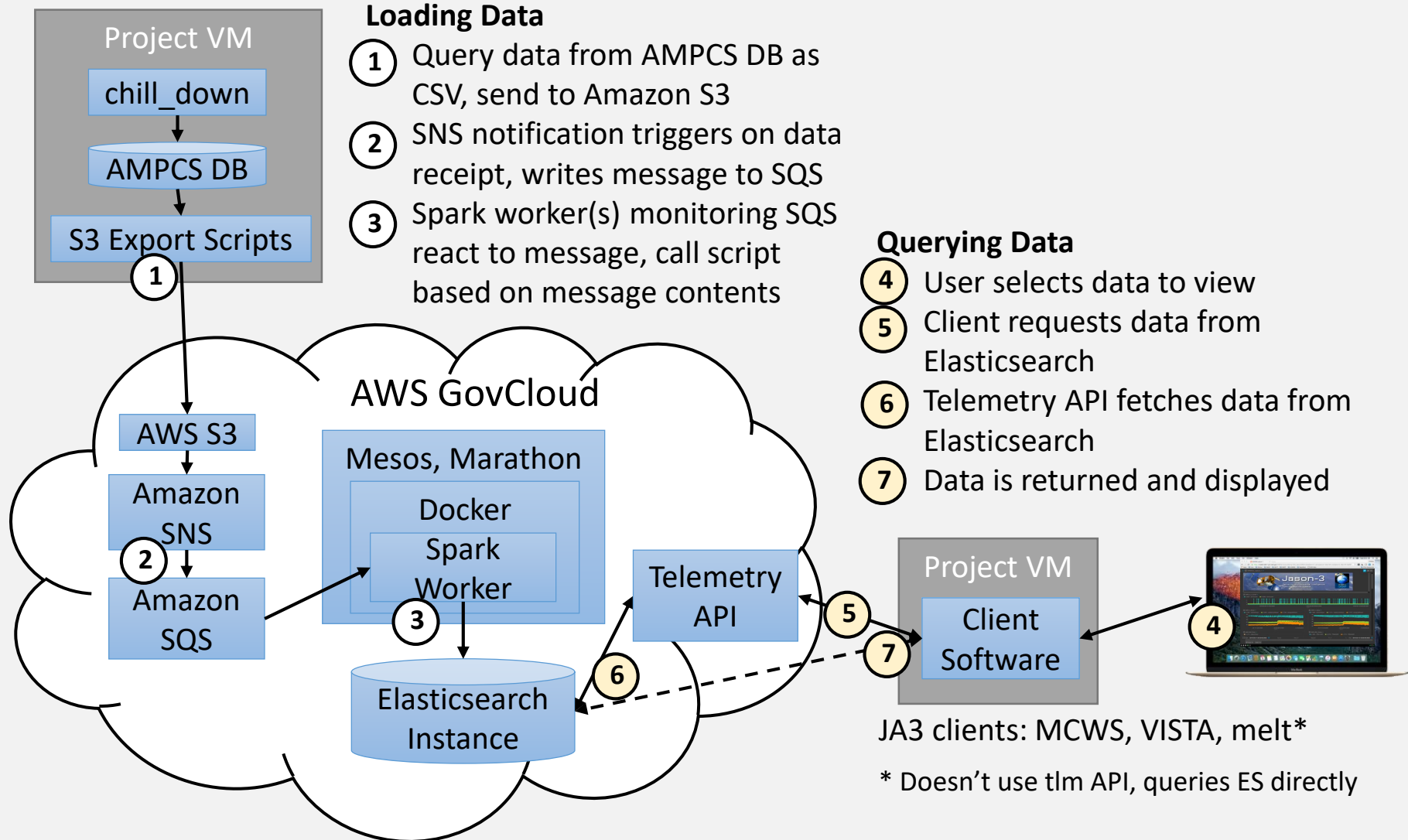


# Enabling Technology

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- ◆ Amazon GovCloud
  - ◆ Compute instances (EC2), data storage (S3 and EBS), notification service (SNS), message bus (SQS)
- ◆ Apache applications for cloud and big data
  - ◆ Hardware resource management (Mesos), container orchestration (Marathon), processing engine (Spark)
- ◆ Elasticsearch - open source product by Elastic Co.
  - ◆ Distributed search and analytics engine
- ◆ AltiMOS use based on JPL heritage from MSL and SMAP missions
  - ◆ JPL-developed infrastructure takes advantage of ES data aggregation features to enable fast telemetry query
  - ◆ Interfaces with multi-mission telemetry database via CSV file

# Processing & Query Data Flow



# Lessons Learned & Next Steps

- ◆ Learning curve
  - ◆ Team needs to learn several new technologies
  - ◆ Multiple knowledgeable eyes on the architecture preferred
- ◆ Establishing new ways of doing things
  - ◆ Often requires some trial and error; start slow and improve incrementally
  - ◆ Different projects have different needs, ex. Mars vs. Earth
- ◆ Cloud-based costs can add up quickly
  - ◆ Not currently dynamically scaling our hardware up and down
  - ◆ ES requires replicas, so pay to store same data twice
- ◆ Next steps
  - ◆ Archive large indices to cheaper storage, auto-restore as needed
  - ◆ Add index to improve “on change” query performance



# Backup

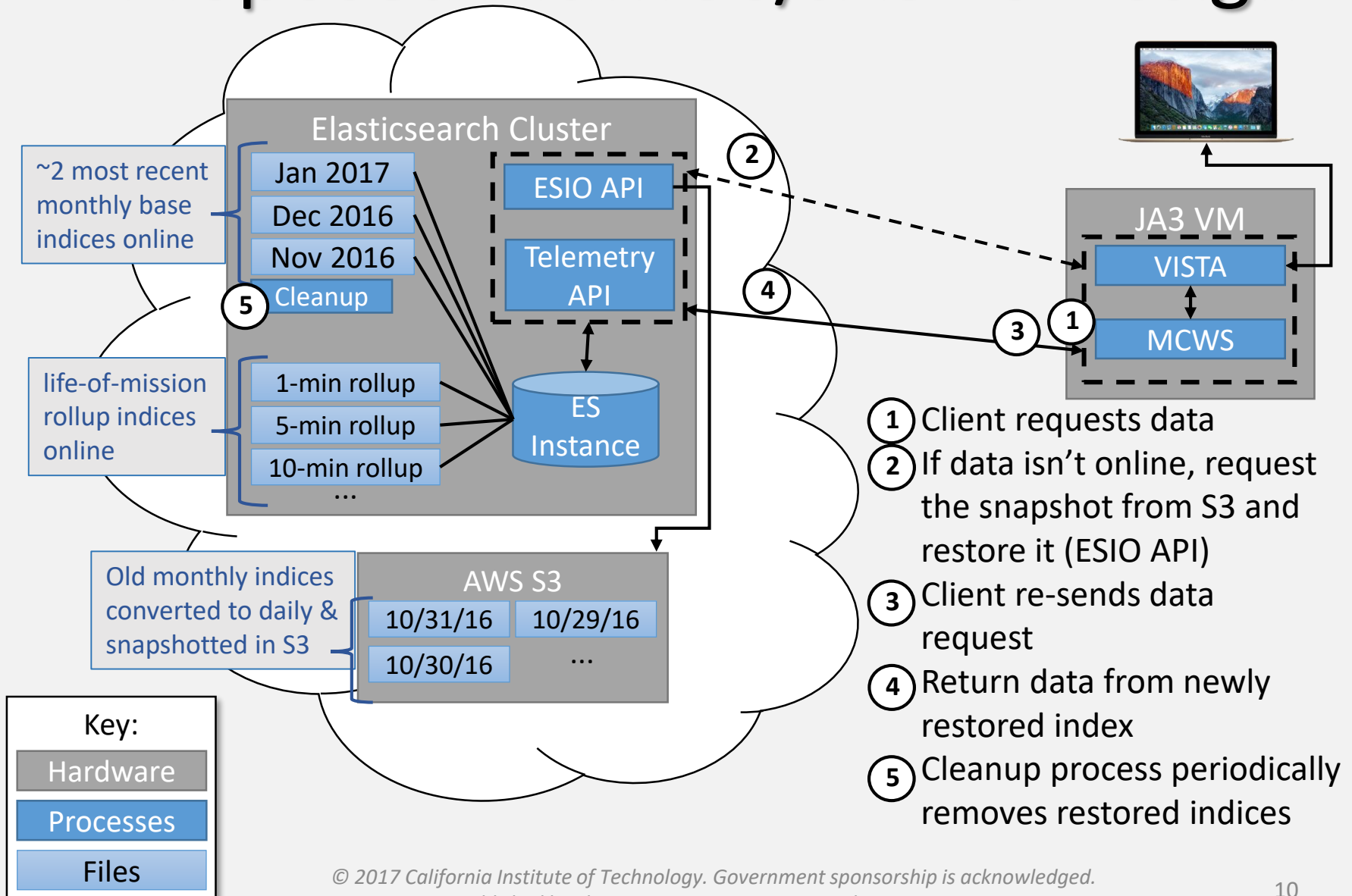


# Earth Altimetry Missions

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- ◆ European-built spacecraft flying JPL instruments
  - ◆ Topex/Poseidon (1992 - 2005)
  - ◆ Jason-1 (2001 - 2013)
  - ◆ Jason-2/OSTM (2008 - present)
  - ◆ Jason-3 (2016 - present)
  - ◆ Jason-CS/Sentinel-6
    - ◆ Sentinel-6a (2020 - 2026)
    - ◆ Sentinel-6b (2026 - 2031)
  - ◆ SWOT (2021 - 2024)
- ◆ All have contributed to a 25-year continuous record of ocean surface topography data

# Proposed AltIMOS/JA3 ES Design



# Shared Hardware Architecture

