

Space Network Time Distribution and Synchronization Protocol Development for Mars Proximity Link

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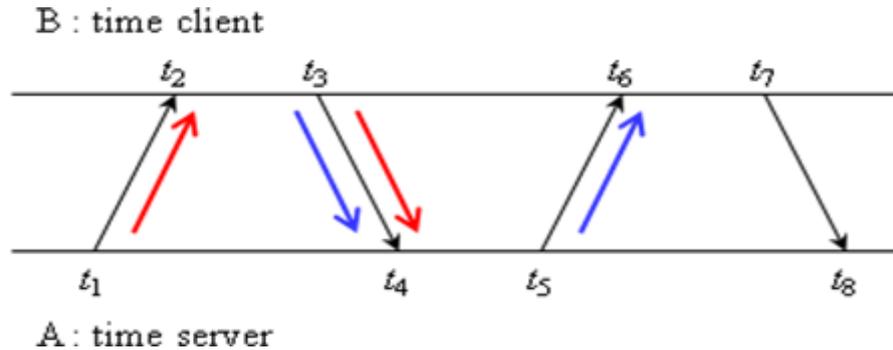
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Outline

- Introduction
 - Background: Time Synchronization
 - Overview: Space Time Synchronization Architecture
- Proximity-1 Interleaved Time Synchronization (PITS) Protocol
 - PITS Protocol Algorithm : Basic Mode and Interleaved Mode
 - Time Capturing comparison between PITS and the current method
- Simulation
 - Setup
 - Result
- Conclusion

Time Synchronization between two nodes:



Ranging

For A,

$$\text{offset} = \frac{1}{2} \{ [(T_2 - T_1)] + [T_3 - T_4] \}$$

$$\text{delay} = [T_4 - T_1] - [T_3 - T_2]$$

For B,

$$\text{offset} = \frac{1}{2} \{ [(T_4 - T_3)] + [T_5 - T_6] \}$$

$$\text{delay} = [T_6 - T_3] - [T_5 - T_4]$$

Assumptions:

1. Symmetric (statistically equivalent) path
2. No errors in the link
3. Not measuring synchronization accuracy but evaluate the protocol interactions

- Basic Symmetric Mode

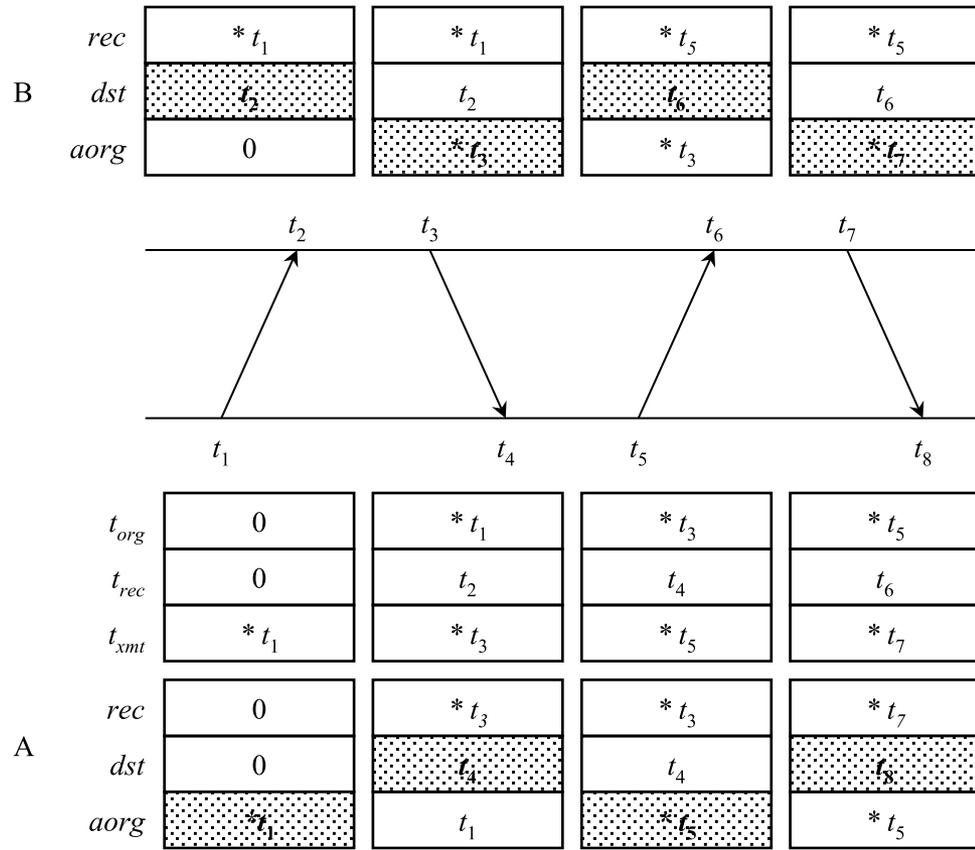
Packet Fields

t_{org} : origin-timestamp
 t_{rec} : receive-timestamp
 t_{xmt} : transmit-timestamp

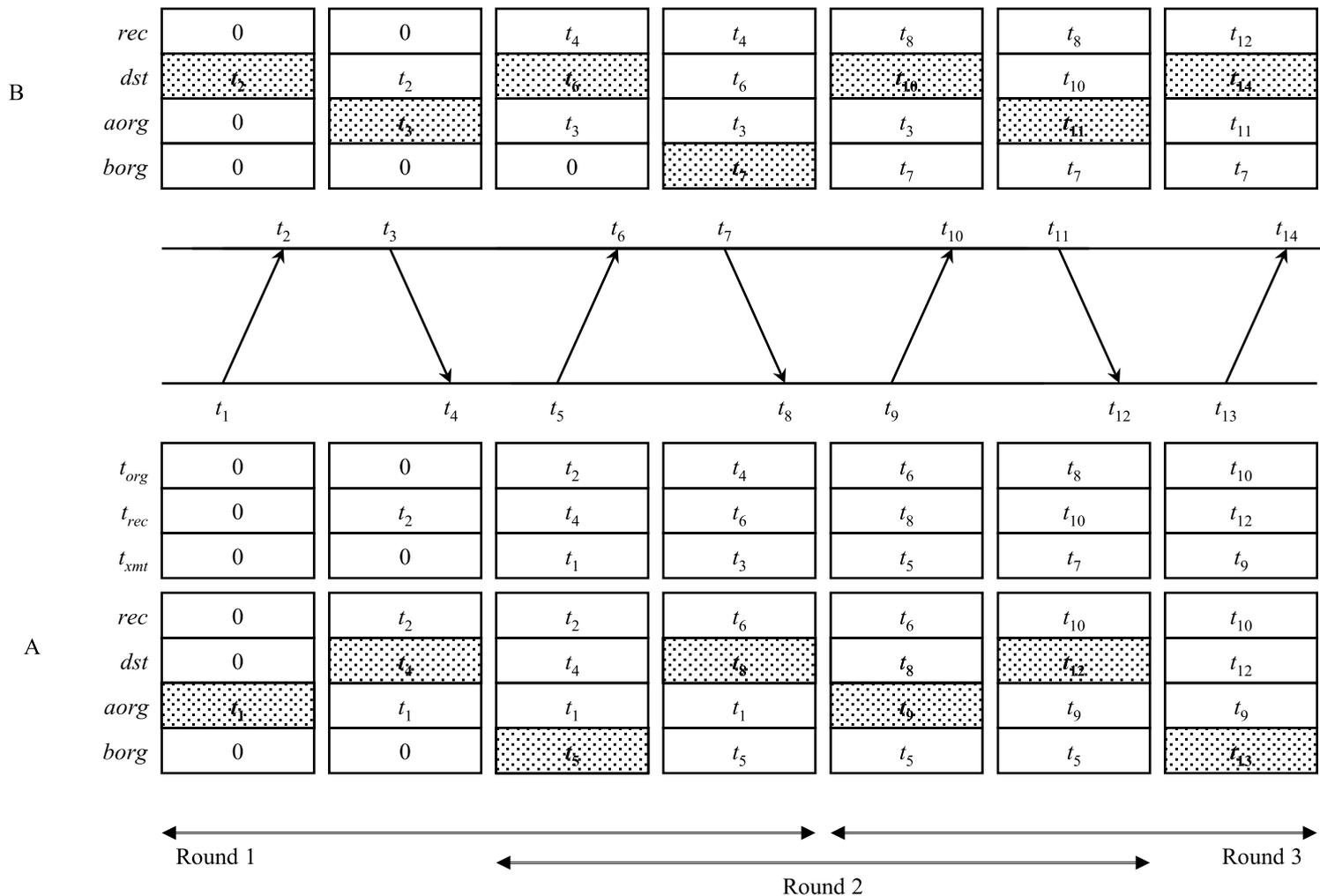
State Variables

rec : receive-timestamp
 dst : destination-timestamp
 $aorg$: origin-timestamp
 $borg$: origin-timestamp used for Interleaved Mode

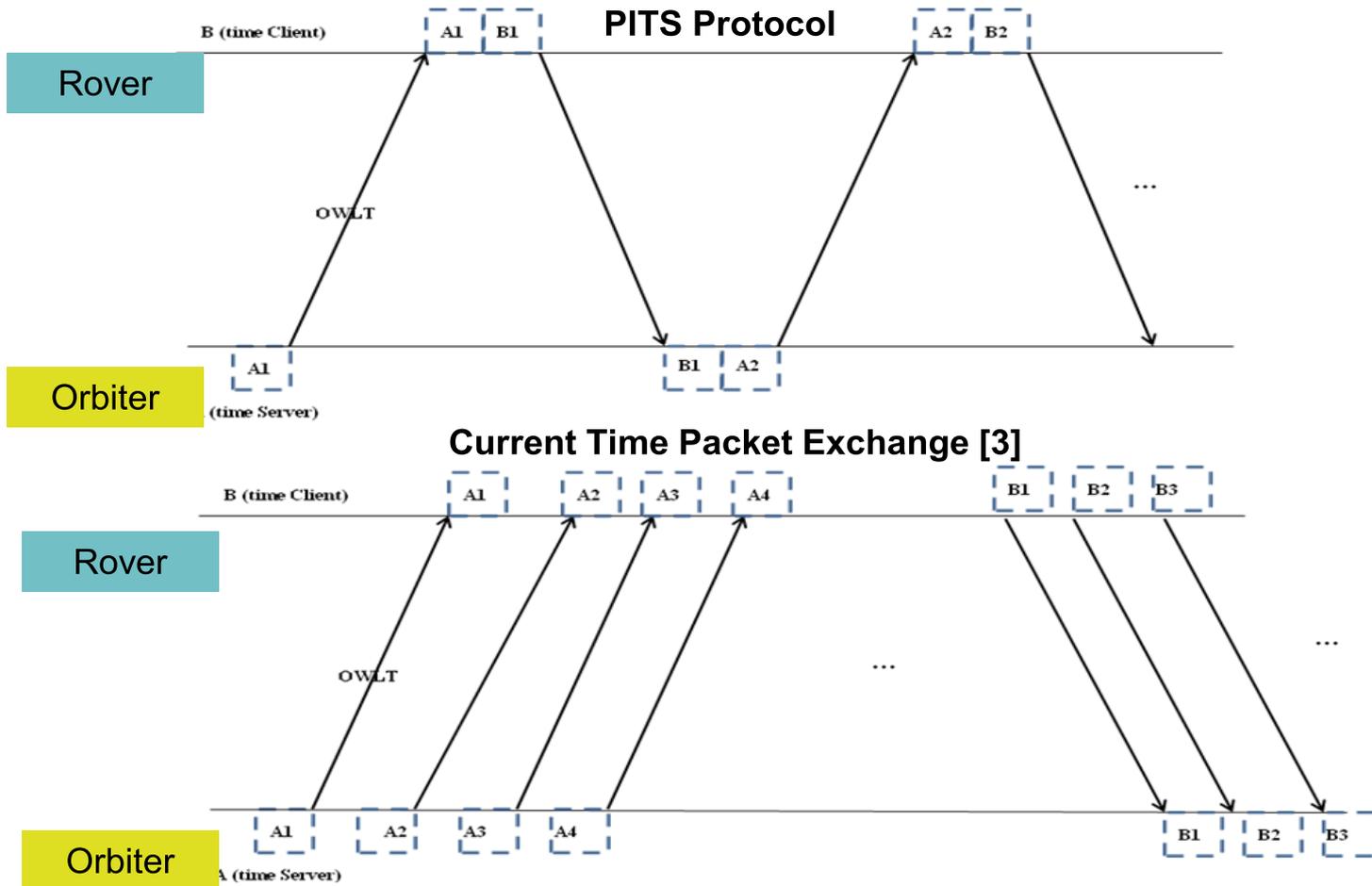
Offset between A and B
 $= \frac{1}{2} [(T_2 - T_1) + (T_3 - T_4)]$
 RTT Delay between A and B
 $= (T_4 - T_1) - (T_3 - T_2)$



PITS Protocol Interleaved Mode[2]

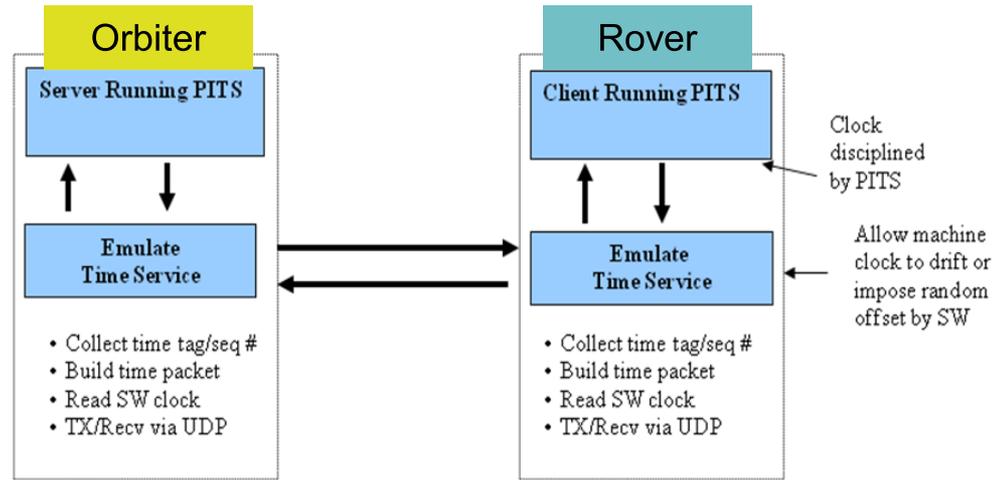


Protocol interaction Comparison between PITS and existing approach

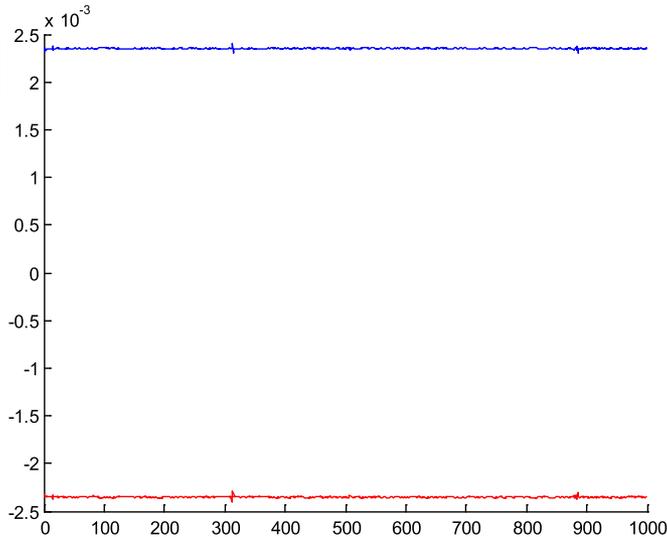


Simulation Setup

- Implemented PITS in C
- Tested over UDP
- Emulated the time differences
- Collected 1000 Time Samples to compute offset and delay

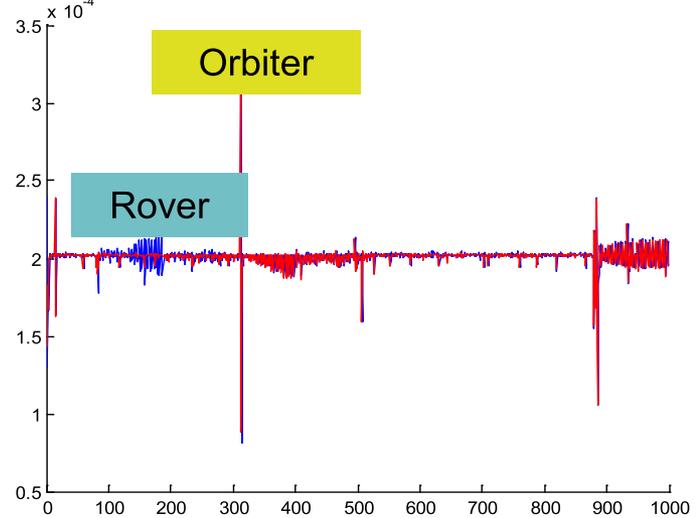


Rover



Calculated Offset between A and B

Orbiter



Calculated RTT between A and B

Conclusions

- Proposed the NTP based PITS protocol to provide common time in Mars proximity domain.
- Provide the onboard time distribution capability at the spacecraft which would be a key component for *In Situ Time Distribution Service*.
- Verified the correctness of the PITS algorithm, validated the design, and provided the preliminary simulation results.
- Will be an effective method to distribute time to other spacecraft through proximity links, as the number of space assets increases.
- Further prototype development and hardware integration and testing will be necessary to capture accuracy.
- Applicable to multi-spacecraft formation flying missions to provide accurate and periodic time updates as well as Space-Based Positioning, Navigation, and Timing (PNT) system[4] to enable integrated communications.

Acknowledgements

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References

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- 2) NTP Interleaved On-Wire Protocol,
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- 3) CCSDS Proximity-1 Space Link Protocol, CCSDS 211.0-B-4:
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- 4) The Positioning, Navigation and Timing (PNT) Overview,
https://www.spacecomm.nasa.gov/spacecomm/programs/system_planning/PNT/default.cfm

Q&A