

Compact Microwave Mercury Ion Clock for Space Applications

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Abstract— We have recently completed a breadboard ion-clock physics package based on Hg ions shuttled between a quadrupole and a 16-pole rf trap. With this architecture we have demonstrated short-term stability $\sim 1\text{-}2 \times 10^{-13}$ at 1 second, averaging to 10^{-15} at 1 day. This development shows that H-maser quality stabilities can be produced in a small clock package, comparable in size to an ultra-stable quartz oscillator required for holding $1\text{-}2 \times 10^{-13}$ at 1 second. This performance was obtained in a sealed vacuum configuration where only a getter pump was used to maintain vacuum. The vacuum tube containing the traps has now been under sealed vacuum conditions for nearly three years with no measurable degradation of ion trapping lifetimes or clock short-term performance. We have fabricated the vacuum tube, ion trap and UV windows from materials that will allow a $\sim 400^\circ\text{C}$ bake-out to prepare for tube seal-off. This approach to the vacuum follows the methods used in flight vacuum tube electronics, such as flight TWTA's where tube operation lifetime and shelf life of up to 15 years is achieved.

I. INTRODUCTION

A small space-qualified atomic frequency standard with stability as good as 10^{-15} over several hours averaging interval would enable one-way deep space navigations, where Doppler data is accumulated in a down-link only fashion. Currently, deep space navigation is implemented by measuring the Doppler frequency shift of a 2-way link from a ground station to a spacecraft (s/c) and the coherent return link. Typically, these links are maintained for 7-8 hours per s/c track, requiring full use of a 34-meter antenna in the Deep Space Network (DSN) for the time the s/c is sufficiently above the horizon.

When more than one s/c orbit around the same planet, they can be tracked simultaneously with one antenna. Multiple s/c tracking by a single antenna can reduce antenna usage and DSN costs.

II. PHYSICS PACKAGE STATUS

The physics package is shown in figure 1. The mechanical package shown is designed to withstand generic random vibration levels of over 9.2 grms. A modal analysis was made of the structure using more than 3000 nodal mesh points to determine resonance frequencies of various mechanical subassemblies. All frequencies are 200 Hz and higher, adequate for many launch requirements. Various electronics circuit boards can be designed to conform to the spaces

available within this structure. The functional layout is described in Ref. 1.

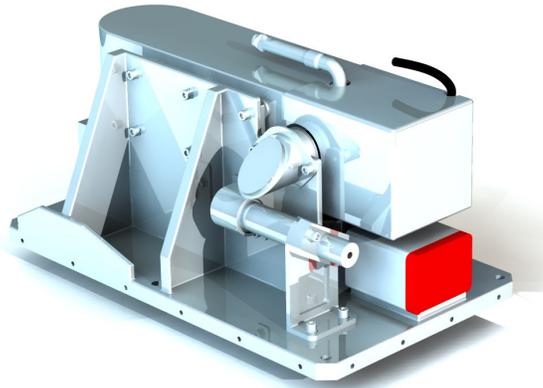


Figure 1. The ~ 3 liter physics package with baseplate, photomultiplier tube and vacuum tube mounting through the two layer magnetic shield. An outer magnetic shield is not shown.

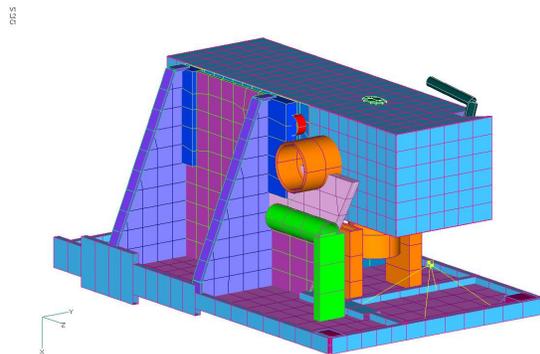


Figure 2. Approximately 3000 finite element mesh points are used to determine resonant frequencies of mechanical assembly. Structure is designed to withstand random vibration levels to over 10 g_{rms} .

III. LAMP LIFETIME STRATEGIES

The ion clock relies on optical pumping to prepare and to detect the $^{199}\text{Hg}^+$ microwave 40.5 GHz transition. The light source is a fused silica bulb ~ 12 mm diameter by ~ 30 mm in length filled to ~ 1 Torr Argon buffer gas with a quantity of metallic ^{202}Hg . The lamp is excited at ~ 200 MHz inside a resonant LC tank circuit, with the bulb placed inside a 2 turn coil to inductively excite a discharge inside. Typically 10W is dissipated within the exciter circuit and bulb for bright mode operation. Under these and similar operating conditions lamps have functioned well for 5 years or more.

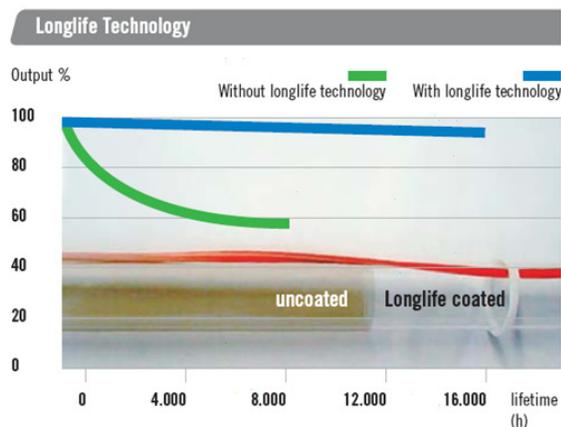
For in-vacuum space operation we have housed the lamp bulb in a package similar to the GPS Rubidium clock [2]. That

is, the bulb and exciter coil are placed inside an ovenized container, with the bulb potted in an Indium thermal heat sink base to maintain and control the cold point temperature and consequently vapor pressure of Hg inside the sealed bulb.

Mercury lamps are used in many applications to create UV light for water purification and sterilization. UV transmitting materials become opaque over time when exposed to high fluxes of UV light and possible chemical interactions with Hg vapor inside, as hundreds of watts of power are used to generate either 254 nm or 185 nm light. This degradation is similar to the slow darkening seen in our Hg clock application, though the rate of darkening is accelerated because of the higher power and temperature used in UV light purification/sterilization applications.

Alternate materials have been investigated which may be more resistant to chemical reactions with Hg and also more UV resistant. The most successful of these is Sapphire as described by Hereaus [3] where a sapphire coating the inside of the fused silica bulb acts as a barrier to chemical reactions where HgO is formed near the surface of the SiO₂ bulb. The pictures [3] show a dramatic decrease in darkening of the glass when sapphire is applied. Other materials and a description of the process is given in reference 4.

Sapphire bulb material has been proposed for use in GPS Rubidium. Some test Rubidium bulbs were built [5] and showed behavior similar to conventional glass bulbs.



Graph of operating life of an uncoated amalgam lamp and a Heraeus amalgam lamp (254nm, 300 W) with Longlife coating.

Figure 3. Improvements to the lifetime of fused silica Hg ultraviolet lamps have recently been achieved. See reference [3].

IV. NOVEL LINE ACQUISITION METHODS

The ion clock resonance signal shown in Fig. 2 is derived from the classic Rabi single microwave square-wave pulse [6]. The resonance linewidth is determined by the duration, T, of the pulse. The resulting frequency linewidth is $0.799/T \sim 0.27$ Hz for typical ion-clock measurements, corresponding to a 3 second microwave pulse.

To measure the $^{199}\text{Hg}^+$ clock reference frequency, the output of a tracking synthesizer is typically stepped to either side of the resonance line center, to the points of steepest

frequency slope. The sequence of measurements yields a sequence of numbers, C(1), C(2), C(3),...C(n), each the number of photon pulses accumulated in some time interval, usually 2 seconds or less. Such successive fluorescence measurements are made on opposite sides of line center. The simplest proportional loop adjusts center frequency of modulation according to

$$\Delta f \propto R_{loop} L_w \frac{C(1) + C(3) - 2C(2)}{2\pi \text{SignalSize}} \quad (1)$$

in order to “track” the line center. In this expression, L_w is the linewidth ($.799/T$ for the Rabi interrogation) and SignalSize is the height of the resonance signal above background light level as shown in Figure 2. The sequence of frequency corrections, Δf are summed so that the tracking synthesizer approaches the line center approximately exponentially. The “second difference” $C(1)+C(3)-2C(2)$ is used so that linear drifts in the UV light source output will not cause a frequency offset.

Signal size depends on several variables including the microwave power so that occasionally the sequence of frequency measurements is interrupted to measure the signal size via fluorescence measurements on line center and several linewidths away from line center, typically 1 Hz or more.

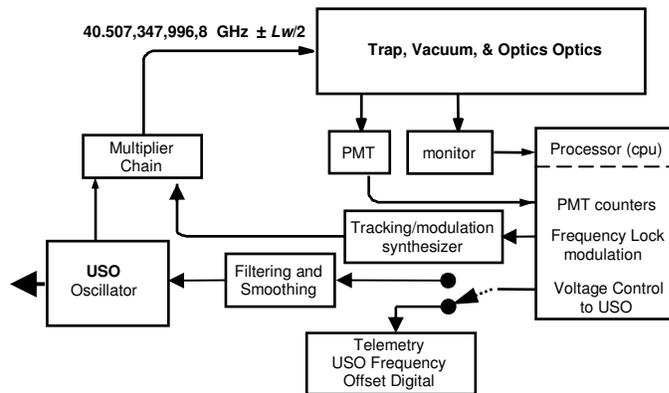


Figure 4. Block Diagram of frequency lock loop.

Another method of determining the line-center is based upon the analytical expression for the Rabi line shape [4],

$$P = \frac{(2b)^2}{(\omega - \omega_0)^2 + (2b)^2} \sin^2 \left(\frac{T}{2} \sqrt{(\omega - \omega_0)^2 + (2b)^2} \right)$$

$$= \frac{\sin^2 \left(\frac{\pi}{2} \sqrt{1 + y^2} \right)}{1 + y^2} \equiv \text{Rabi}(y) \quad (2)$$

where

$$y^2 = \frac{(\omega - \omega_0)^2}{(2b)^2} = (2T(v - v_0))^2 \quad (3)$$

and we have assumed power is optimized,

$$bT = \frac{\pi}{2}. \quad (4)$$

The steepest point for use in frequency discrimination occur at $y \cong \pm 0.761$, while the half-max points occur at $y \cong \pm 0.799$.

In practice, the Rabi resonance lineshape is a very good model for the measured signal as shown in Figure 2. The full measurement yields a background light level, Bck , a signal-size, Amp , and a line-center frequency, ϵ . The total light collected vs frequency is thus described by three parameters as

$$Light = Bck + Amp * Rabi(y - \epsilon) \quad (5)$$

A method for measuring frequency stability of the resonance line would be to make 3 frequency measures as shown in Figure 4, and invert the equation

$$Light = Bck + Amp * Rabi(y - \epsilon) \quad (6)$$

to extract values for Bck , Amp , and ϵ .

This method allows frequency tracking of the line-center, collection of engineering data of both lamp light output and signal size. The signal size measurement can be used to continuously optimize microwave power levels, a useful measurement for long term autonomous clock operation. This line acquisition method is complete in three measurements unlike the proportional method described earlier which only approaches line-center exponentially.

In practice, three measurements, $C(1)$, $C(2)$ and $C(3)$, are made at different frequencies y_1 , y_2 , and y_3 . The following 3 equations are then inverted

$$\begin{aligned} C(1) &= Bck + Amp * Rabi(y_1 - \epsilon) \\ C(2) &= Bck + Amp * Rabi(y_2 - \epsilon) \\ C(3) &= Bck + Amp * Rabi(y_3 - \epsilon) \end{aligned} \quad (7)$$

Three values for y are shown in Figure 4, $y \cong \pm 0.761$ and $y = 0$.

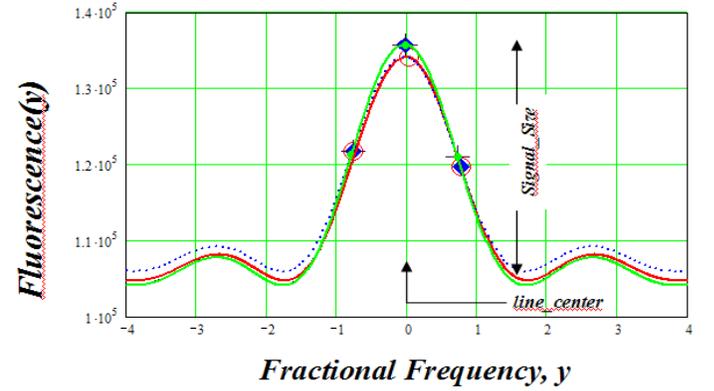


Figure 5. The theoretical Rabi line-shape with a constant background light level $Bck = 105,000$ counts and $Signal\ Size = Amp = 30,000$. A signal-to-noise level of ~ 30 has been simulated, and 3 successive solutions are shown.

To monitor the line-center frequency, the 3 most recent measurements are used as described above to determine line-center frequency, background light level and signal size. Every measurement is followed by an inversion of the three equations and yields a new set of parameter estimates. Figure 5 shows simulated frequency tracking where

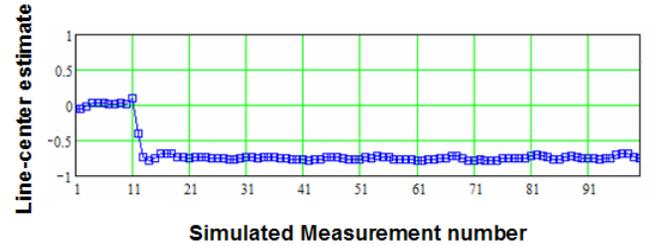


Figure 6. The response of the tracking algorithm is shown for an instantaneous change in line center (at step 10) by $\Delta y = 0.75$.

center frequency is changed from $y = 0$ to $y = -0.75$ at step 10 of the 100 step sequence. This simulation is based on an average signal-to-noise ratio of ~ 32 . The response time is very fast compared to the proportional methods. The step size of this instantaneous line-center change can be too large for the tracking to follow, in part because far from line-center, there may not be a unique inverse solution to the 3 equations at the heart of the method. This non-uniqueness can also cause problems as the Signal-to-Noise ratio diminishes.

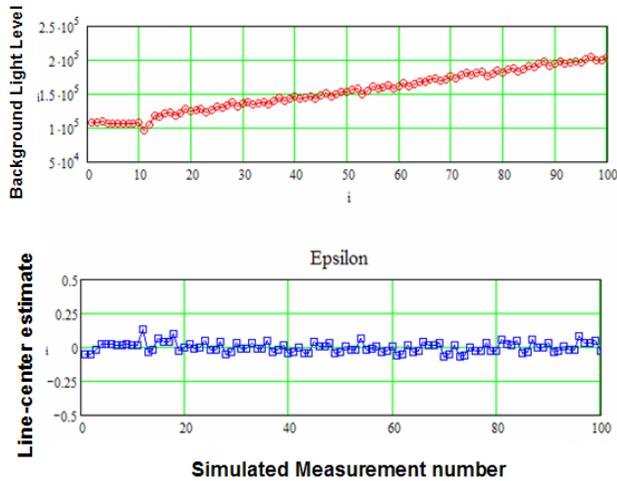


Figure 7. The non-linear curve-fit tracking algorithm does not show a frequency shift when the light-source drifts in its output level. In the above simulated line tracking, a large linear drift was imposed on the light level starting at measurement 10.

Because this method separates the influences of background light, signal size and linecenter, a linear drift in the light level from the lamp does not seem to force a frequency pulling of the estimated line center. Figure 6 shows a simulated large light level drift imposed over the simulated frequency tracking noise data, with no evidence of frequency pulling.

We have tested this algorithm in laboratory measurements where $^{199}\text{Hg}^+$ ion frequency was tracked using an H-maser local oscillator. The magnetic shields for the ion clock were removed so that ambient magnetic fields would change the clock frequency to test the algorithm's ability to follow changes. The Allan deviation of the resulting sequence of line-center frequency estimates is shown in Figure 7.

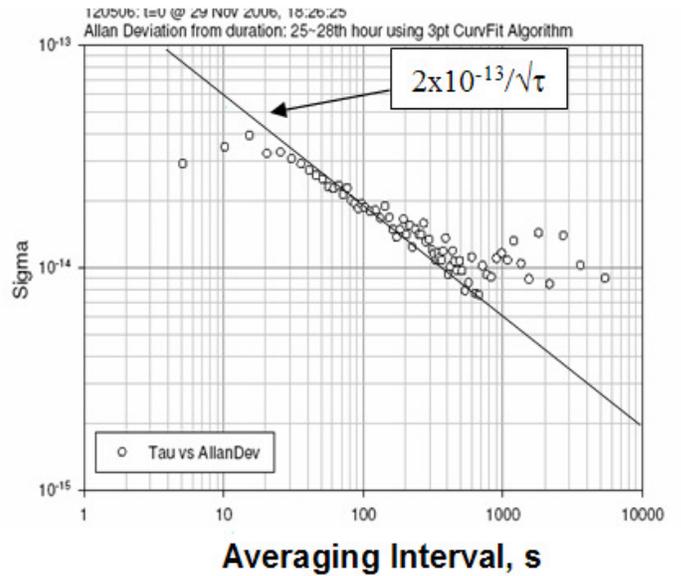


Figure 8. In-lab frequency tracking of the $^{199}\text{Hg}^+$ clock transition using the non-linear curve-fit tracking algorithm as outlined in this paper. During this measurement the ion clock magnetic shields were removed resulting in frequency instabilities beyond 1000 seconds averaging interval.

ACKNOWLEDGMENT

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