

Design of a Data-Driven Micro-Display for Situation Awareness in Bursty Environments



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UC Santa Cruz – Department of Computer Science
JPL/Caltech – Human Interfaces Group



Design of a Data-Driven Micro-Display for Situation Awareness in Bursty Environments*

*(when not much is happening most of the time)



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California Institute of Technology,
NASA Jet Propulsion Laboratory in Pasadena, CA
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2011 Advancement to Candidacy
(Computer Science)

2010 MS Computer Engineering
()

2003 BS Computer Engineering
BS Mathematics

20+ Papers published

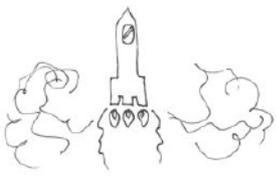
17 Co-authors

5 Classes instructor / TA

5 Fields

1 Keynote address

- Interaction Design** How IxD complements and differs from user research
- Complex Systems** Characteristics and examples, and why monitoring and controlling is hard
- The Deep Space Network** What it is, how operators work it, and what we learn
- The Postage Stamp** Intervention design, implementation, and reception
- Implications** Automation, simulation, design analogy, and situation awareness advancements



Interaction Design How IxD complements and differs from user research

Complex Systems Characteristics and examples, and why monitoring and controlling is hard

The Deep Space Network What it is, how operators work it, and what we learn

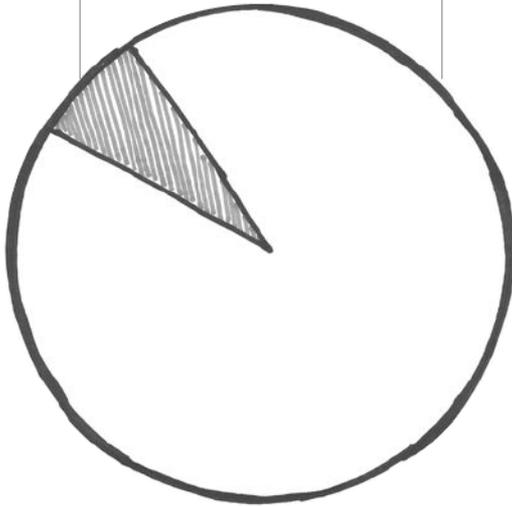
The Postage Stamp Intervention design, implementation, and reception

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Building stuff (10%)

Prototype

Creating low- to high-fidelity prototypes to support the work



User research (90%)

Ethnography

Examining how people work within their sociotechnical system

Design methods

Using design activities and techniques to elicit responses to specific inquiries

Goals for user research

- 1 Perceive the same things as users
- 2 Understand how users reason about the perceptions
- 3 Become adept at predicting the future state of a system, as the users do

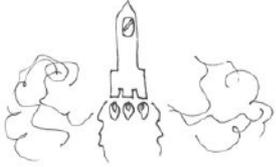


Goals for interaction design



- 1 Determine who the users are and what they need to see and do
- 2 Expose information, not data
- 3 Create the way users experience the changing states of a system

Interaction Design How IxD complements and differs from user research

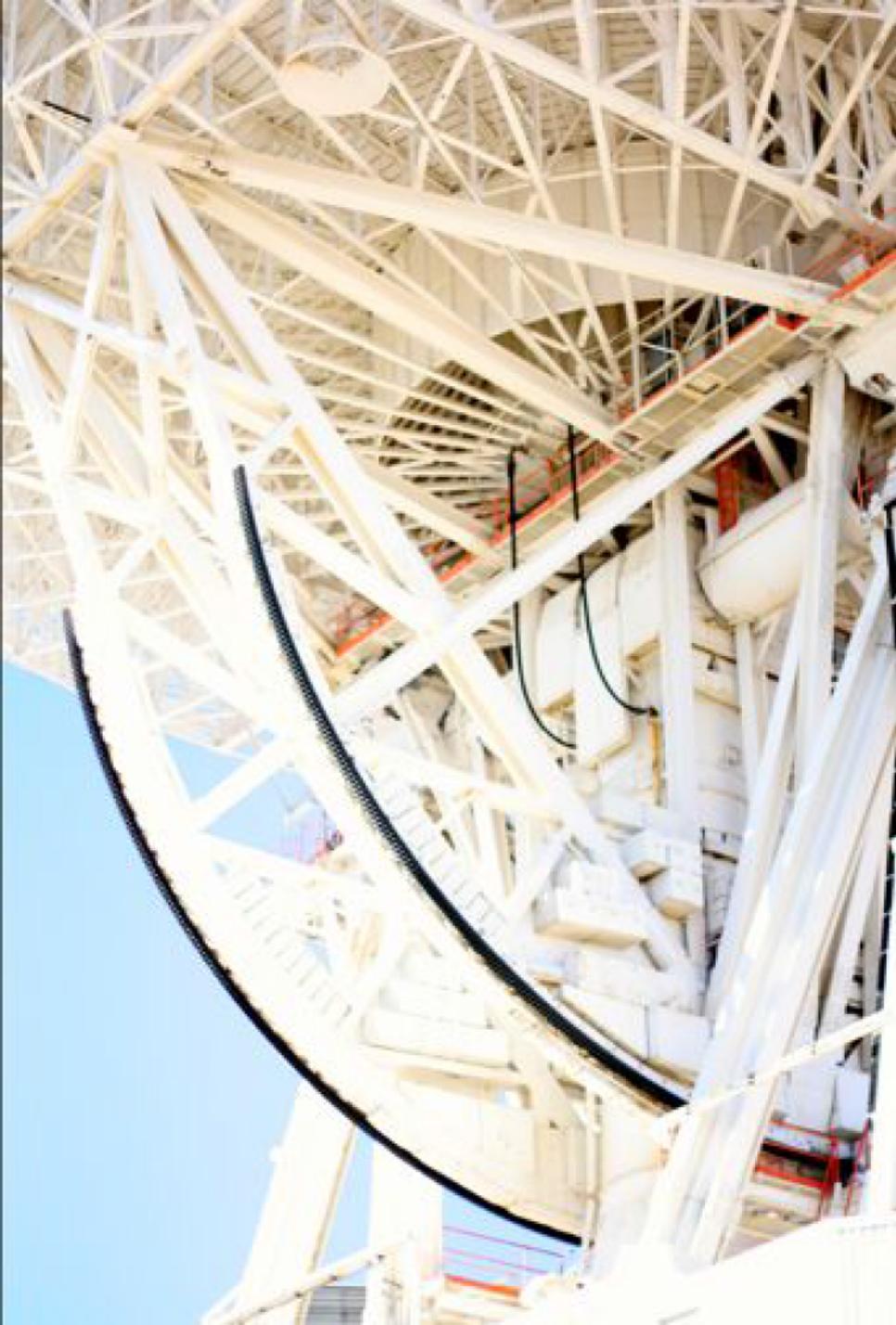


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Complex systems

Partially automated

Variety of sensor sources

Large aggregation of hardware, software, and human behavior

Great variety of states the system can assume

Causal relationships which may be distant in time and space

Feedback loops between system variables

High stakes (error risk)



Operation

Highly complex technical tasks

Primarily physical or perceptual tasks

Required timely decision-making

High variety of task situations

High task load

Required simultaneous secondary tasks

Highly trained operators

Complex systems need complex supervisors





In the head

Forming and maintaining a mental model of the system

In the world

System response to dynamic activity and operator input



In the head

Forming and maintaining a mental model of the system

In the world

System response to dynamic activity and operator input

If this were a cache

We would call this coherence

(but instead we can call it alignment)



Maintaining alignment in a partially-automated world



Situation Awareness

- L1 Perception of elements in current situation
- L2 Comprehension of the perceived data
- L3 Projection of future states

(Endsley, 1988)



Task Action Sequence

Execution

- 1 Set goals
- 2 Intend to act
- 3 Specify actions
- 4 Execute actions

Evaluation

- 5 Perceive system state
- 6 Interpret
- 7 Evaluate the outcome

(Norman, 1988)



Task Action Sequence

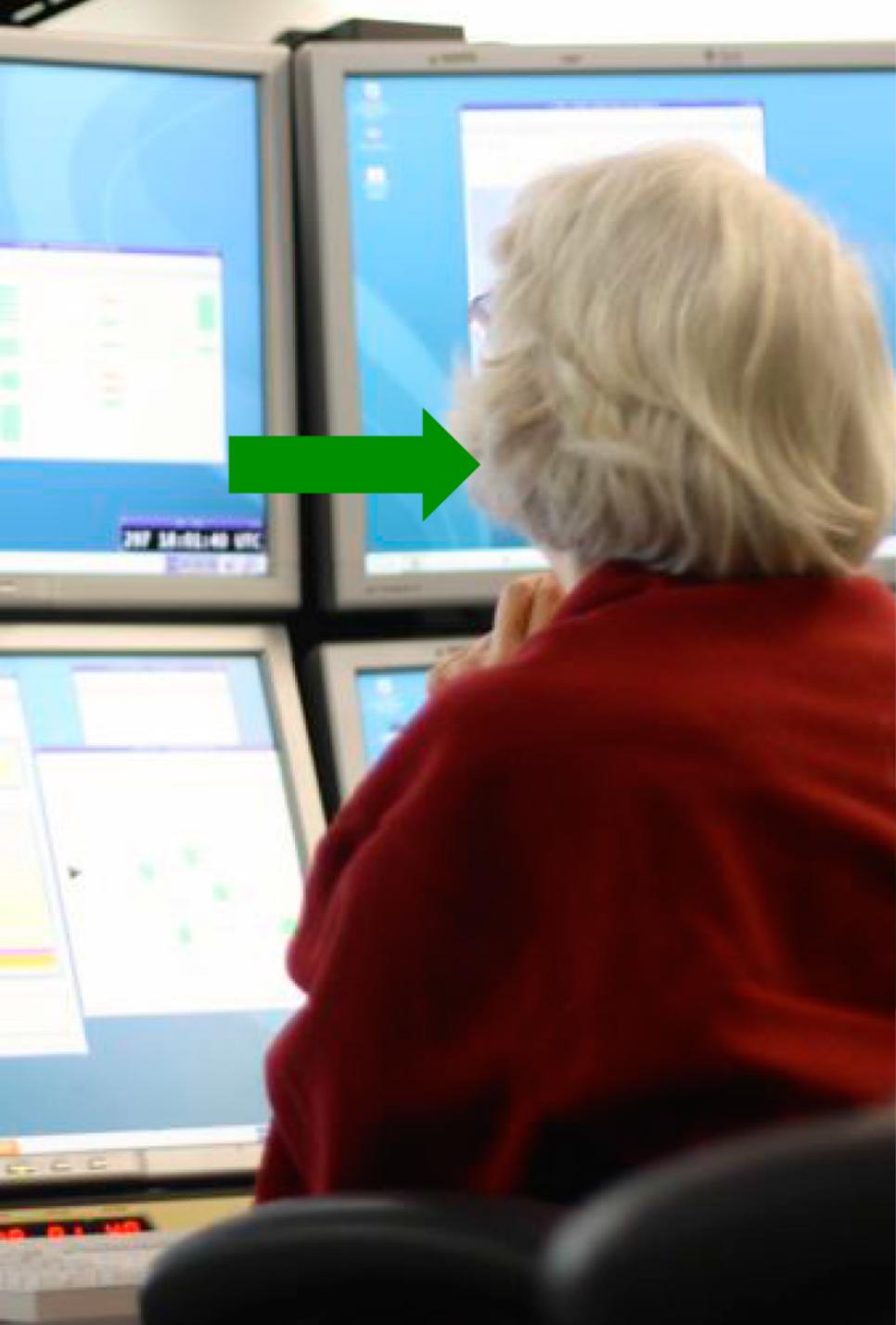
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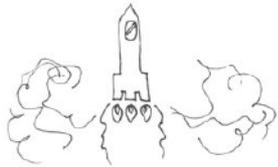
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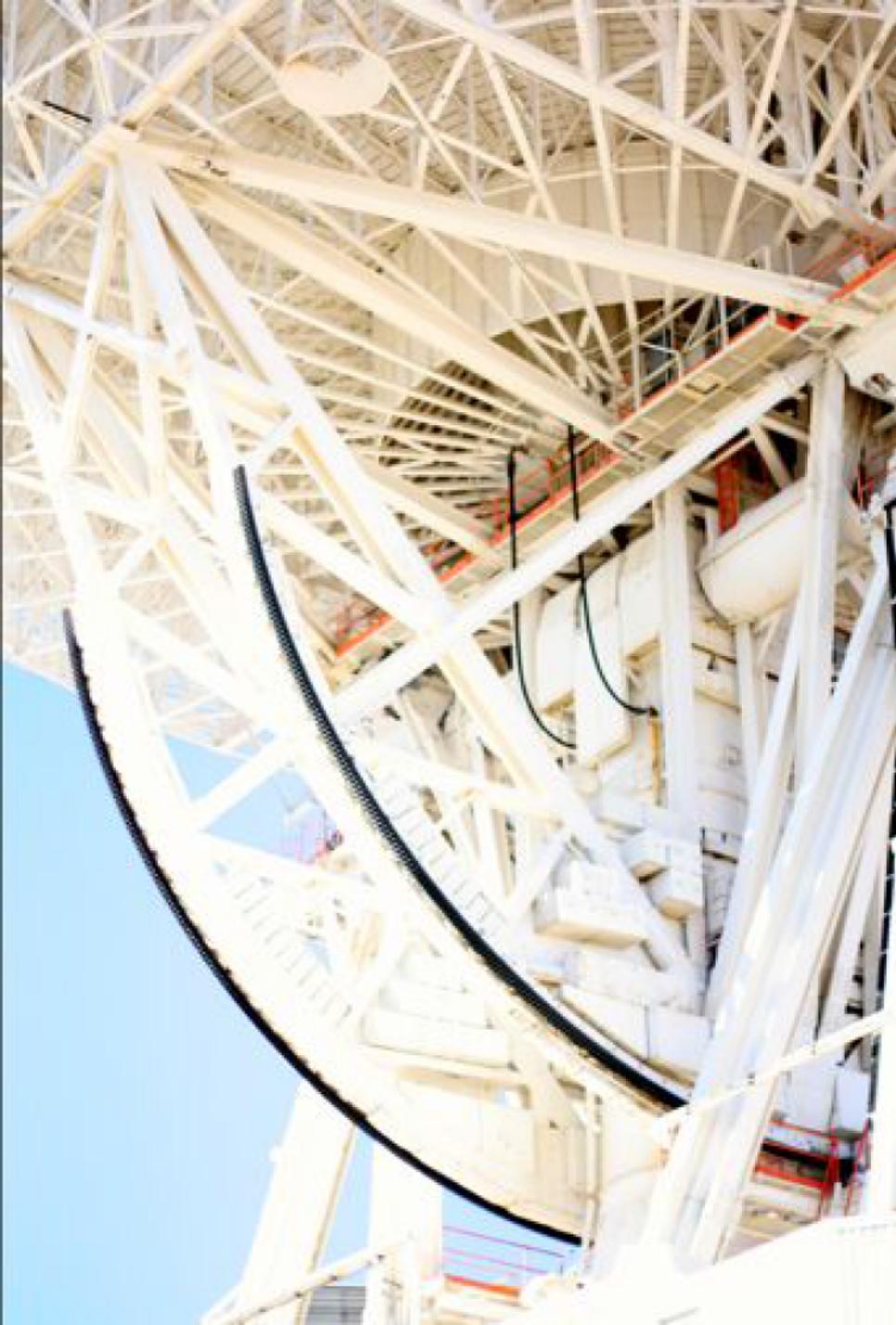


The Deep Space Network What it is, how operators work it, and what we learn

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Operating the Deep Space Network

1 Allocate resources

Set up and ensure proper working order of equipment for support activities

2 Operate and troubleshoot

Ensure supports are handled according to project instructions; prevent and respond to anomalies

3 Coordinate activities

Work with maintenance and test crews

4 Report and verify

Ensure and assist discrepancy reporting

5 Ensure safety

Be up to date on training and aware of surroundings



1 **Allocate resources**

Set up and ensure proper working order of equipment for support activities

2 **Operate and troubleshoot**

Ensure supports are handled according to project instructions; prevent and respond to anomalies

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Work with maintenance and test crews

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Be up to date on training and aware of surroundings





Prepare

Verify necessary support documents and equipment

Step 1



Pre-cal

Configure, calibrate equipment

Step 2



In-Track

Provide necessary support

Step 3



Post-cal

Cool down and stow equipment

Step 4



Report

Document discrepancies

Step 5



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Document discrepancies

Step 5



Prepare

Pre-cal

In-Track

Post-cal

Report

Mode changes such as
band, bandwidth, etc.

W

t

Displays

Scr: 053 / 0101 T: DSS: 54

101 11:05:11

IF Switch: 16554X01C1 (IF513114) S/C ID INFO: 001 **053** File Browser Summary

Receiver

ACQ RCV HALT RCV

CARRIER ACQ HALT

Loop Status OFF

Frq (Hz) 8406948316.3

Pc (dBm) -484.84

Pc/No (dB-Hz) -300.00

Carrier Resid (Hz) 111516.711

Predict Mode 1W

AGC (V) 1.762695

MP AGC (V) 0.019531

SNT (K) 23.246

SNT State ENABLED

Loop BW (Hz) 15.0000

SPE (deg) -152.43

FFT All CNF

SUBCARRIER ACQ HALT

Loop Status OFF

Frq (Hz) -0.00

Pd/No (dB-Hz) -300.00

Loop BW (Hz) 0.00000

SPE (deg) 90.0000

FFT All CNF

SYMBOL ACQ HALT

Loop Status OFF

Rate (sp/s) 85320.00

Pred Rate (sp/s) 85319.96

SNR (dB) -300.00000

Loop BW (Hz) 5.00000

SPE (deg) -105.00

FFT All CNF

Telemetry

ACQ TLP HALT TLP

Tim Predict Mode ENABLED

MCD3

IDLE

BSNR (dB) -1.96

MCV A1586

All CNF

FRAME SYNC

IDLE

In-Lock Frames 2802

Frame Error Rate 0.00

All CNF

REED-SOLOMON

IDLE

Frames 2804

Bad Codewords 60

Codeword Error Rate 0.00

All CNF

No CRC Validation

Tracking

RNG D RNG E

DCD Interface GO

Pacq (FDM) (%) 100.00

Pr/No (dB-Hz) 37.18

Residual (ru) 10671

DRVID (ru) -1

Rng Blocks Sent 5

Range Data ENABLED

Range Lock Status OFF

Car Blocks Sent 224

Carrier Data ENABLED

All CNF

Formatter

DCD Interface GO

Bit Rate (bps) 4258.66666

Pred Bit Rate 14220.0000

Blocks Sent 2817

Telemetry Data ENABLED

VS CNF

Channel Status/State

Channel RRP RNG TLP

ACTIVE ACTIVE IDLE IDLE

Performance Overviews

REC RRP DATA/IF

Assembly Configuration Overviews

Channel RRP TLP

OVERALL SUBSYSTEM

ACQ HALT ALL

D-C-D

Close

Displays Help

Sch: 053 / 0101 DSS: 54 101 11:05:11

IF Switch: 16554X01C1 (IF517114) S/C ID INFO: #01 **053** File Browser Summary

Receiver

ACQ RCV **HALT RCV**

CARRIER **ACQ** **HALT**

Loop Status: OFF

Frq (Hz): 8406948316.3

Pc (dBm): -484.84

Pc/No (dB-Hz): -300.00

Carrier Resid (Hz): 111516.711

Telemetry:

Tracking

RNG D **RNG E**

DCD Interface: 00

Pacq (FDM) (%): 100.00

Pr/No (dB-Hz): 27.18

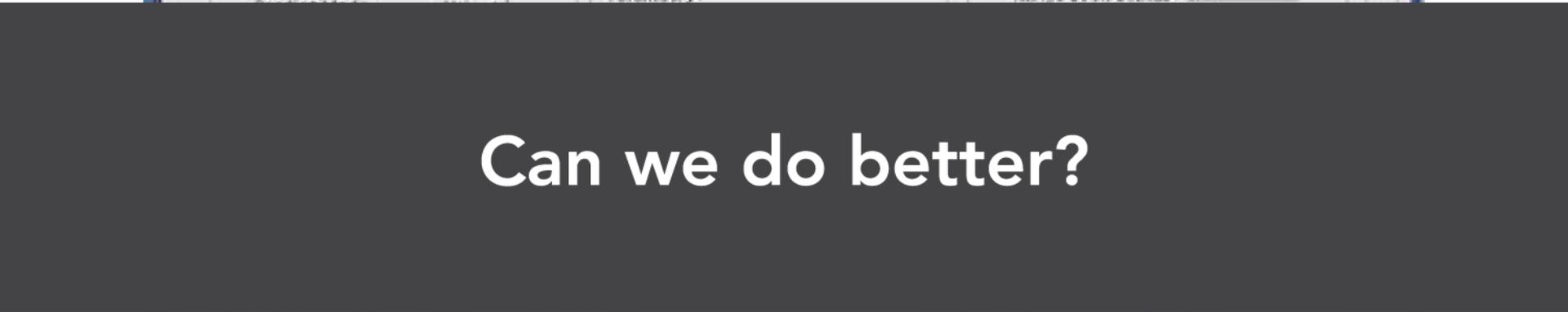
Residual (ru): 10671

DRVID (ru): -1

Rng Blocks Sent: 5

Range Data **ENABLED**

Range Lock Status: OFF



Can we do better?

FFT **All** **CNF**

SYMBOL **ACQ** **HALT**

Loop Status: OFF

Rate (sp/s): 85320.00

Pred Rate (sp/s): 85319.96

SNR (dB): -300.00000

Loop BW (Hz): 5.00000

SPE (deg): -105.00

FFT **All** **CNF**

IDLE

In-Lock Frames: 2802

Frame Error Rate: 0.00

ALL **CNF**

REED-SOLOMON

IDLE

Frames: 2804

Bad Codewords: 60

Codeword Error Rate: 0.00

ALL **CNF**

No CRC Validation

Channel Status/State

Channel **RRP** **RNG** **TLP**

ACTIVE **ACTIVE** **IDLE** **IDLE**

Performance Overviews

REC **RRP** **DATA/IF**

Assembly Configuration Overviews

Channel **RRP** **TLP**

OVERALL SUBSYSTEM

ACQ **HALT ALL**

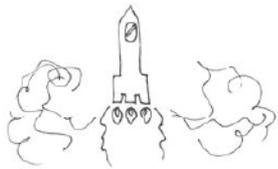
Close

Number of predict codes: 3

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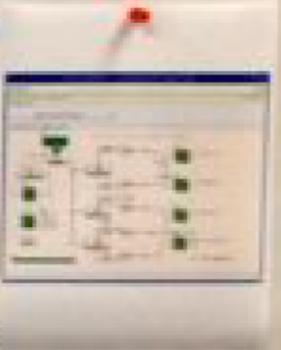
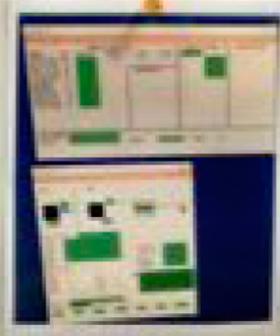
The Postage Stamp Intervention design, implementation, and reception

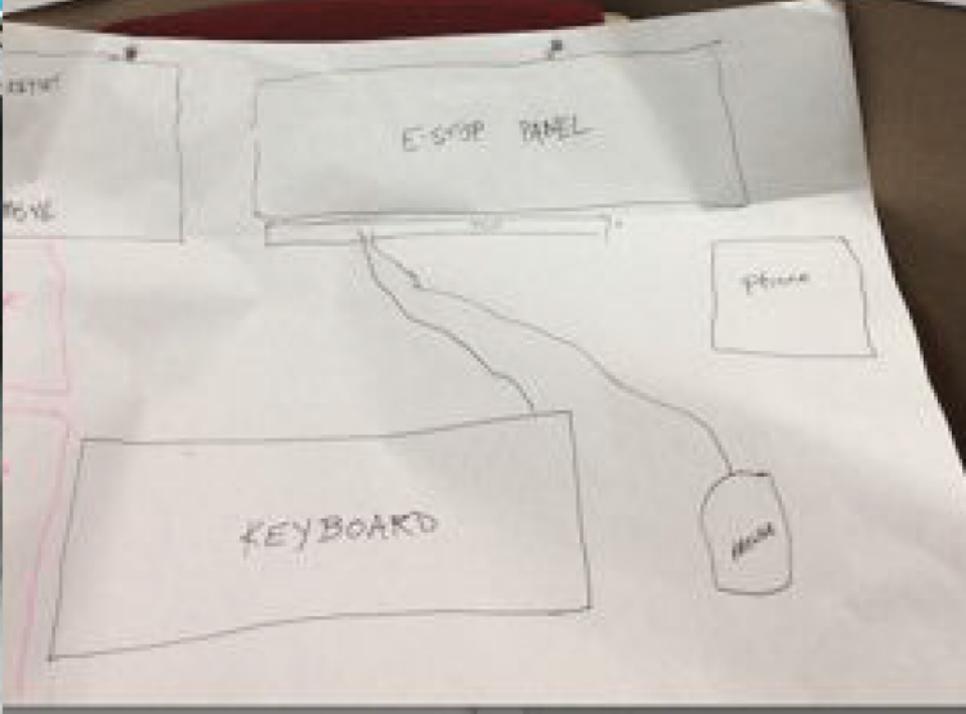
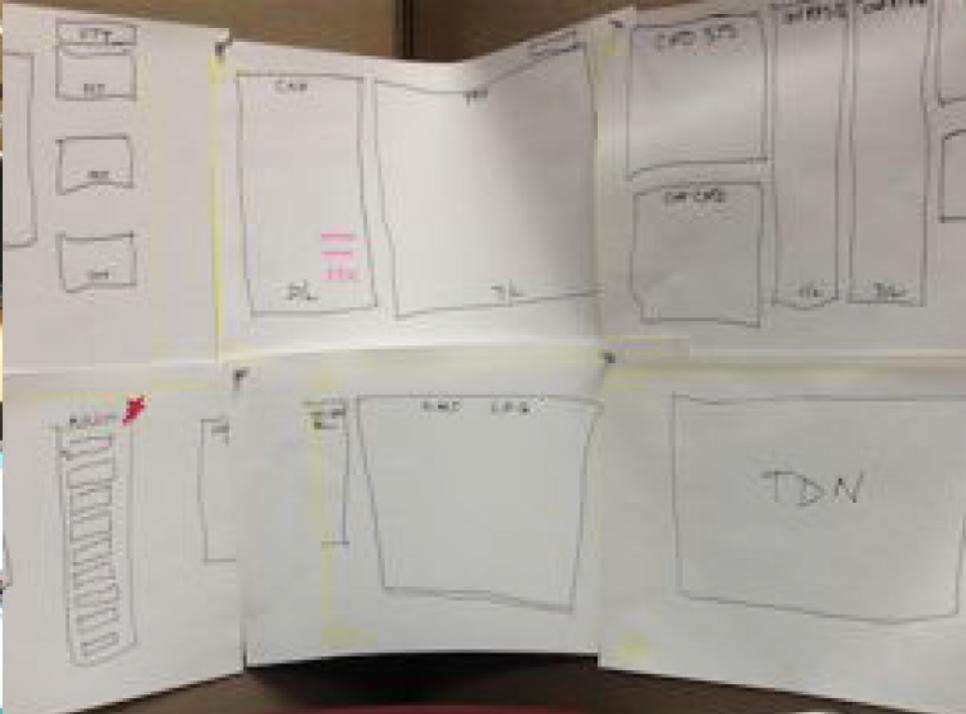
Implications Automation, simulation, design analogy, and situation awareness advancements

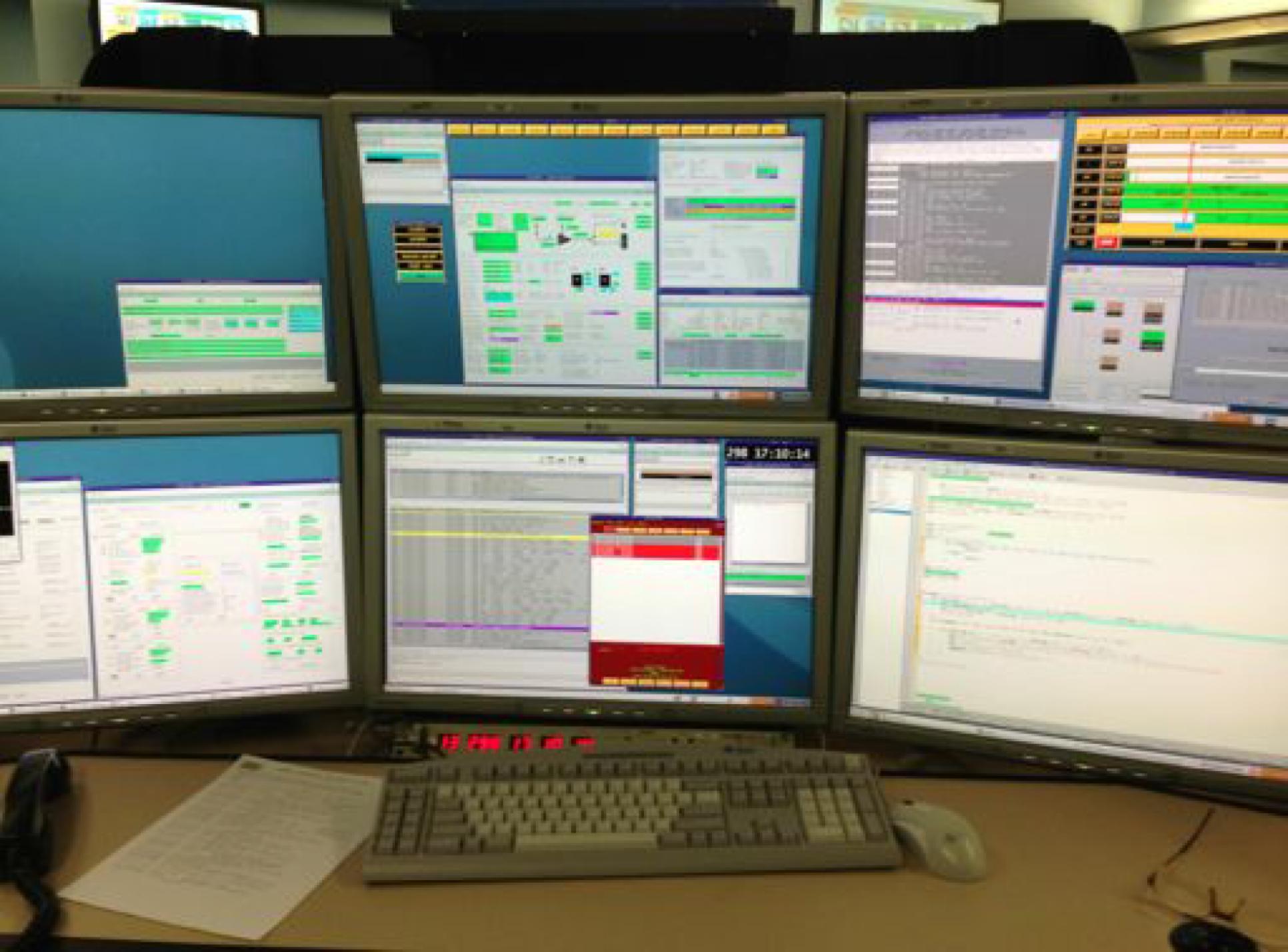
SOE

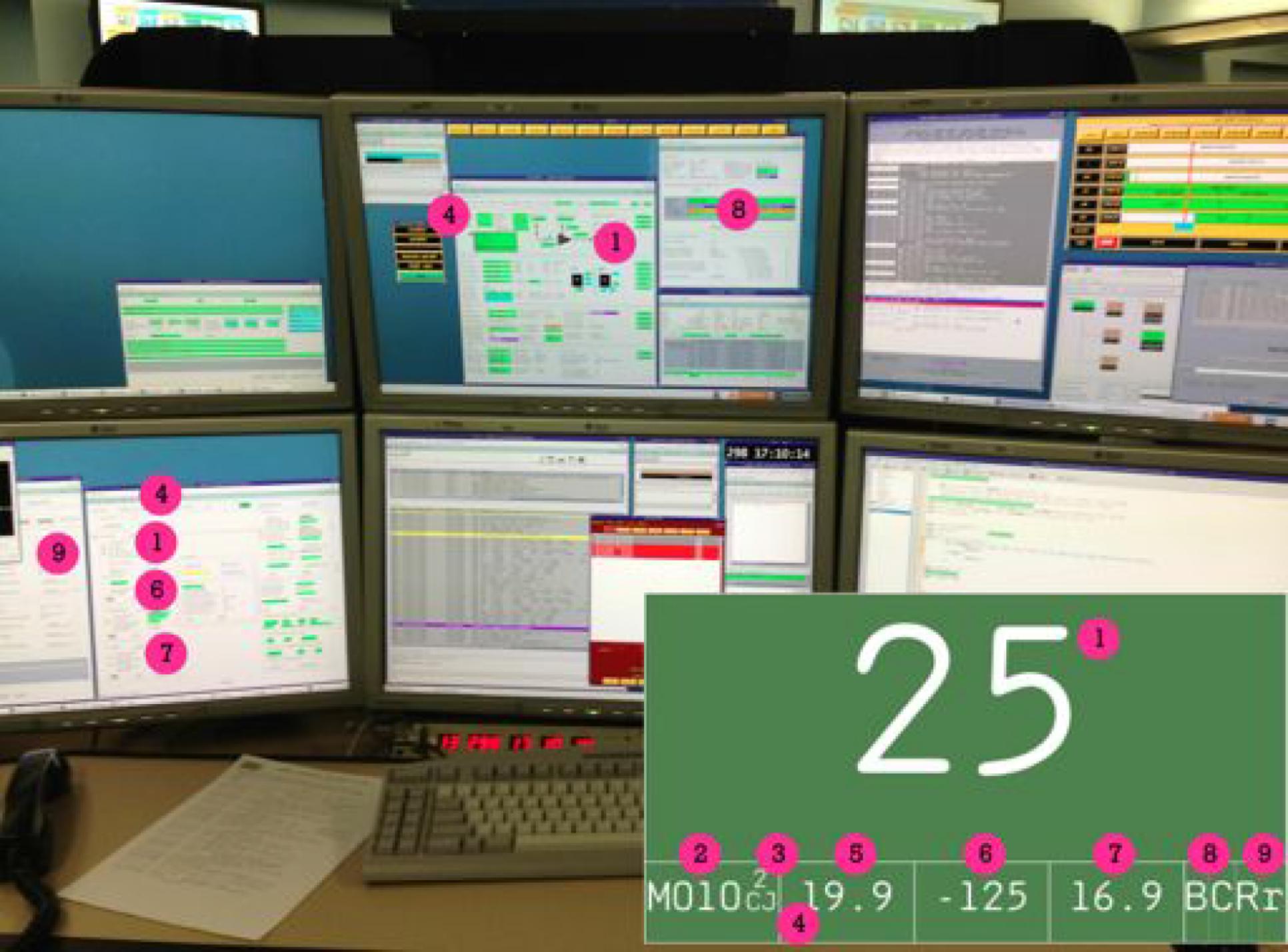
LOG

S
X
B
(MOM)
24









4

1

8

4

9

1

6

7

25

1

2

3

5

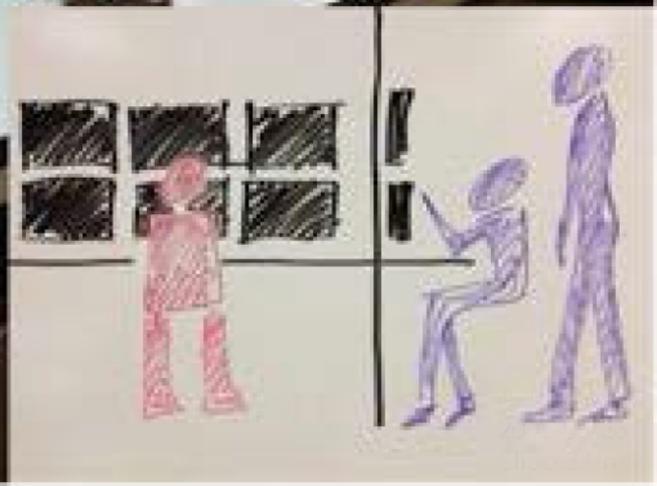
6

7

8

9

MO10CJ	19.9	-125	16.9	BCRr
	4			



UP	VGR2
DWN	43
SYM	
CBRT	
BOT 01:39:34	

UP	VGR1
DWN	14
SYM	
CBRT	
BOT 00:49:34	

UP	MOM
DWN	24
SYM	
CBRT	
BOT 03:09:34	

UP	CLU1
DWN	45
SYM	
CBRT	
BOT 02:34:34	

149 07 05 26

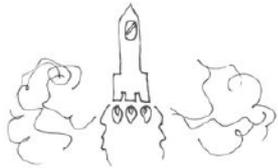


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Telemetry actuals

Measured data values attached to hardware telemetry



Telemetry actuals

Measured data values attached to hardware telemetry

System expecteds

What the system expects to see, e.g. due to prediction and/or command



Telemetry actuals

Measured data values attached to hardware telemetry

System expecteds

What the system expects to see, e.g. due to prediction and/or command

Operator predicteds

What the operator expects to see given Level 3 situation awareness (projection of future states)

Actual	Expected	Predicted
--------	----------	-----------

X
X

X
X

Compare to historical data and present results

Support comprehension rather than perception alone (Endsley)

X

X

“Is the antenna doing as I commanded?”

X

X

Predict what the operator will expect to see, and present results of that computation

X

X

Condition data to remove noise

X

X

Interpolate and/or retransmit missing data

X

X

Flag / transform live stream to meet operator data needs

X

X

Post-process to determine edge cases and flag errors

If you have this problem

Complex

Describing the real system is impossible or impractical

Subsetting

We are only interested in a subset of the real system

Quick iteration

We are designing something and need to iterate quickly

Evaluation

We have specific evaluation requirements

Use a simulator

Complex

Describing the real system is impossible or impractical

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Pitfalls in designing simulations

Pitfall 1

Data-driven simulation
lacks emotion, cost, and
risk



Pitfall 1

Data-driven simulation
lacks emotion, cost, and
risk

**Create experiences,
not simulations**

Research the user

Find out what motivates the user towards
risk-aversion

E.g., Psychosocial and sociotechnical factors

Experience prototype

Little environmental things give the
experience realism

E.g., Provide documentation, desk, environment, and
distractions similar to work

Pitfall 2
 Real data is difficult to obtain;
 Realistic data is difficult to create



Pitfall 2

Real data is
difficult to
obtain;
Realistic data is
difficult to create

**Simulate the data for
data-driven
simulation**

Start slow

Simulate the data stream and incrementally
increase the fidelity of data

E.g., Postage stamp initial prototype used simulated
data stream

Test the concept, not the design

Identify the concept under test, and tailor
the design to the data

E.g., Concept is summary display for increased SA;
design is the physical layout of the display

Use people where you lack data

Wizard-of-Oz techniques that apply
experts to the problem

E.g., Expert-as-simulator in DSN ops



Pitfall 3
Real-time
simulations are
slow and boring



Pitfall 3
Real-time
simulations are
slow and boring

**Don't try to make it
fun (it's not)**

Use expert subjects

And make sure they are invested in the
design under test

E.g., Expectant dads, not random students;
Link control operators, not designers

Test bits and pieces

Rapidly test small bite-sized chunks of the
design

E.g., Testing for "glanceability" a stack of screenshots

- 1 Provide access to time-based data such as history for operators to correlate current behavior with past behavior, or predicted behavior to current behavior
- 2 Make prominent relevant changes in system state, such as for when the operator looks away or tends to secondary tasks
- 3 Curate transition and animation for irrelevant changes to minimize distracting animation yet make salient important information
- 4 Provide timely data with minimal telemetry delay as determined by operator's data needs
- 5 Minimize latency in data transmission and in interface transitions
- 6 Determine and expose relationships between interrelated components and variables within the system
- 7 Calculate and expose differences between actuals, expecteds, and predicteds
- 8 Simulate first with clean, efficient, curated data
- 9 Grow operator attention capacity efficiently
- 10 Fall off from high-intensity periods gracefully

“This is so cool.”

“I take back everything I was thinking about you guys. The display looks good.”

Fin

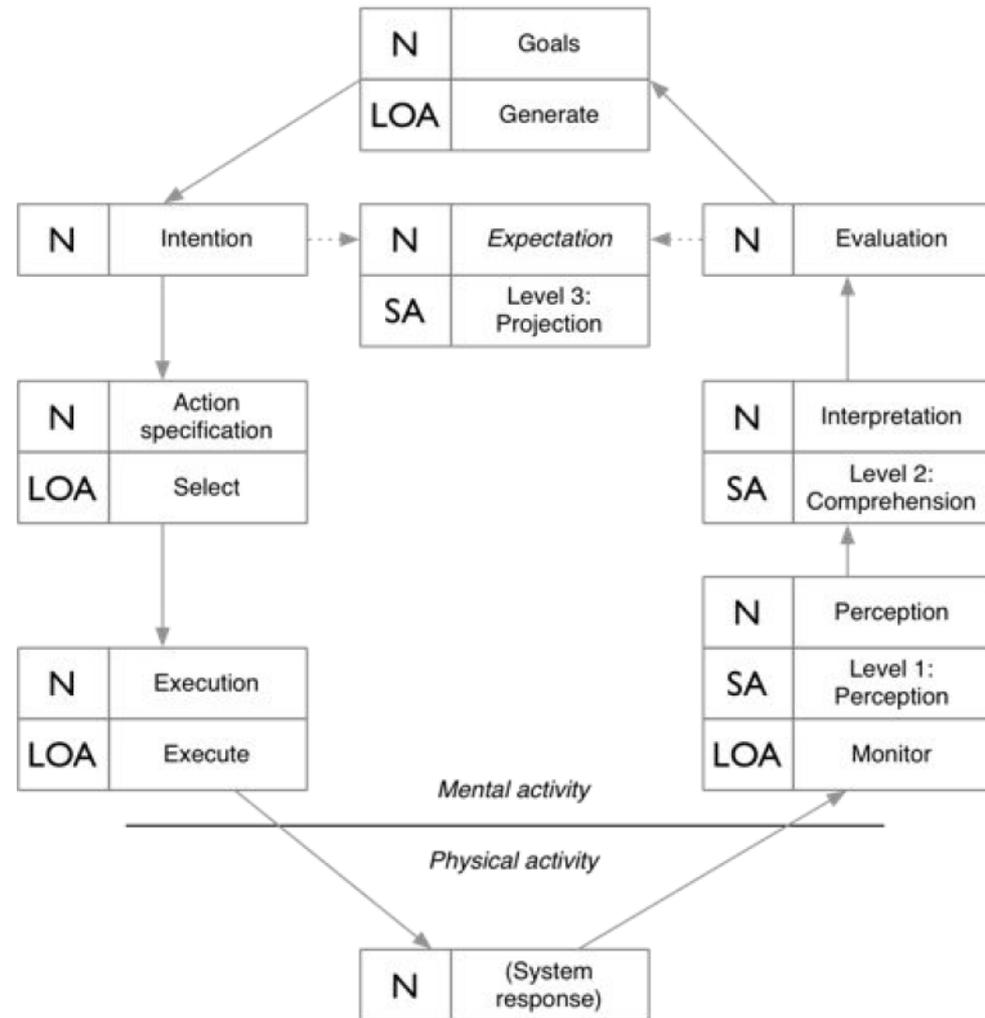
Console

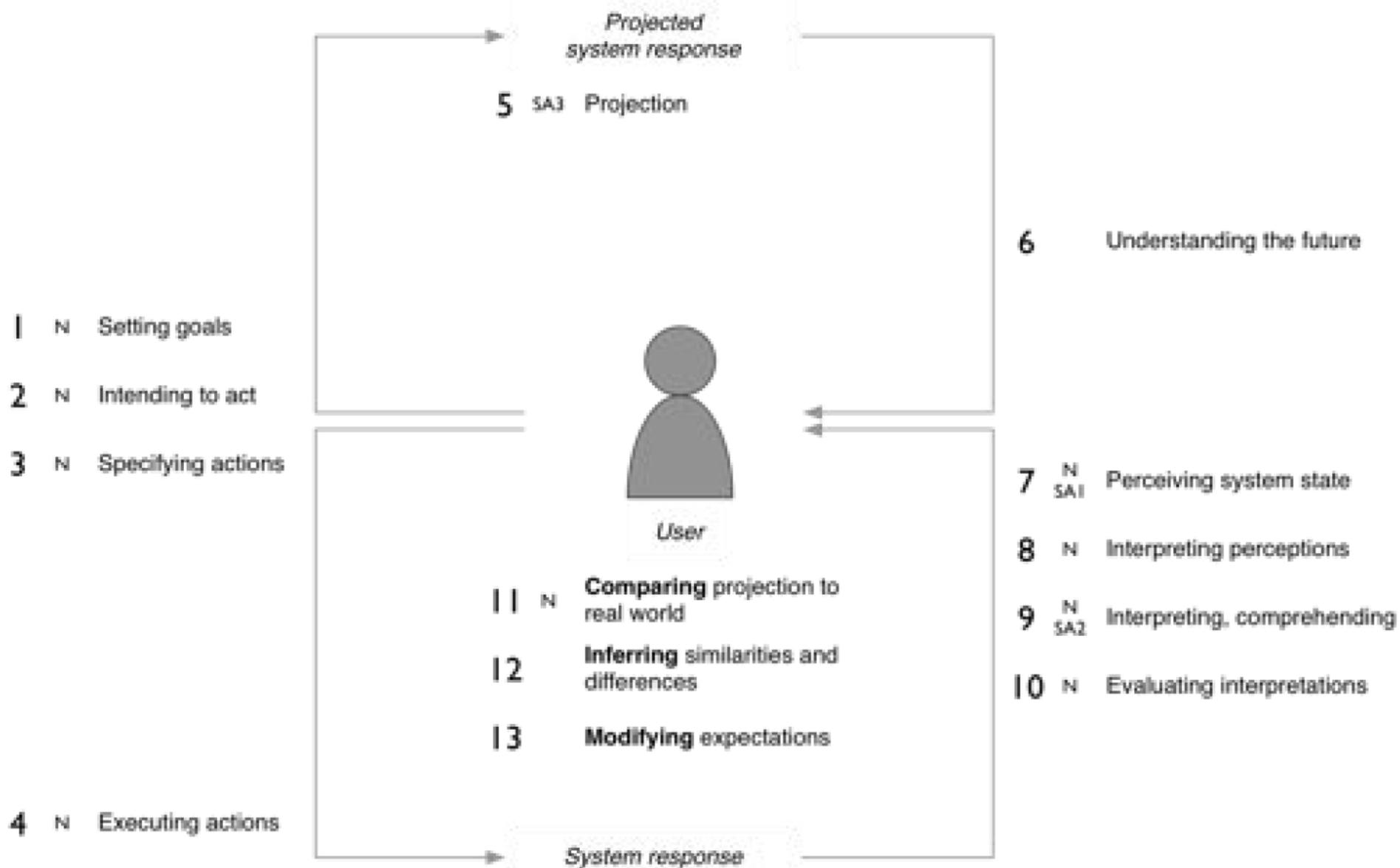
63

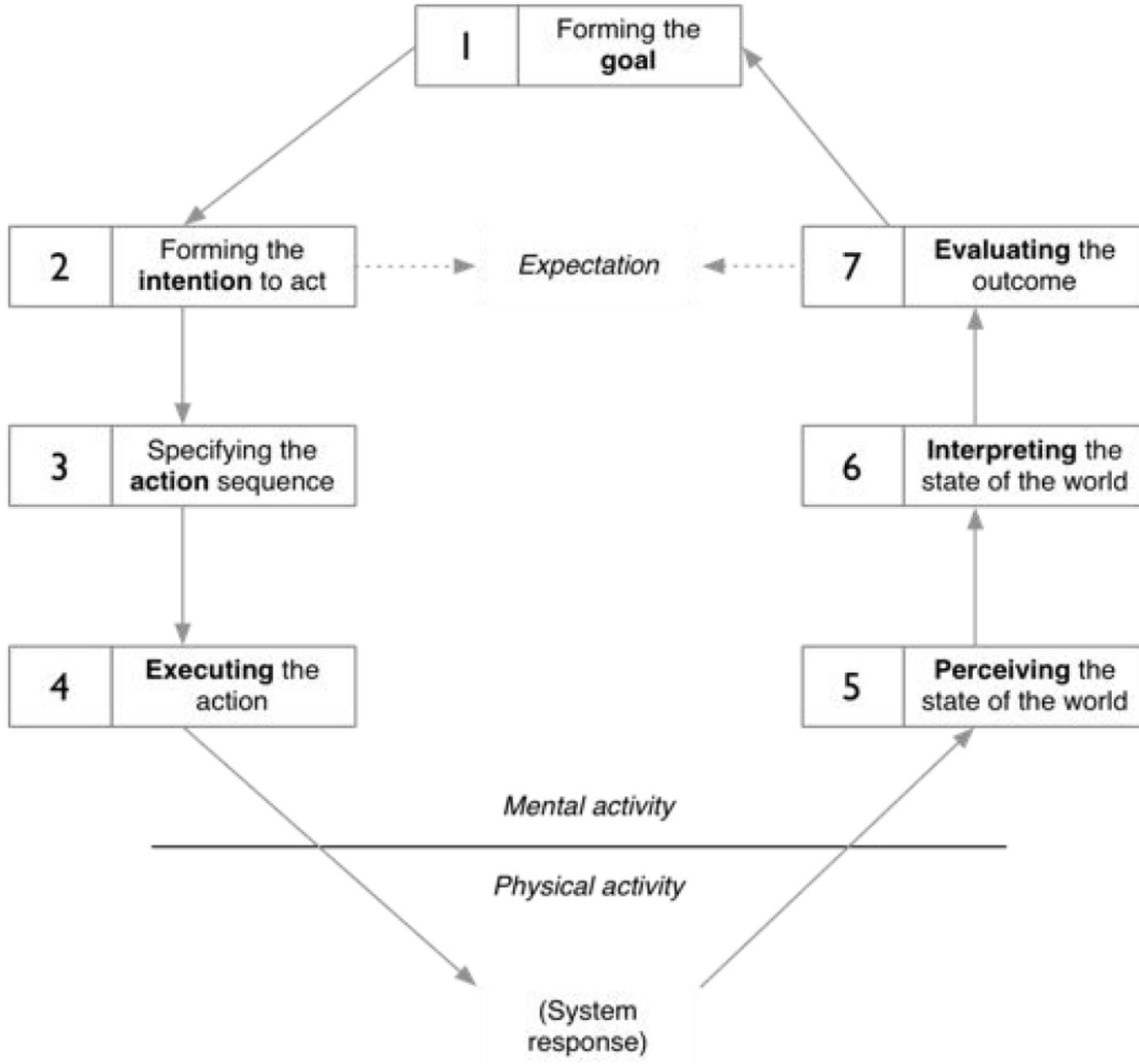
GBRALI	19.9	-125	16.9	BC RI
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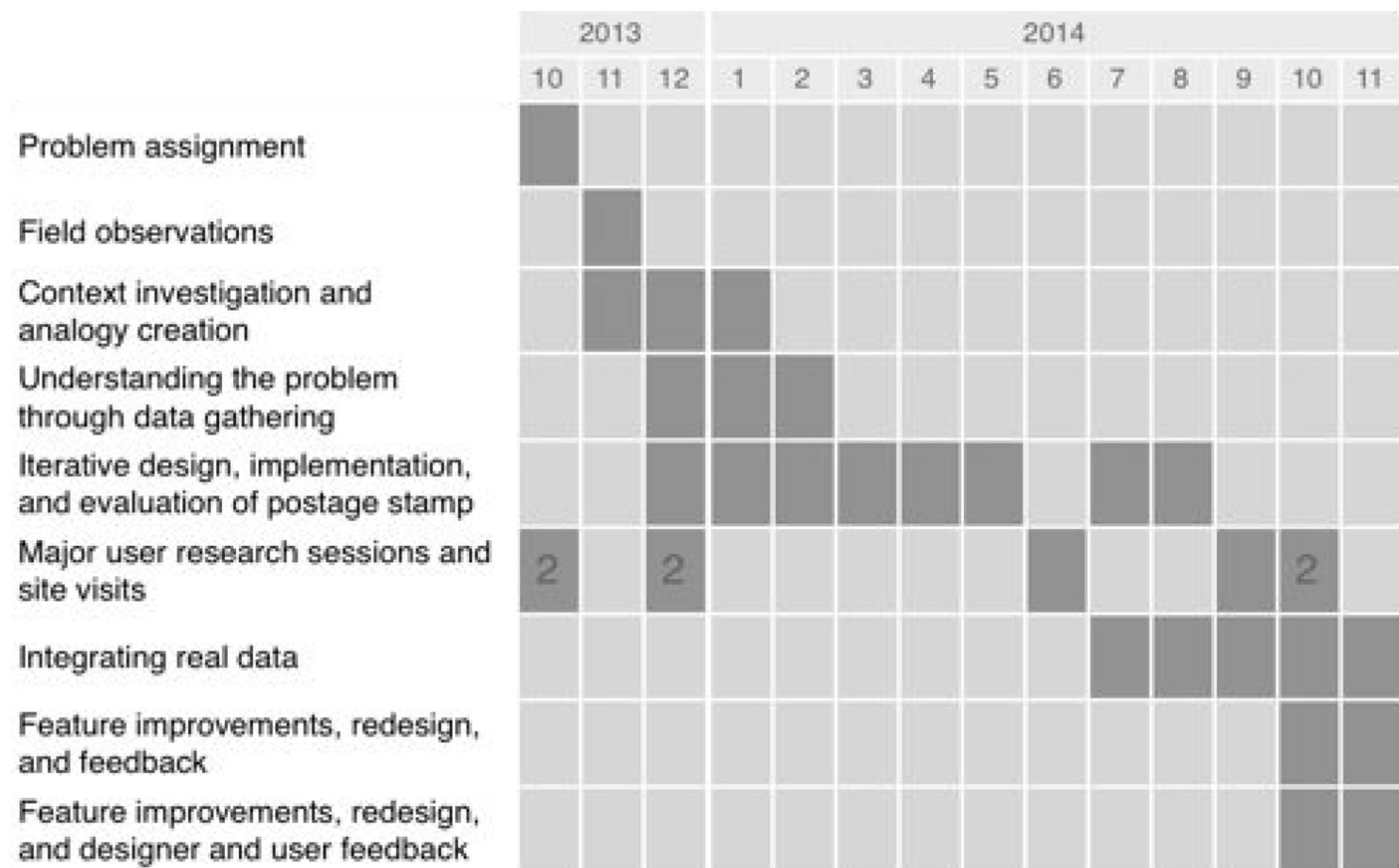
Situation Awareness

- 1 Perception of elements in current situation
- 2 Comprehension of the perceived data
- 3 Projection of future states



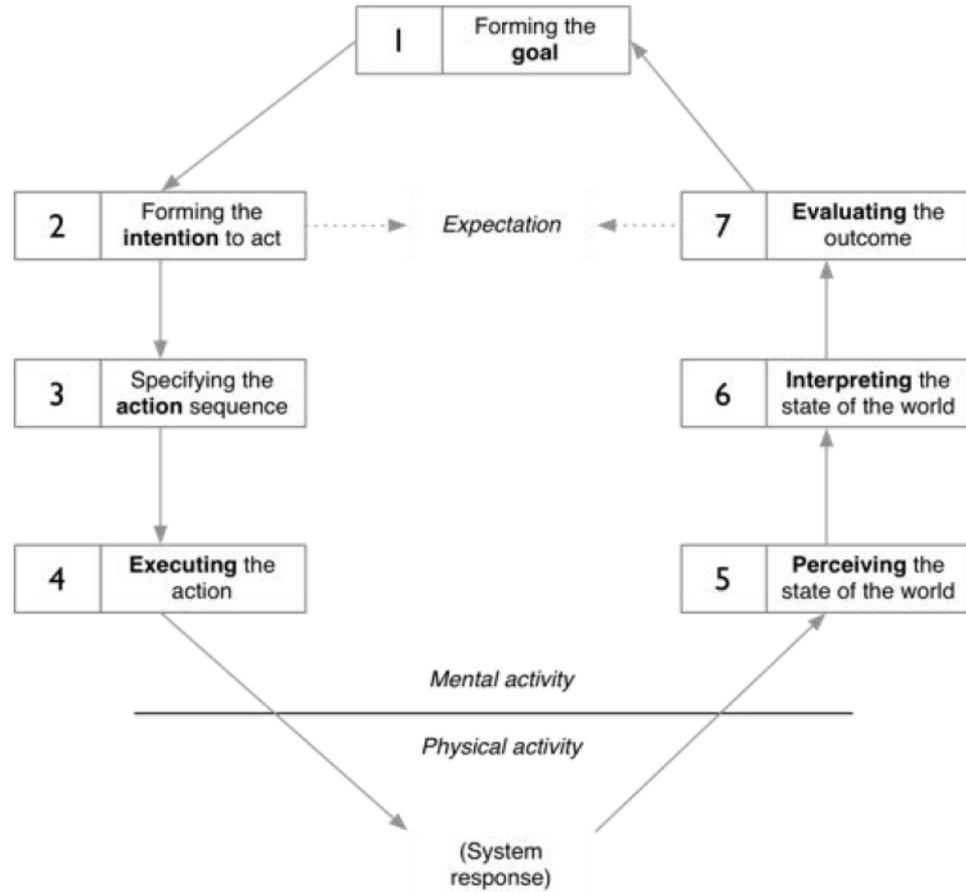


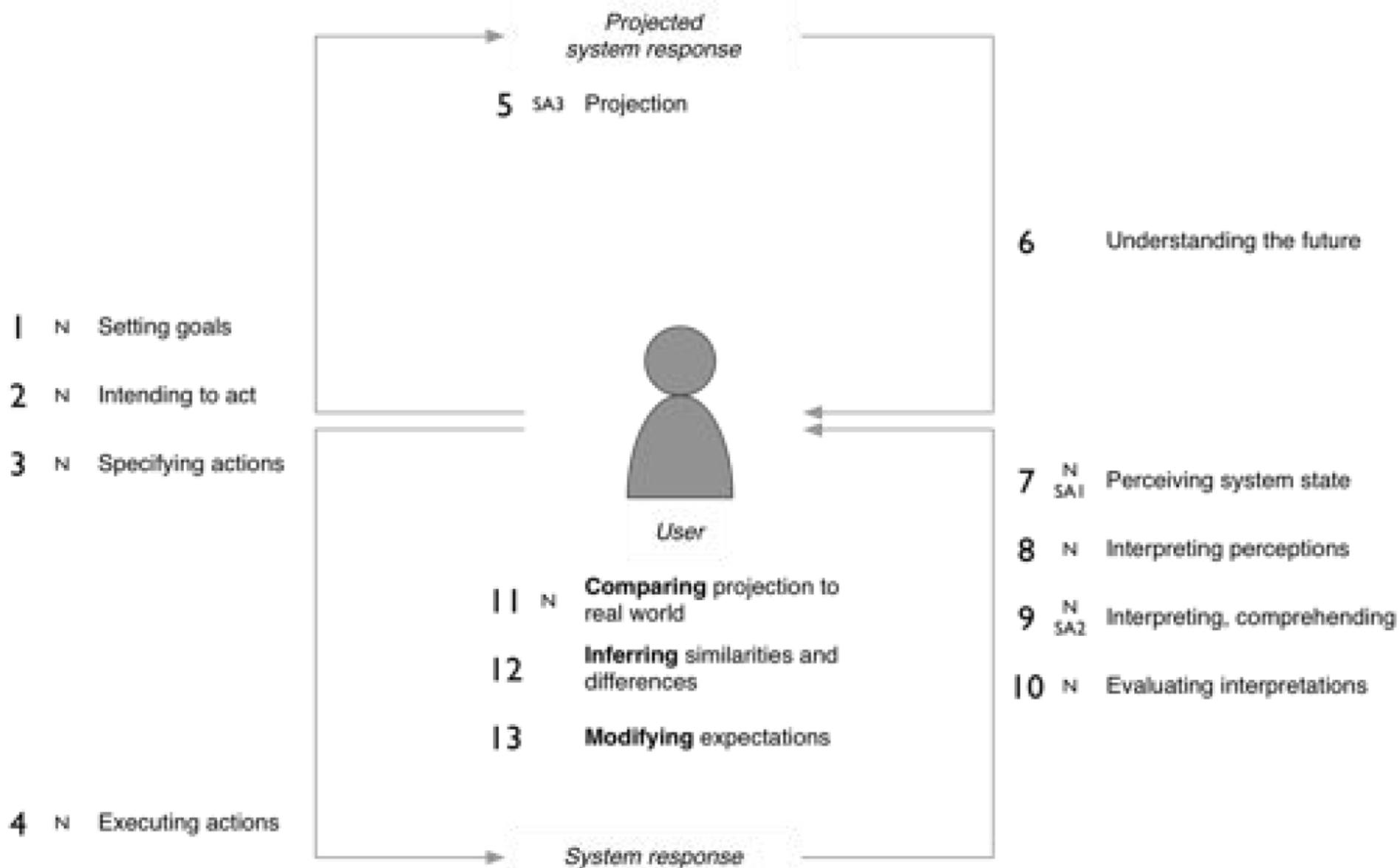




Situation Awareness

- 1 Perception of elements in current situation
- 2 Comprehension of the perceived data
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2.0 Operate and troubleshoot

2.1 Ensure attended supports are executed according to briefing and/or documentation provided

- Do I have all necessary documentation or briefing information?
- Are there any changes since the previous support?
- What are the expected and measured parameters?
- How do I accommodate any deviations?

2.1.1 Ensure activities outside of the nominal operating parameters are properly executed

2.1.2 Ensure continued proper working order of equipment

2.2.1 Identify cause of alarm

- What is the most likely cause?

Causes

- Predicted vs expected vs actual
- Equipment anomaly
- Environmental factors

2.2 Respond to anomalous conditions (alarms)

- What is causing the alarm?
- Can I resolve the alarm?
- Do I need to send out maintenance?
- What is the impact on data return to the project?

2.2.2 Identify impact on data return

- What is the data integrity?

Discuss with project (?)

2.2.3 Resolve problem

- What is the best way to resolve the problem?

Coordinate activities with maintenance

2.3 Provide proactive control

- What is the status of other facilities?
- What is the status of the other tracks at my facility?
- Can I prevent an alarm from occurring?
- What preventative actions are needed?

2.3.1 Assess status of adjacent facilities

2.3.2 Assess status of tracks at local facility

2.3.3 Unix admin as applied to equipment file structure