



2013 IEEE AP-S Symposium



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Propagation Model for FINDER Radar

Presented by

Vaughn Cable
California Institute of technology
Jet Propulsion Laboratory
vcable@jpl.nasa.gov



Clarksville, Tenn., May 6, 2003-- A home near Clarksville Tennessee is destroyed when hit by a tornado. Photo by Mark Wolfe/FEMA News Photo



Introduction



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FINDER – Finding Individuals in Disaster and Emergency Response

Motivation - Finding persons still alive in piles of rubble, following an earthquake, a severe storm, or other disaster is a difficult problem (photo on beginning slide)

Team - This work was carried out at the Jet Propulsion Laboratory, California Institute of Technology -

- Manager (PI) – James Lux
- Hardware design – Salman Haque, Richard Ohanian
- Software design - Hiram Ghaemi, Mike McKee
- Antenna design - Luis Amaro
- EM simulation – Vaughn Cable

Sponsor – Funding provided by the Department of Homeland Security, Science and Technology Directorate



Topics



Radar Approach
Lab Experiments Prototype
Field Testing Rubble Models
FDTD Results



Radar Configuration



CW Radar -

- Selected CW radar - simplest (e.g., police radar)
- ~3 GHz gives sufficient transparency of rubble

Processing -

- Consistent (periodic) motion of heart & lungs causes detectable phase shifts
- Can “see” multiple heartbeats

Antennas -

- Single transmit & multiple receive antennas allow 1st order spatial discrimination
- Both H & V polarizations are useful

Portability -

- Single package (suitcase)
- 12 hour battery pack





The Radar

*At the Virginia Task Force 1
Training Site in Lorton, VA*



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Rubble Models





Prototype Field Tests



- Outside on real rubble
- Typical range of detection was ~25' in rubble & 100' in free space
- Rebar does not matter – just scatters more
- 4"x4" metal mesh does not matter ($\lambda = 5-10\text{cm}$)
- Spurious target processing is yet to be implemented
 - Targets behind or next to the radar, with the propagation reflecting off the rubble

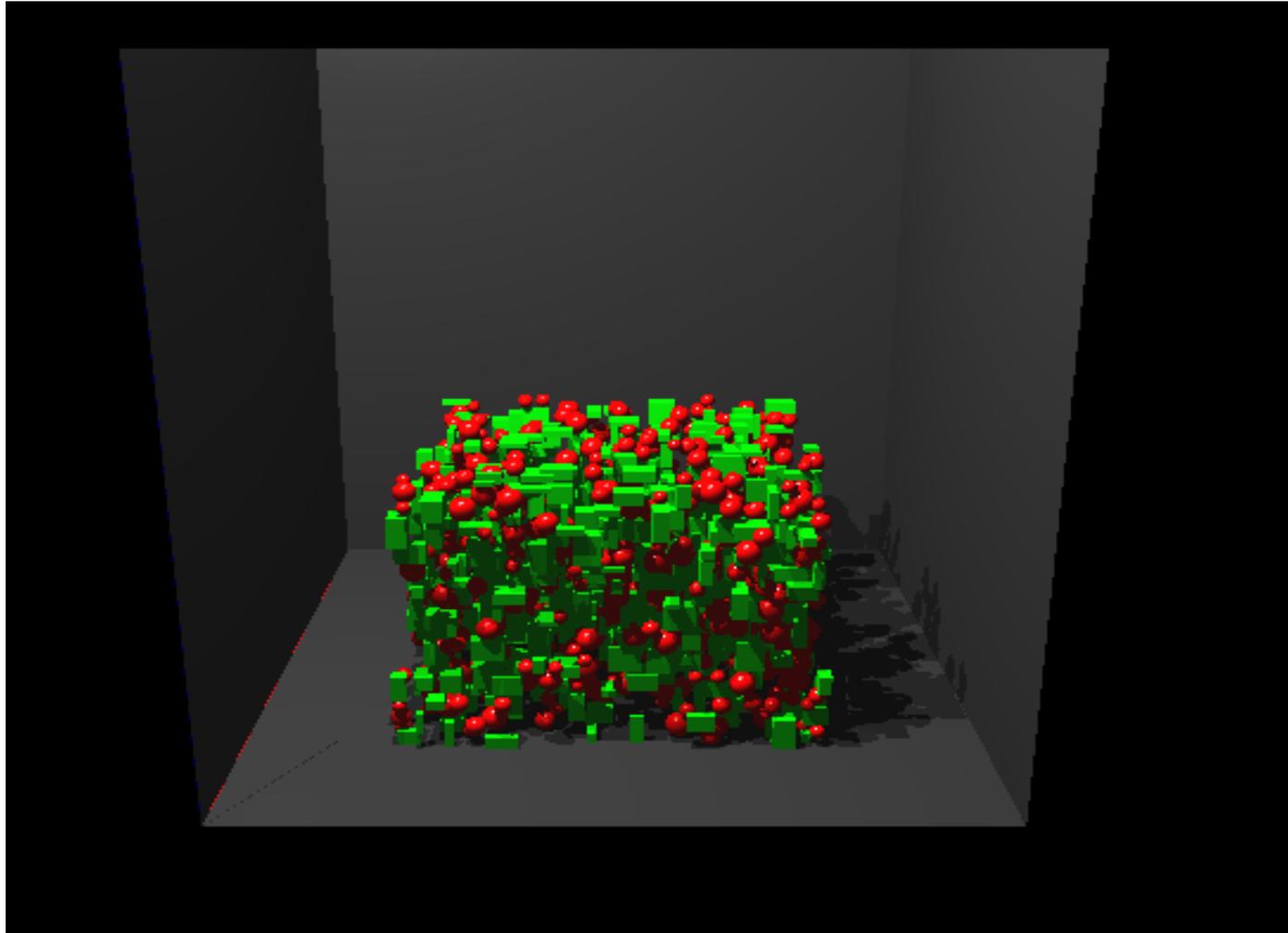


Rubble Numerical Model



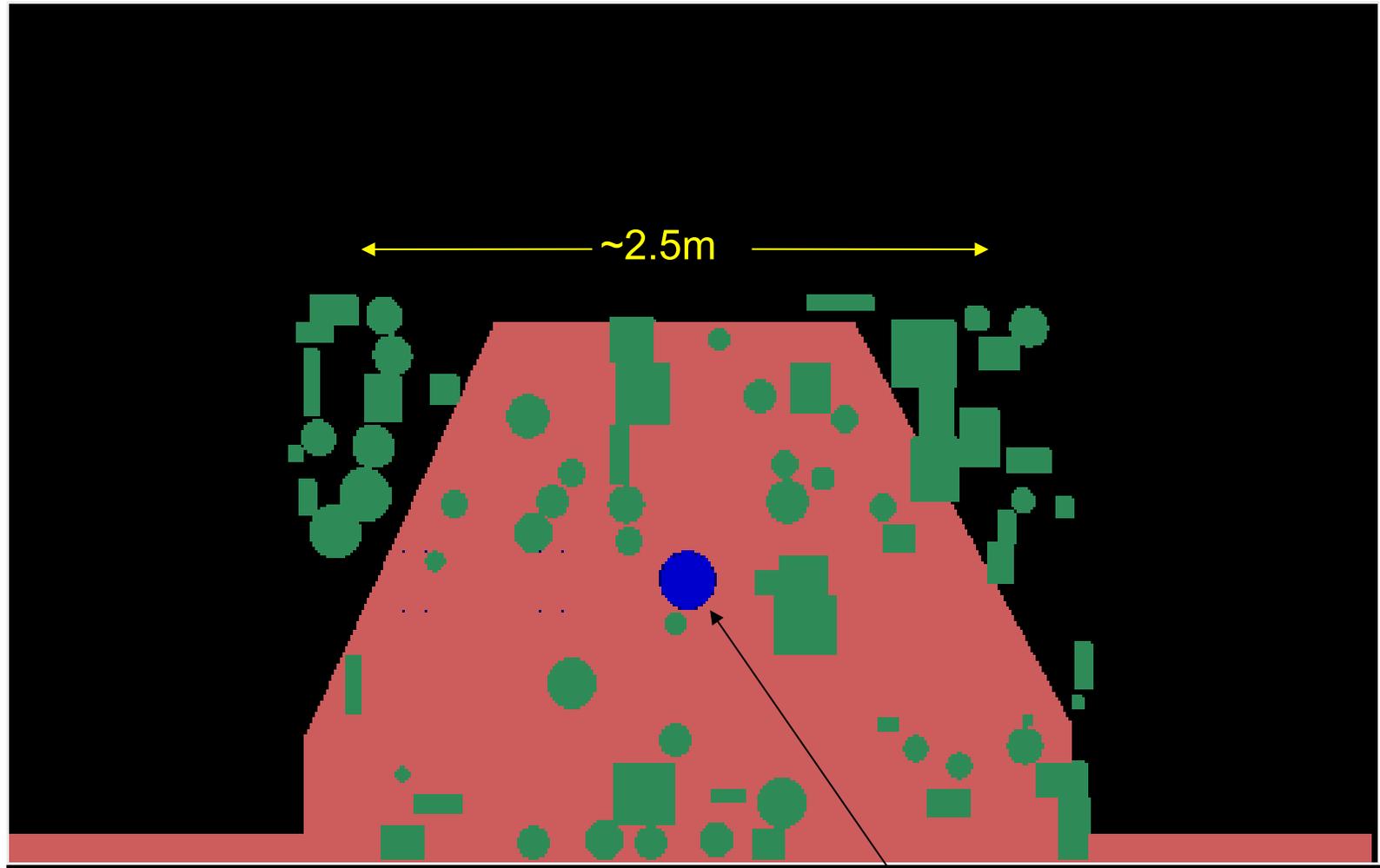
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3D FDTD 500x500x300 cell Model Lossy Dielectrics



20 cm sphere (saltwater)



3D FDTD Excitation

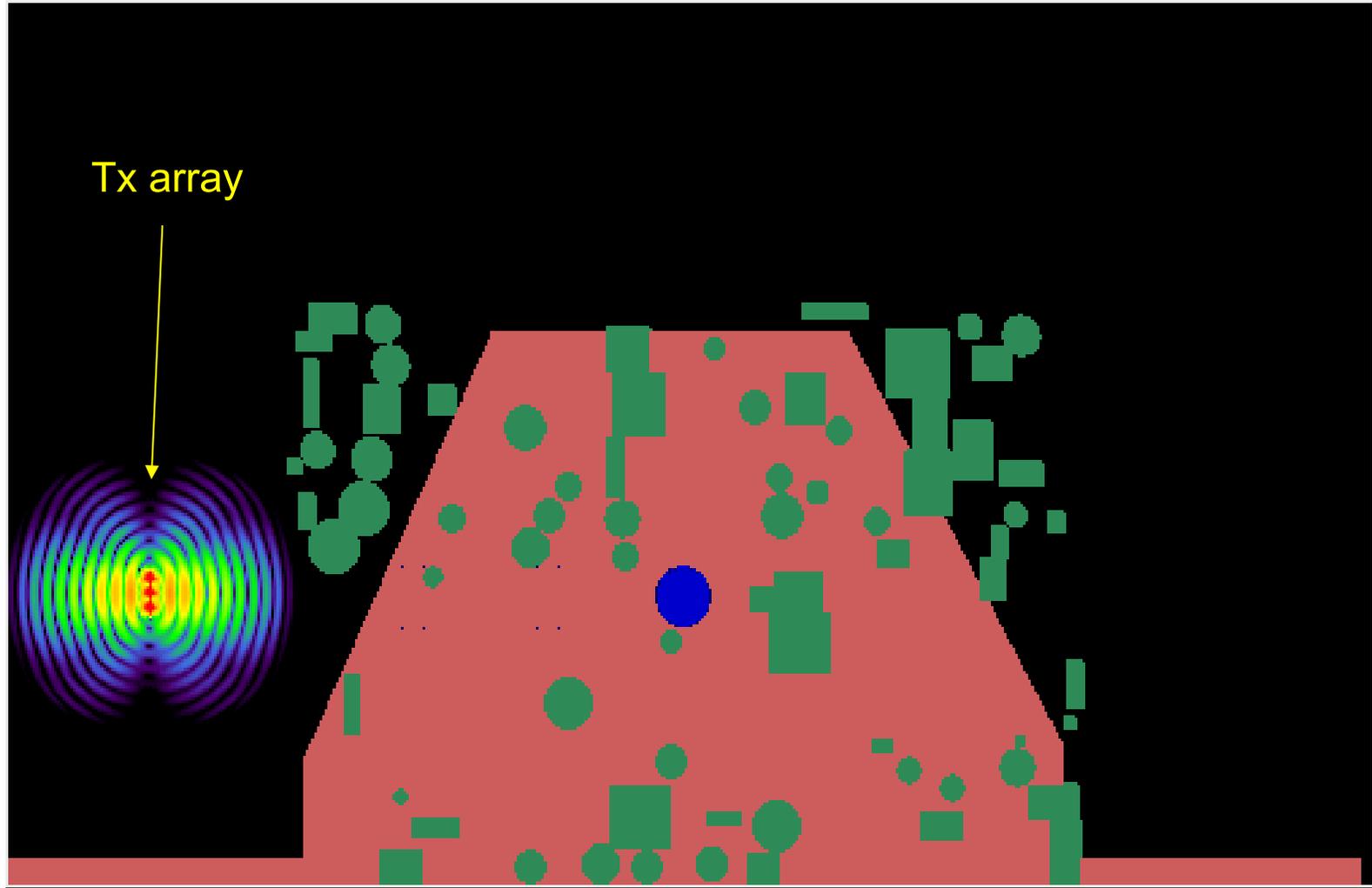
3x3 broadside V-pol array at 3 GHz

Timestep 100 with 19.3 psec/step



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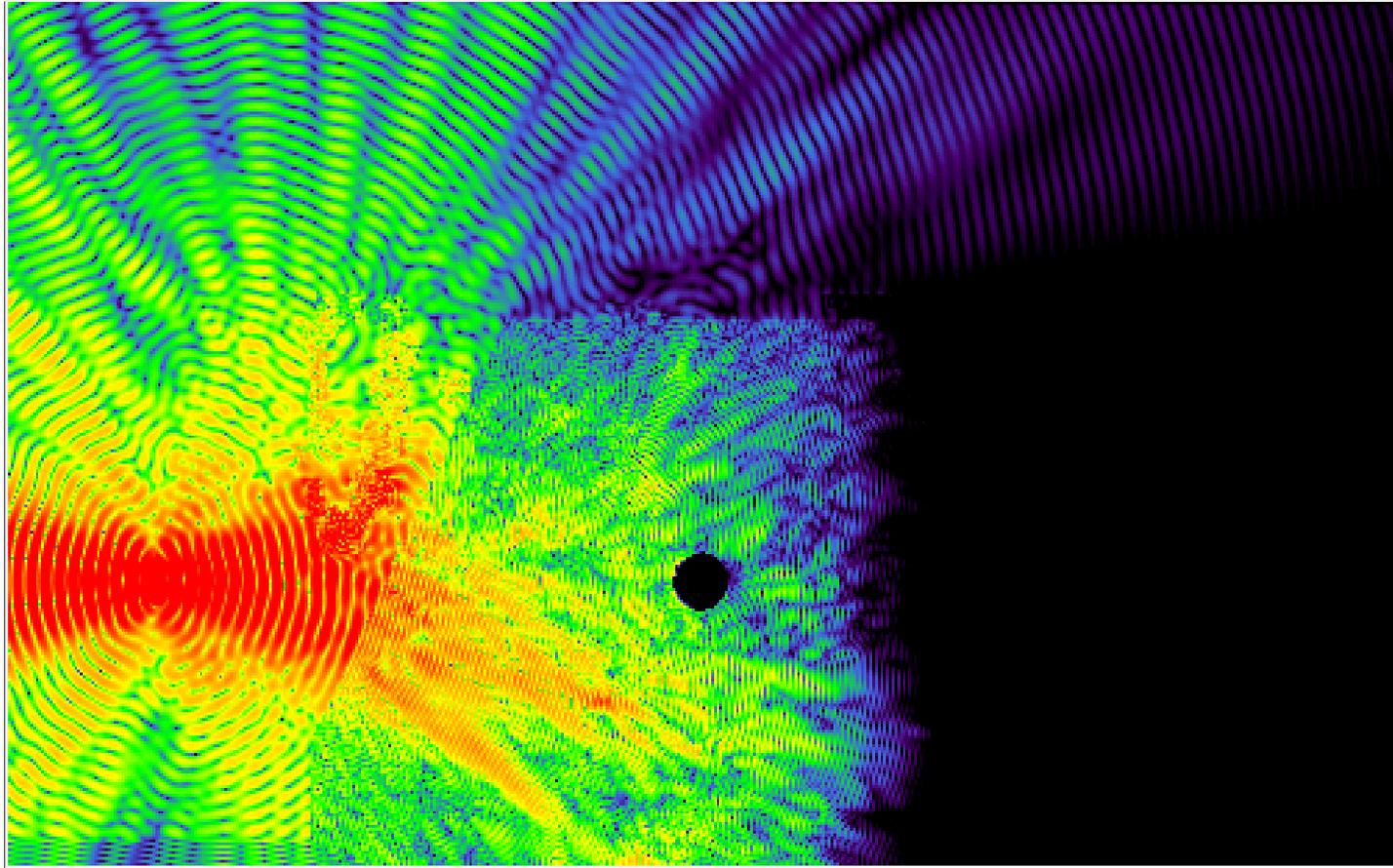


FDTD Run Timestep 1200 Dielectrics hidden



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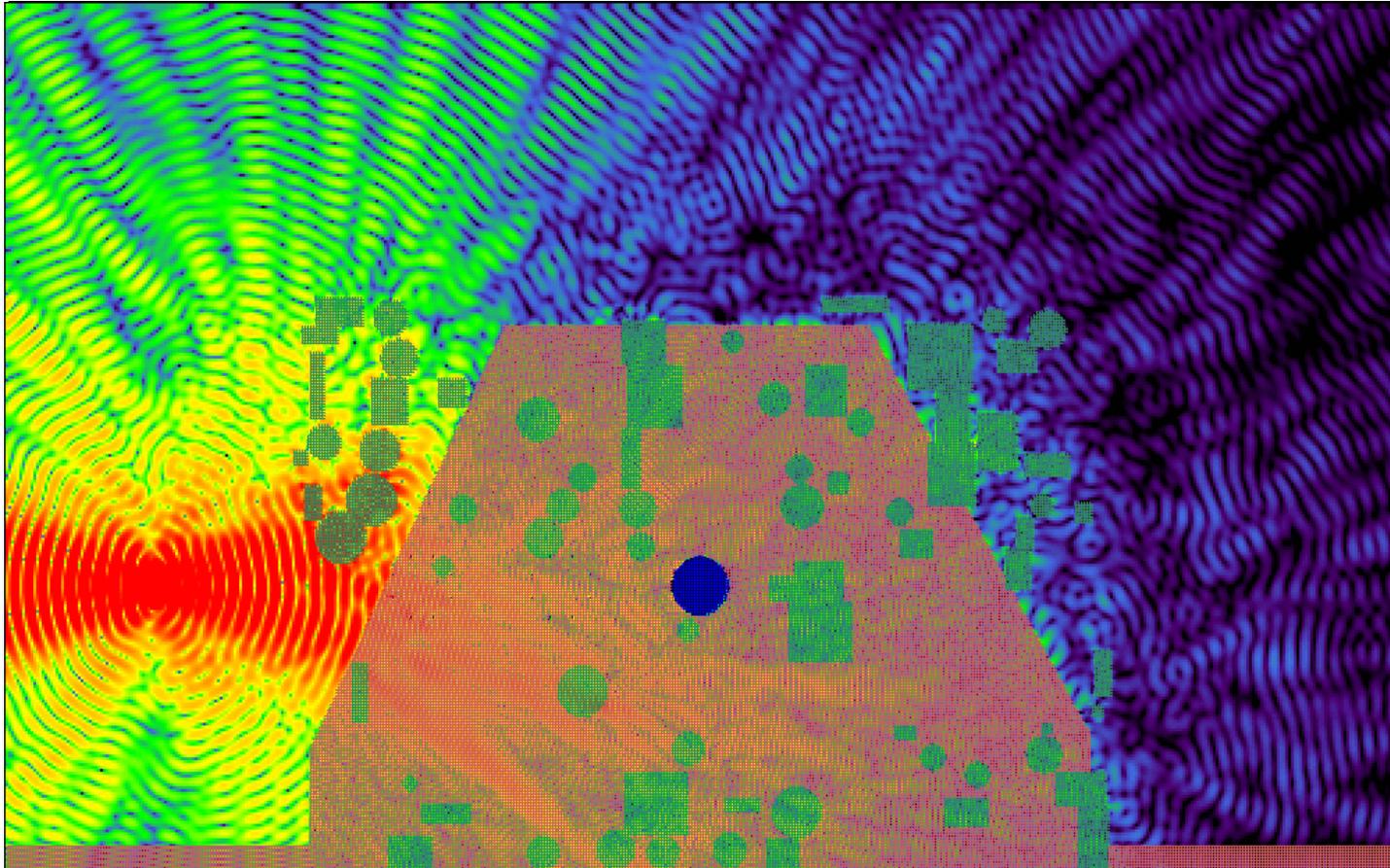


FDTD Run Timestep 5000 (~SS) Dielectrics visible



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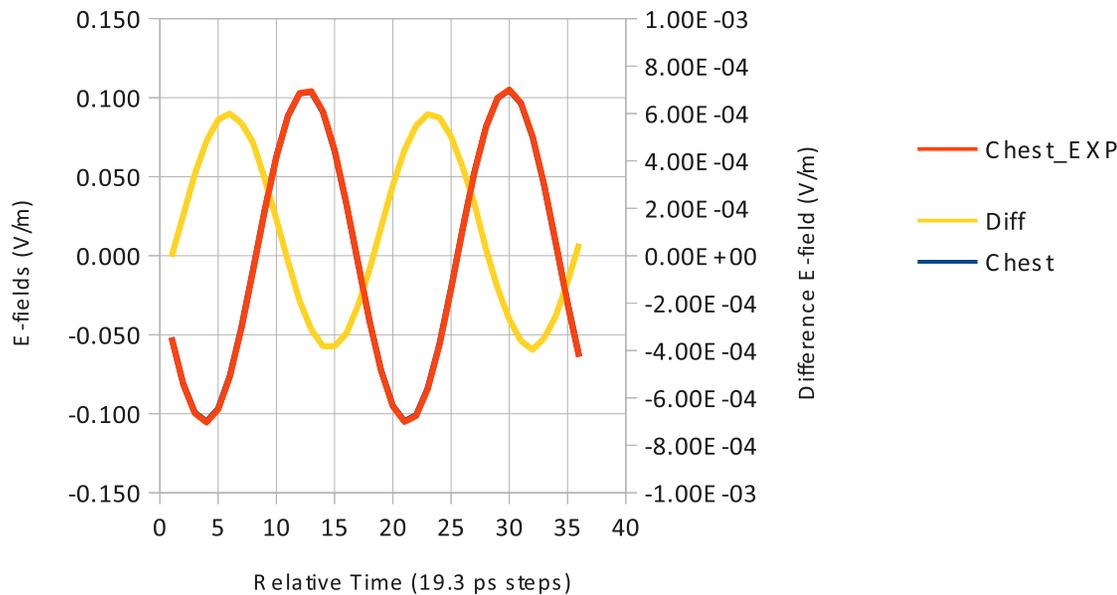


Simulated Measurement of Phase Difference Between Received CW Radar Signals



CW Radar Received E-fields

E_{chest} , $E_{\text{chest_EXP}}$, & Difference field



$$E_{\text{chest}} = 0.1 \sin(\omega t)$$

$$E_{\text{chest_EXP}} = 0.1 \sin(\omega t - \Psi)$$

Ψ = phase shift induced by expansion (EXP) of chest model

$$\text{Diff} = \sin(\omega t) - \sin(\omega t - \Psi) \approx \Psi \cos(\omega t)$$

where phase shift Ψ is small, so Ψ modulates the amplitude of $\cos(\omega t)$.

In this case, the perceived phase shift is ~ 0.34 deg for a 2 cm expansion of 20 cm dia sphere.

Note, here, Ψ is too small to see on this time scale so

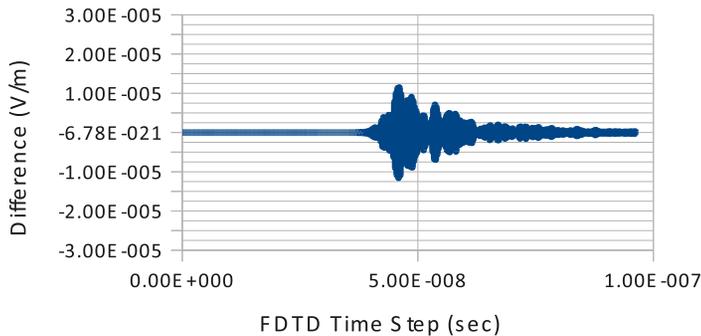
$E_{\text{chest_EXP}}$ hides E_{chest} .



Simulated Measurement of Phase Difference Between Received Pulse Radar Signals



1 Pulse Radar Received E-field Difference field for 1 cm expansion

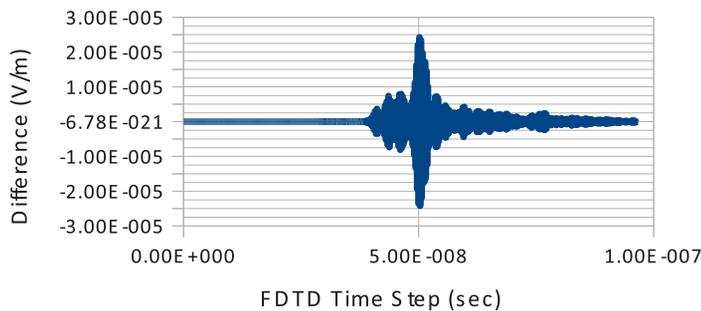


In this case, the received pulse is a sine wave “windowed” by a Gaussian pulse, so we again have

$$\text{Diff} = \{E_{\text{chest}} - E_{\text{chest_EXP}}\} \approx \Psi \cos(\omega t)$$

where phase shift Ψ is small.

2 Pulse Radar Received E-field Difference field for 2 cm expansion



Here, we see the perceived phase (amplitude) has doubled for double the sphere expansion for a 20 cm (dia) sphere.



Conclusions



- First Prototype (Mark 1) completed and tested with real rubble.
- Target phase shifts modeled & verified with FDTD
- Design in progress for smaller RF modules
- Software improvements in progress
- More performance testing at outdoor sites