



Mars 2018

Planetary Protection and Sample Integrity Focused Technology Development

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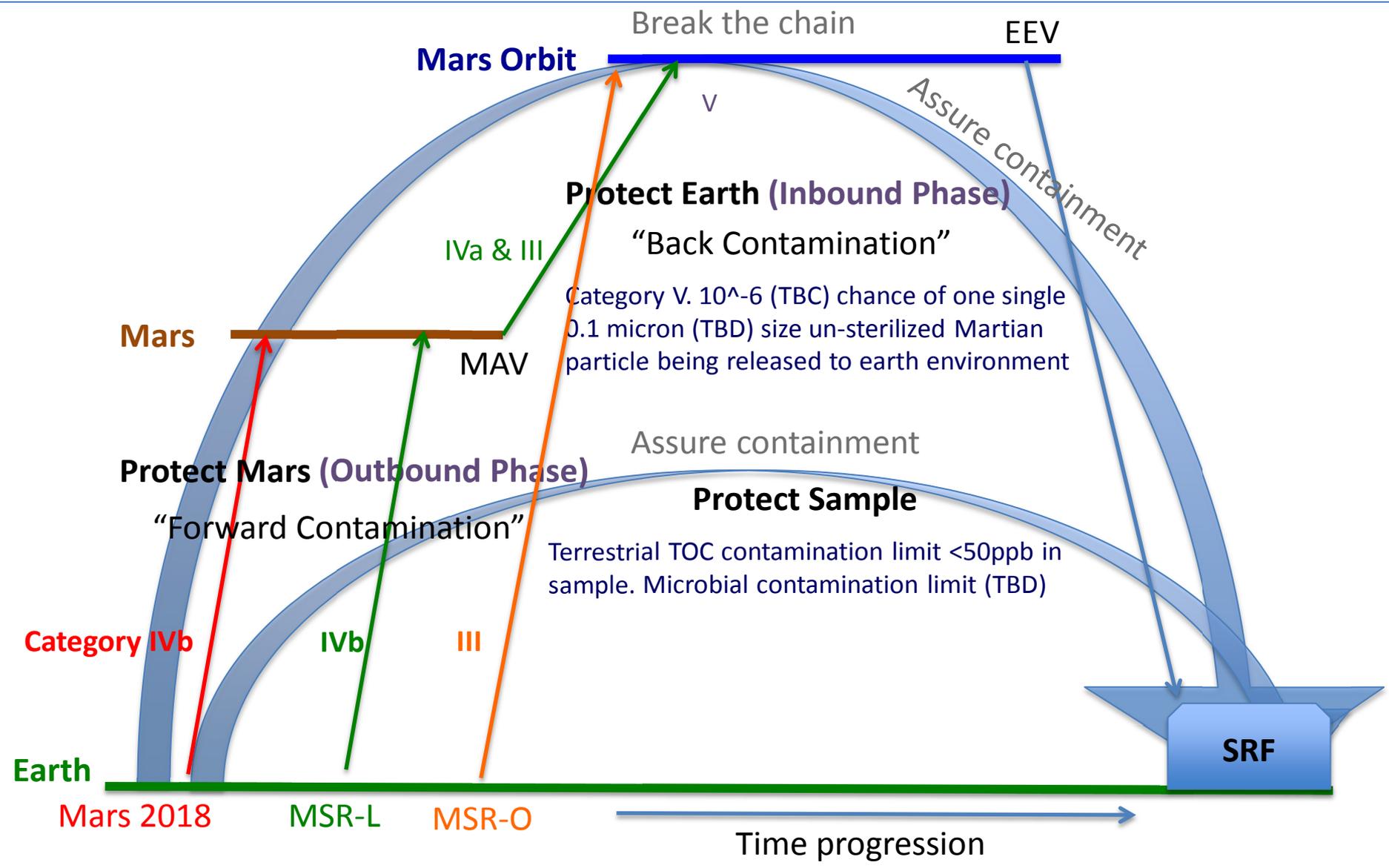


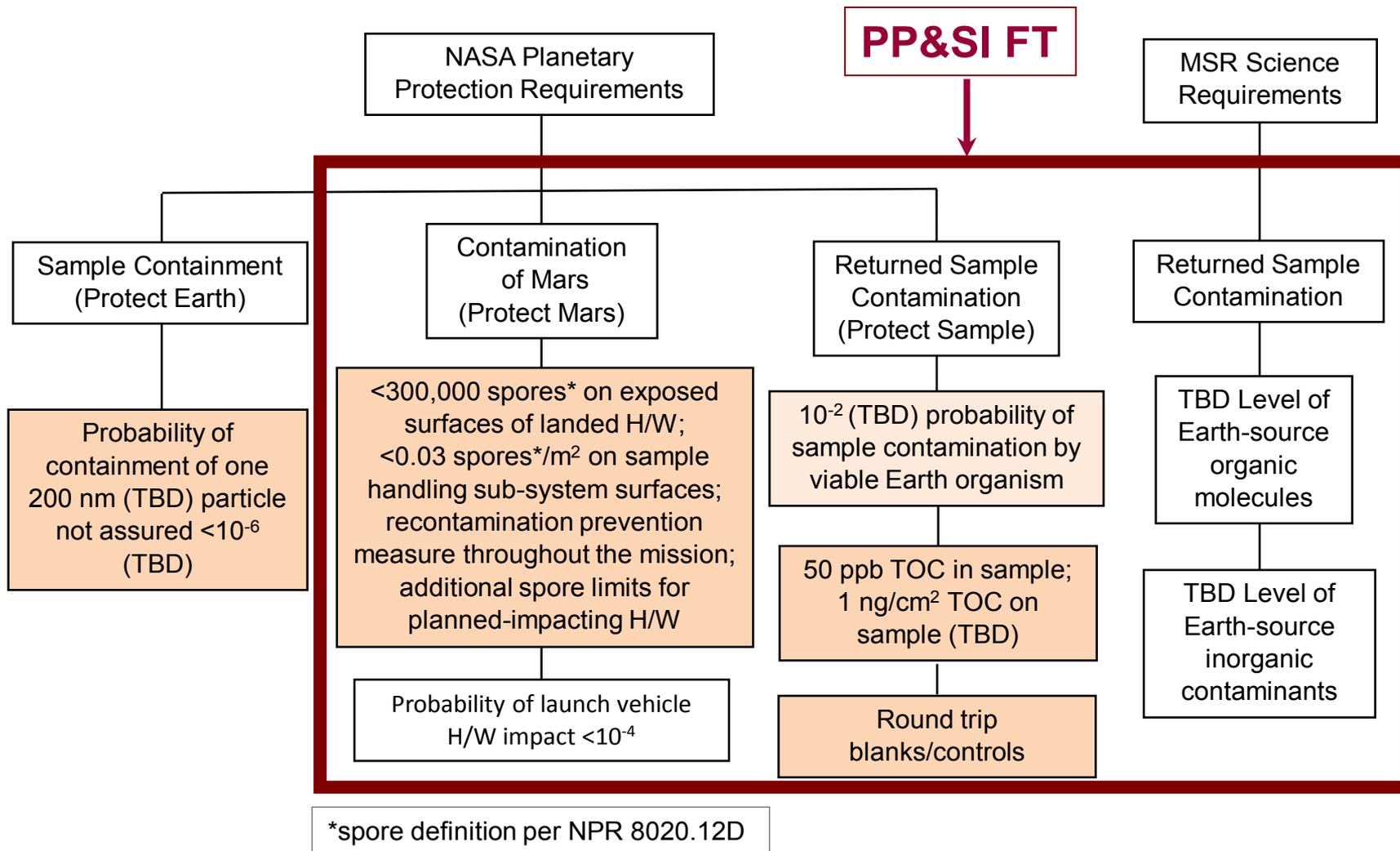
Outline

- Introduction
- MSR Planetary Protection Requirement (Draft)
- Technology Gap for Mars 2018
- PP&SI Focused Technology Plan



Planetary Protection Requirement Categories





Draft requirement guideline by Planetary Protection Officer for MSR, taken as goal for technology development.



Mars 2018

PP Category V and IVb

In situ life detection, caching, and sample return to Earth



MSL

PP Category IVa (recent change)

In situ measurements



Orbiter

PP category III

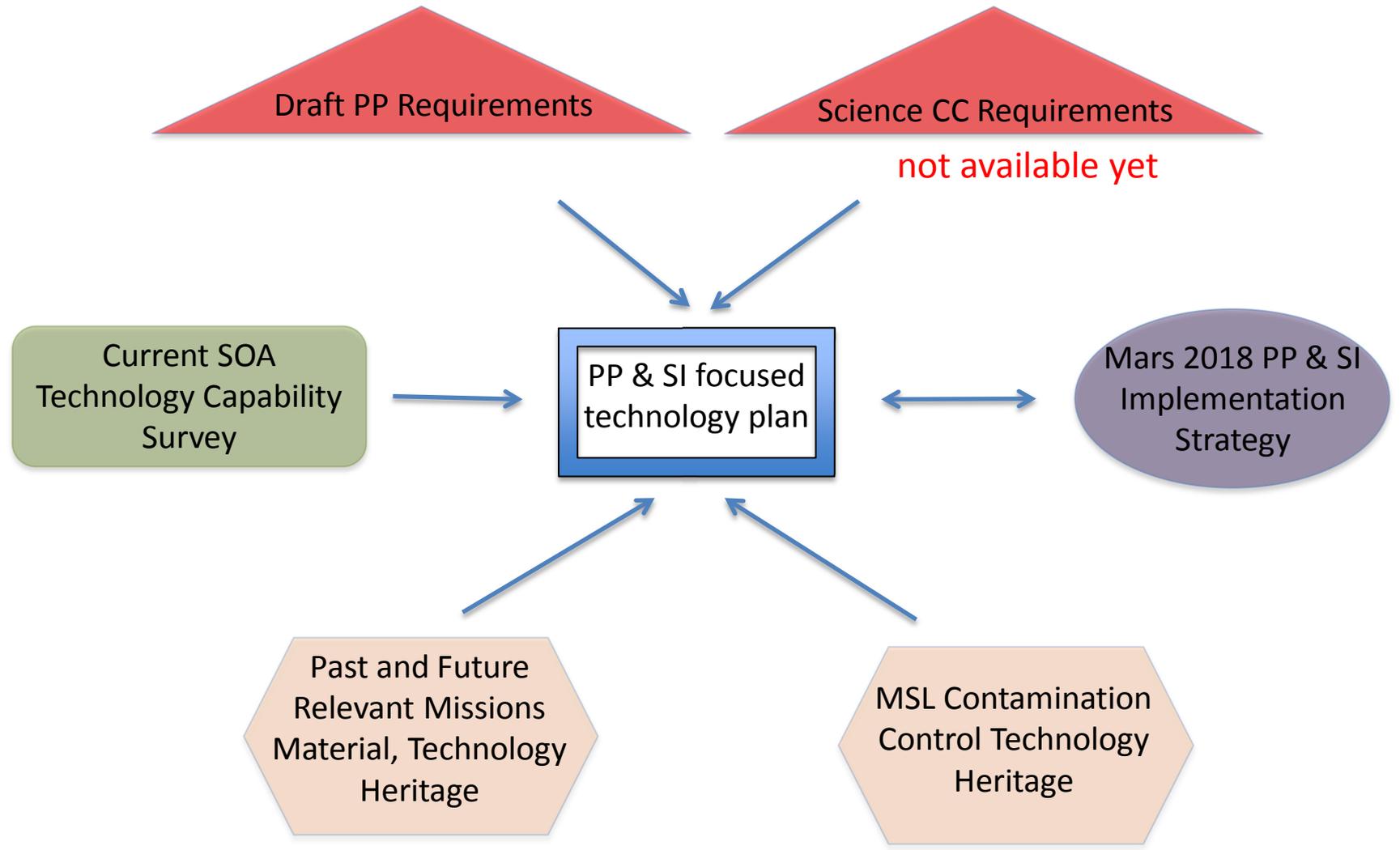
Crashing risk only

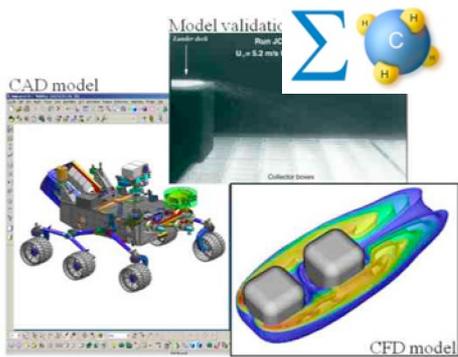
Mars 2018 new PP requirements and needs

- Sample handling hardware remain sterile until the sampling activity is completed (Not in Category IVc or IVa)
- Total 50 ng/g TOC contamination in sample. (MSL CC requirements only restrict the organic contamination transfer from hardware surfaces)
- Microbial contamination limit in sample (TBD)
- 1 ng/cm² TOC (TBD) Sample contacting hardware cleanliness and recontamination prevention measures required throughout the mission operation. (MSL CC requirement is 100 ng/cm² without recontamination prevention requirements)
- Sample integrity through containment, sealing and reduce any contamination risk during sample storage on Mars
- Round-trip blanks/controls are required (MSL optional)
- NASA PPO approval before launch (MSL, project approval for organic contamination)



Technology and capability gaps in the areas of contamination risk assessment, cleaning, sterilization, validation, and containment.





I. Contamination risk assessment

- Quantitative contamination burden assessment of hardware
- Contamination (biological and organic) transport measurement and modeling
- Risk assessment of sample contamination



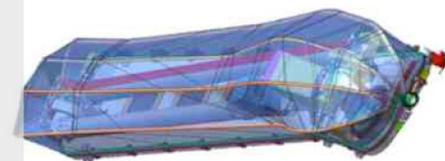
II. Surface sterilization and precision cleaning

- CO₂ cleaning, laser, plasma
- Cleaning validation (microbes, molecules, particles)
- SHEC cleaning



III. Re-contamination prevention

- Clean assembly
- Contamination barrier
- Organic sensor, getter



IV. Sample containment, sealing, sample integrity

- Material selection, compatibility to Martian samples
- Sealing method and materials
- Sample integrity





Description:

System Engineering approach to establish quantitatively the pathway of contamination transport from spacecraft hardware and environment to samples

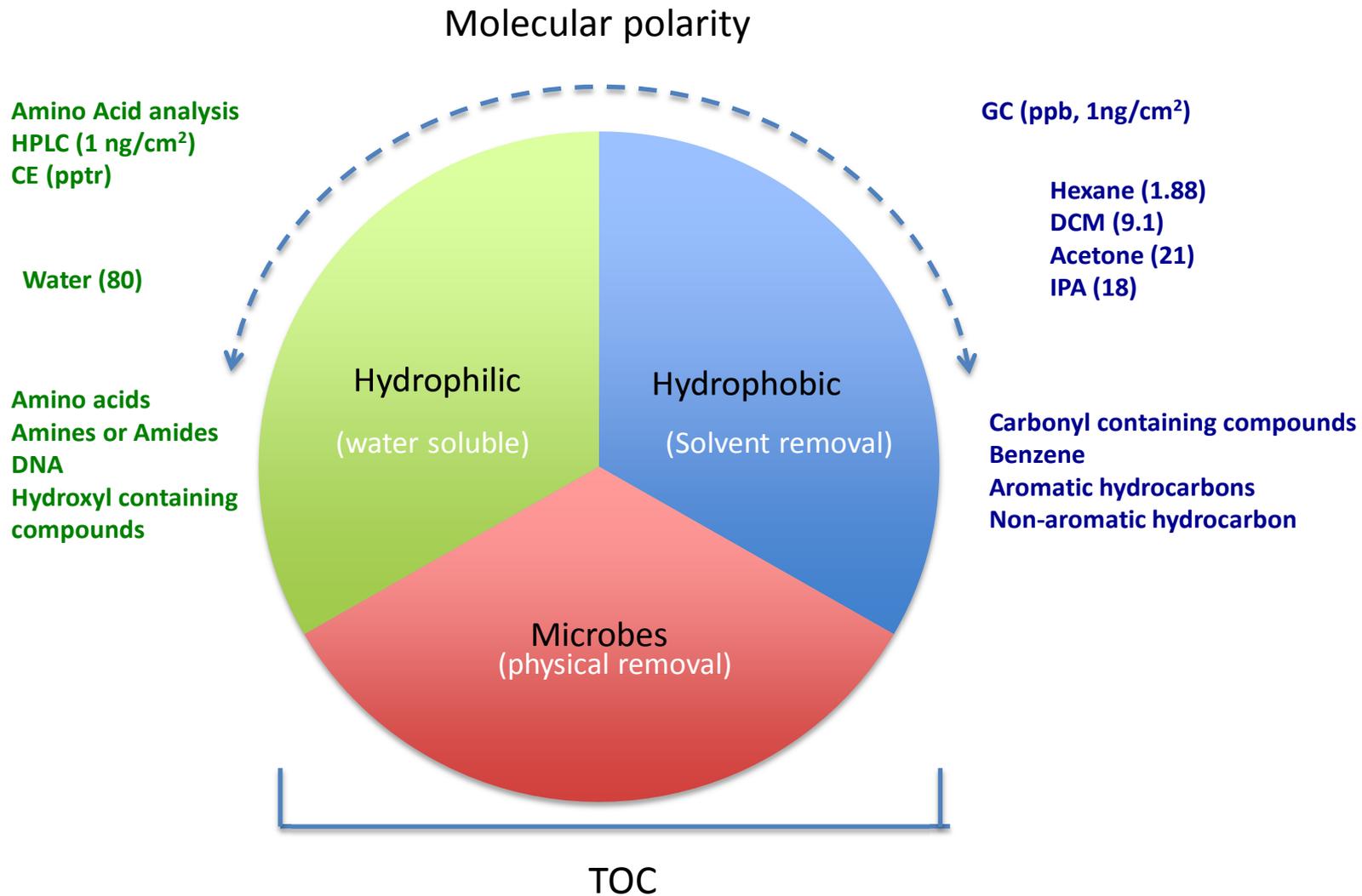
- Quantitative organic and microbial contamination burden assessment of hardware
- Contamination (biological and organic) transport measurement
- Transport modeling, Integrated tool development
- Risk assessment of sample contamination

Objectives:

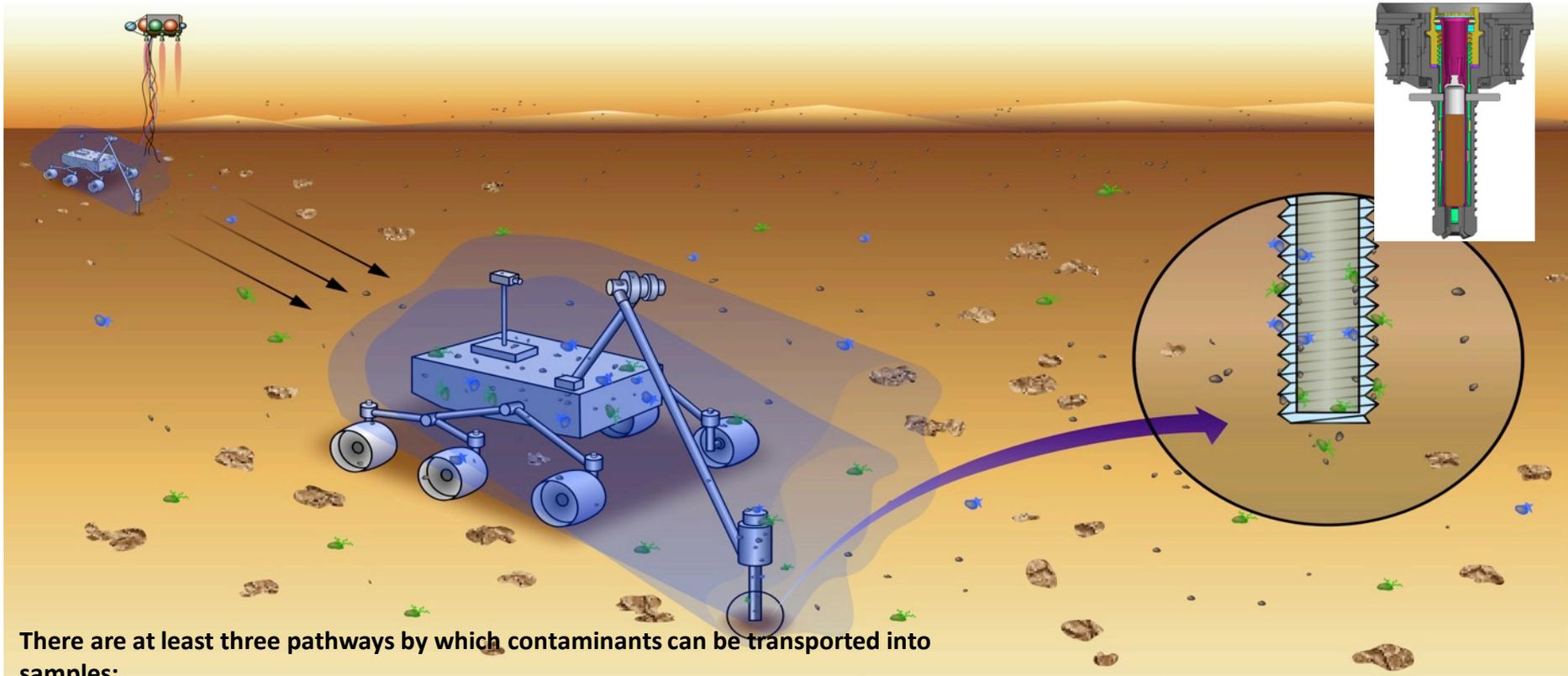
- Enable the Mars 2018 project to develop reliable implementation approaches including a set of flow-down requirements on outgassing material usage limits, hardware surface cleanliness levels, and hardware containment needs.
- Enable the project to demonstrate that it meets the PP sample organic and microbial contamination requirements



Total Organic Carbon Composition Chart

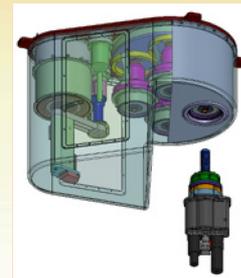


(Proportion is for illustration only)



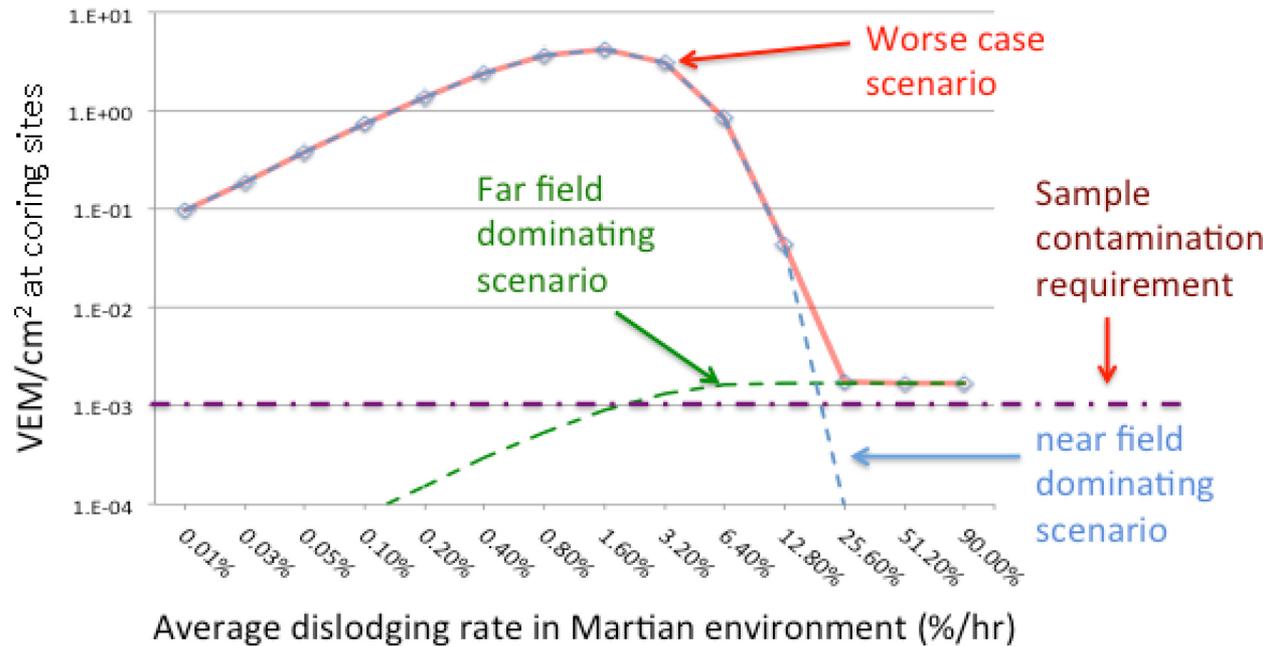
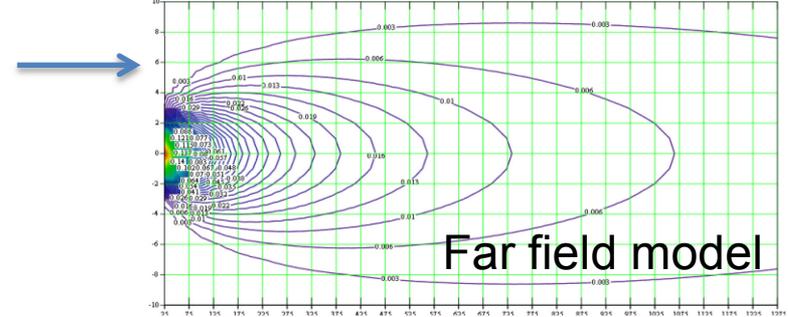
There are at least three pathways by which contaminants can be transported into samples:

- Direct contact – microbial and molecular contaminants are transferred from the hardware surfaces to samples by direct contact.
- Particle transport – Microbes and molecular contaminant-containing particles are dislodged from spacecraft hardware surfaces by wind or by mechanical forces and are then carried by wind to the sampling ground or into the sample tube.
- VOC transport – outgassed volatile organic compounds from nonmetallic parts will diffuse or be carried by wind to condense on the sampling ground, sample contacting hardware, and samples.



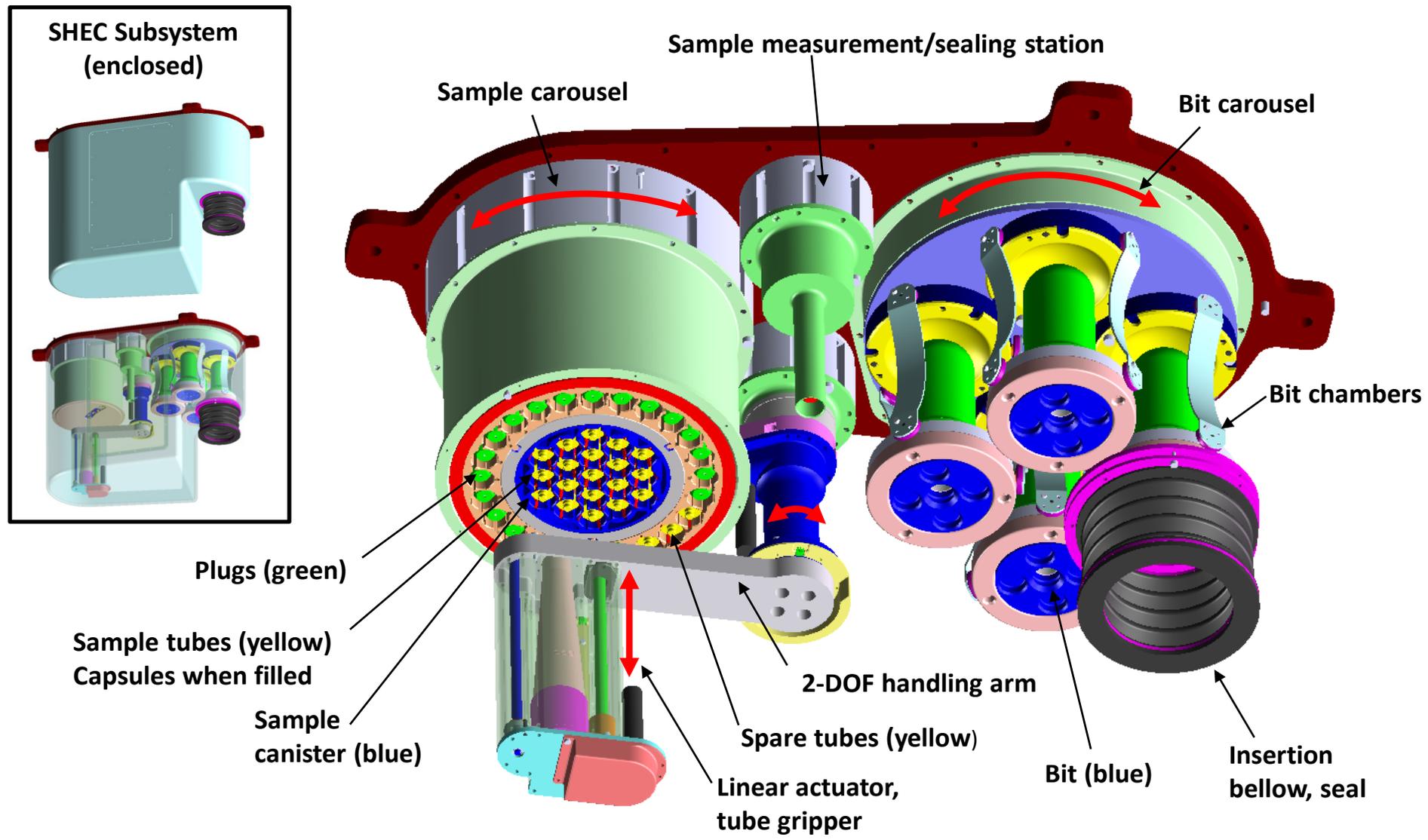
Assumptions:

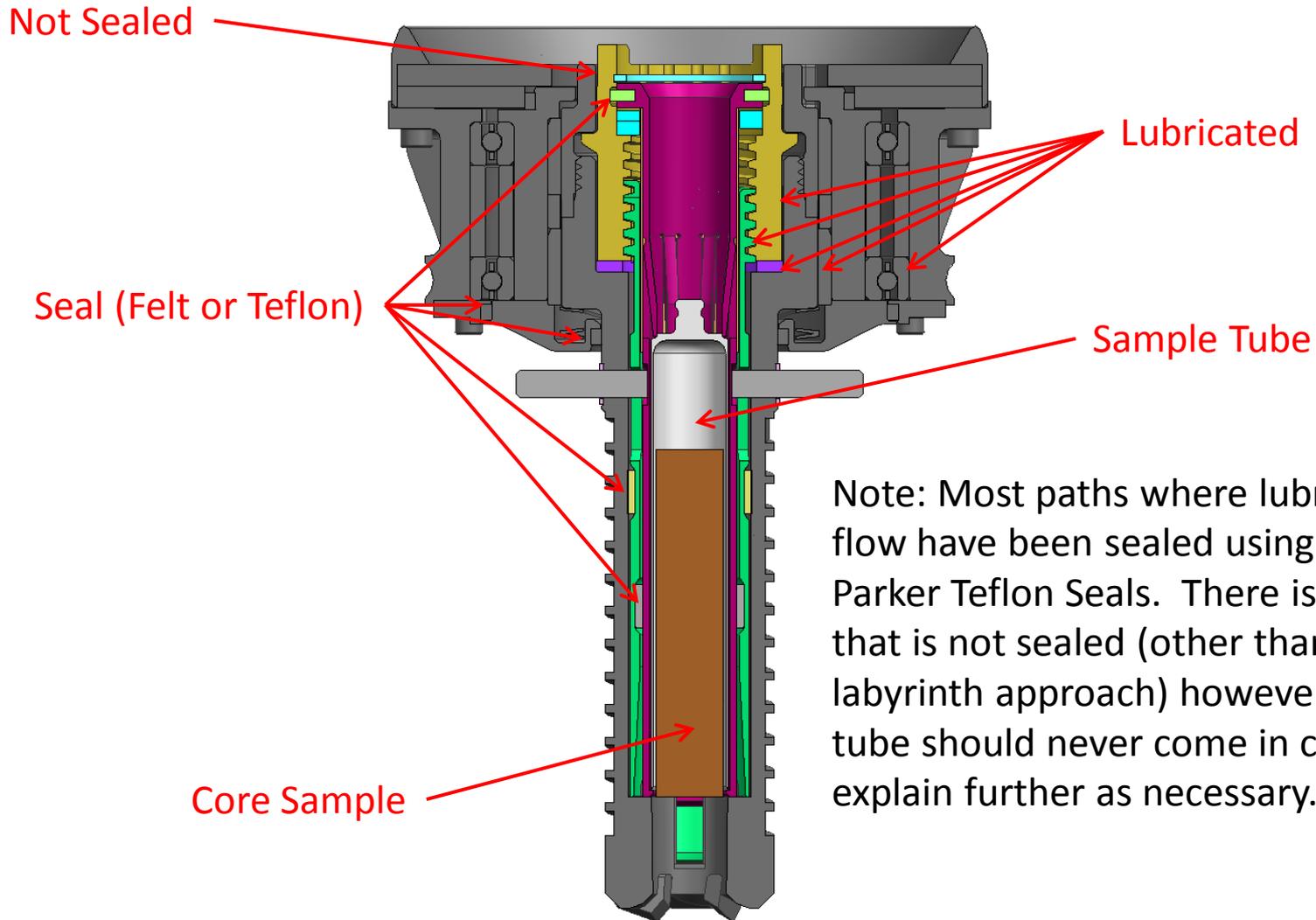
- Far field model under unidirectional wind of 7 m/s steady
- Rover moves 1 km away in the direction of the wind 48 hours after landing
- Another 24 hours at the sampling site
- Initial total spores on the rover is 3×10^5 and the corresponding VEM 3×10^8



Key points illustrated:

- The simple BOTE estimate illustrates that the risk of sample contamination is not low.
- It also shows that understanding accurately the particles dislodgement and the Martian weather conditions are critical to the overall contamination risk.





Note: Most paths where lubricant can flow have been sealed using Felt or Parker Teflon Seals. There is one path that is not sealed (other than utilizing a labyrinth approach) however the sample tube should never come in contact, can explain further as necessary.



Times of day
wind events

Speeds of day
wind events

Selection among
sterilization
options

Load settings
from a row in a
spreadsheet

Form1
Settings (click to change)

Calculator of Probability of Roundtrip Viable Earth Microbe (VEM) in Sample from Mars

Click to manually set wind event times & speeds:

Manual DayWind Times

Manual DayWind Speeds

Options to reduce VEM probabilities

<p>Sterilization</p> <input type="radio"/> NONE <input type="radio"/> HS = 0.1 <input type="radio"/> DHMR = 0.0001 <input checked="" type="radio"/> H2O2 = 0.001 <input type="radio"/> UV = 0.0001 <input type="radio"/> other = 0.01	<p>Cleaning</p> <input checked="" type="radio"/> NONE <input type="radio"/> IPA <input type="radio"/> UPW <input type="radio"/> Multiple Solvents <input type="radio"/> Semiaqueous <input type="radio"/> Oxygen Plasma	<p>Clean Sampling</p> <input type="radio"/> NONE <input checked="" type="radio"/> In Use
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Computation finished

Parameter values – user can change by clicking on them (see next slide)

BB_L = 100000
 BB_R = 100000
 BB_else = 50000
 BB_F = 40000
 BB_PPR = 300000 spore count
 V_R = 200 m/day
 T_L_1_S = 10 days
 T_L_1_C = 10 days
 T_R_1_S = 25 days
 T_R_1_C = 25 days
 DeltaT_L_S = 15 days
 DeltaT_L_C = 15 days
 DeltaT_R_S = 10 days
 DeltaT_R_C = 10 days
 N_L_S = 20
 N_L_C = 20
 N_R_S = 25
 N_R_C = 25
 A_S = 20 cm^2
 A_C = 1 cm^2
 A_R_S = 20 cm^2
 A_R_C = 1 cm^2
 A_ex_L = 20 m^2
 A_ex_R = 20 m^2
 A_ex_F = 270 m^2
 A_ex_else = 40 m^2
 f_e = 0
 f_d = 0.1
 f_m = 0
 f_f = 0
 f_c = 0.9
 V_n = 4 m/s
 t_R = 20 days
 k_1 = 1
 Z1_Inner = 1 m
 Z2_Inner = 3 m
 Z3_Inner = 100 m
 Z4_Inner = 1000 m
 Z4_Outer = 10000 m
 f_CR = 0
 q_exponent = 4.55
 Particle_minD = 0.3 micrometers
 Particle_maxD = 500 micrometers
 VwminInput = 3.5
 cs = 1
 sm = 3
 cm = 0
 filters = 0

Parameter values –
user can change by
clicking on them
(see next slide)

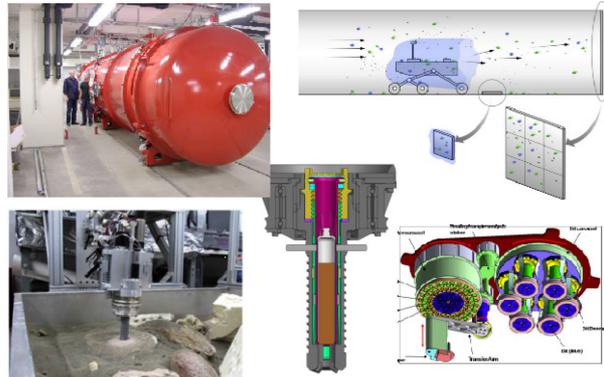
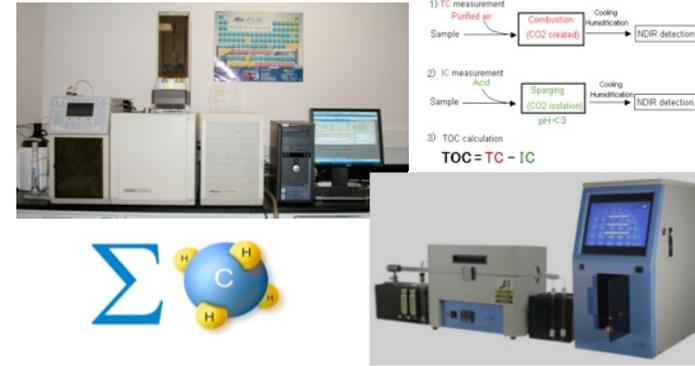


Main areas include physical process understanding, model development and validation, and an end-to-end model integration.

- 1. Wind-induced particle dislodgement*
- 2. Vibration-induced dislodgement*
- 3. Direct coring tool contamination*
- 4. Contamination inside the SHEC*
- 5. Martian wind information*
- 6. Special weather conditions*
- 7. Far field transport models*
- 8. Near field transport*
- 9. Organic vapor transport*
- 10. Quantify organic molecules-particle association*
- 11. Spore-particle association*
- 13. The ratio of VEM to spores*
- 14. Particle size distribution*
- 15. End to end model integration and analysis*

Contamination Burden Assessment

- Develop strategies to quantitatively assess the total organic carbon (TOC) burden of spacecraft hardware.
- Quantitatively assess the total microbial burden of spacecraft hardware



Contamination Transport Measurements

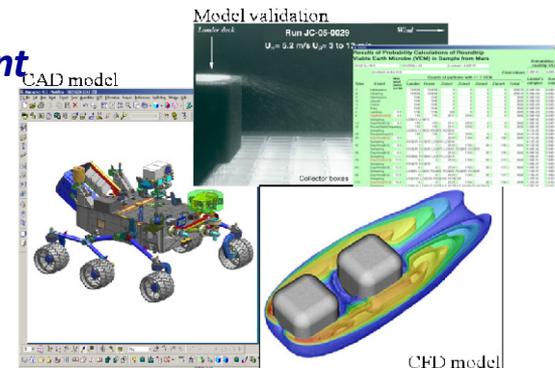
Objectives: Generate critical and realistic physical parameters that are necessary to develop a comprehensive end-to-end microbial and organic contamination transport model

Approach: by conducting experiments in testbeds including the Mars Wind Tunnel with drill, SHEC, and rover analogue, critical relevant interaction phenomena pertaining to particle and organic removal, transport will be measured.

Contaminant Transport Integrated Interactive Model Development

Objectives:

- Determine contaminant transport during surface operations in the Martian atmosphere to quantify spacecraft cleanliness requirements for surrounding area and samples.
- Develop an integrated interactive tool for assessing prognosis of meeting PP requirement





Description:

Develop precision cleaning technologies to achieve surface organic cleanliness and microbial sterilization. It also has potential for in situ cleaning applications

- CO₂ jet cleaning, Laser/plasma cleaning
- Cleaning validation (microbes, molecules, particles)
- SHEC cleaning

Objectives:

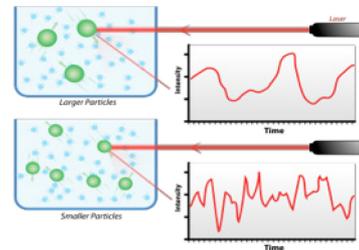
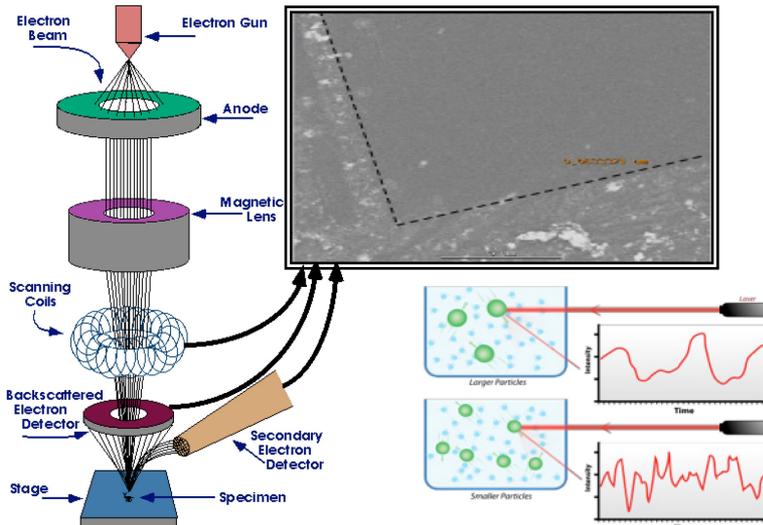
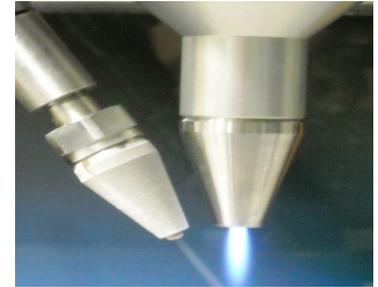
Enable the Mars 2018 project to successfully implement planetary protection (category IVb and sample contamination requirements) and mission science requirements



CO₂ Jet Cleaning

Objectives:

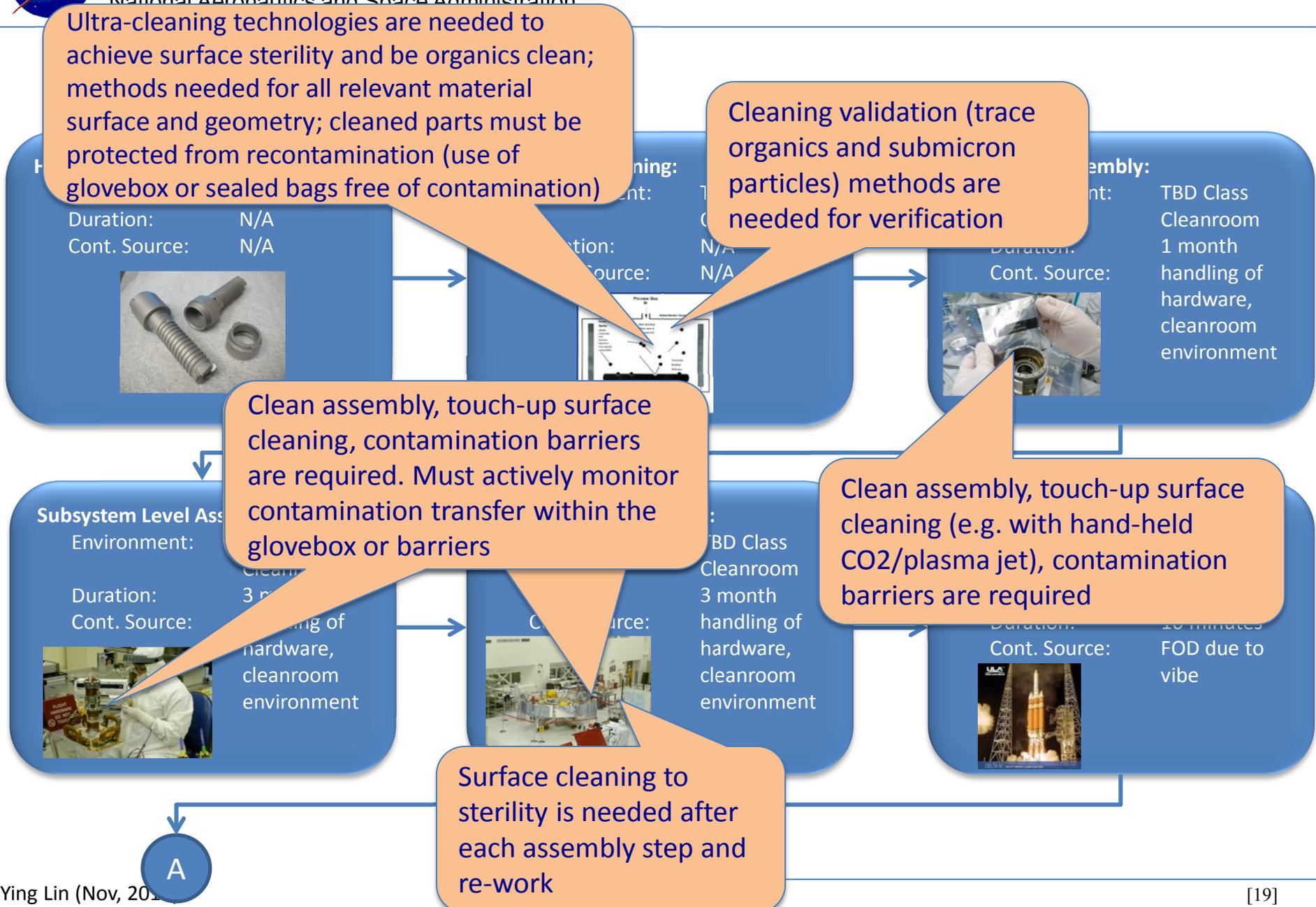
- Develop a cleaning method that will remove sub-micron particles by varying parameters such as CO₂ crystal size, speed of delivery onto surfaces
- Validate cleaning efficiency
- Develop a TRL 6 touch-up cleaning device
- Evaluate the possibility for in situ clean sampling applications on Mars



Cleaning Validation

Objectives:

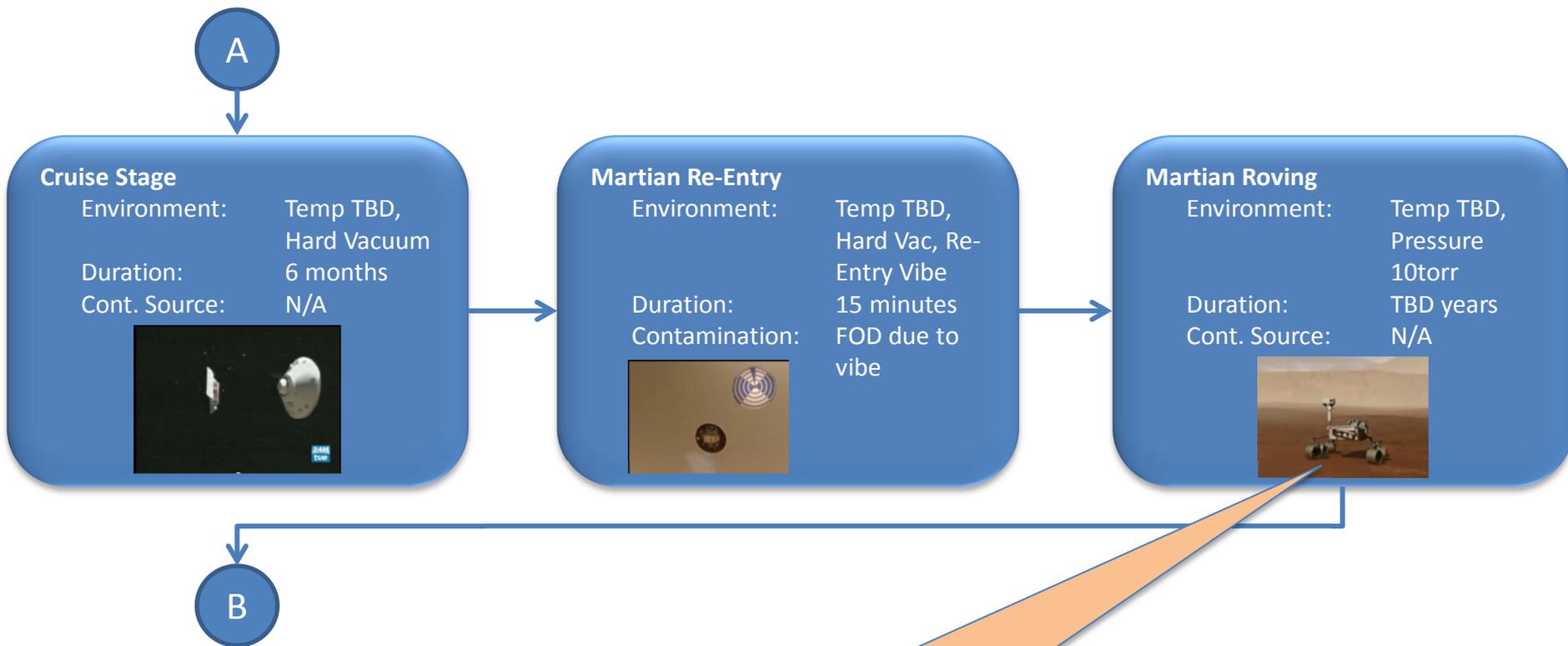
- Validate surface cleaning methods
- Design and build optical detection system for surface particle analysis
- Calibrate and measure detection sensitivity
- Distinguish contaminant types



A



A Possible PP Implementation Approach (Con't)



Procedures must be taken to avoid sampling area contamination from rest of (dirtier) lander or rover. Transport models (vapor, particle, contact) for Martian environments are needed for contamination risk analysis



B

Insert clean sample tube in bit assy and remove Bit from SHEC

Environment: Temp TBD, Pressure 10torr

Duration: ~10 minutes

Cont. Source: N/A



All coring and sample handling parts must be protected from recontamination from dirtier parts of the lander or rover. Need transport model and experimental verification

Environment: Temp TBD, Pressure 10torr

Duration: ~2 hours

Cont. Source: Cross-cont. from previous samples



Place Bit Assy into SHEC and remove sample Tube from Bit

Environment: Temp TBD, Pressure 10torr

Duration: ~10 hours

Cont. Source: Cross-cont. from previous samples



Cap and Seal Sample Tube and Place in Sample Canister

Environment: Temp TBD, Pressure 10torr

Duration: ~10 minutes

Cont. Source: Cross-cont. from previous samples



Req#1: no live microbes
 Req#2: 50 ppb TOC
 Modeling tools, experimental data are needed for requirements flow-down (e.g. limits on offgassing, outgassing rates, non-metallic materials used: amounts and locations, hardware surface cleanliness requirements)

Place Sample Canister on Martian Surface and await Fetch Rover

Environment: Temp TBD, Pressure 10torr

Duration: ~5 years

Cont. Source: Atmospheric dust, failed

Sample integrity, material compatibility

C



Description:

Strategies for preventing re-contamination between hardware components.

- Clean assembly
- Contamination barriers
- Organic sensor, getter

Objectives:

- Prevent contamination transport between hardware components (molecular and particulates)
- Protect cleaned sample contacting hardware from re-contamination during ground handling and sample acquisition on Mars
 - PP requirements (*MSR Campaign, Caching Mission, and MAV Mission, July 2011*) :
 - Surface molecular cleanliness of $< 1\text{-}10 \text{ ng/cm}^2$ (TBD)
 - Surface microbial cleanliness $< 0.03 \text{ spores/m}^2$
 - No particles $> 200 \text{ nm}$ in diameter (TBD)
- Prevent contamination of Martian sample from terrestrial contaminants carried by spacecraft
 - PP Requirement: $< 50 \text{ ng/g}$ of terrestrial organics transferred to Martian sample
 - Microbial contamination probability limit $< 10^{-3} \text{ VEM}$ (TBD)

Implementation Strategies

- Clean assembly techniques (mini-environments)
 - Vacuum enclosure required for 1 ng/cm² cleanliness level
- Develop contamination barriers
 - Encapsulation on Earth and Mars
- Molecular sensors for monitoring of contaminants
- Develop custom filters and molecular getters
- Fly controls/blanks to monitor contamination health

Cross-Contamination Prevention Technologies



Objectives:

- Develop strategies to prevent re-contamination of hardware components
 - Clean assembly
 - Contamination barriers
 - Molecular sensors, getters

Description:

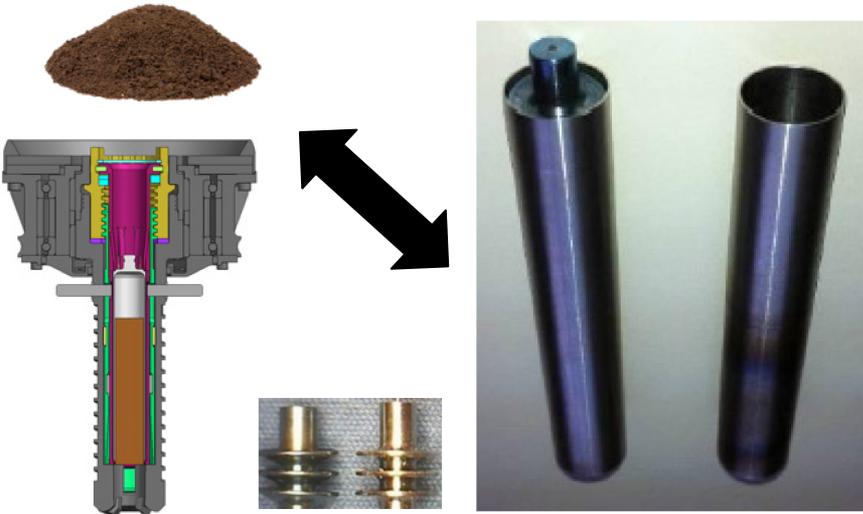
Establish and test candidate material capabilities to samples by working with the caching and science teams to fulfill sample integrity science requirements for Mars 2018

- Material selection, compatibility to Martian samples, sample integrity
- Sealing method and materials

Sample Containment, Sealing, and Sample Integrity

Objectives:

- Define and deliver standard procedures for evaluating and recommending compatible materials.
- Evaluate sample/container interaction through chemical, mechanical, and physical compatibility tests using Martian analogue soils
- Assess material integrity against environmental factors
- Investigate materials and sealing techniques within constraints of the Martian environment
- Deliver a material lifetime prediction based on an Arrhenius-based model fit of the data





Summary

- Mars 2018 is a Cat V and IVb mission with corresponding PP requirements
- MSR PP requirements are sufficiently different from all previous Mars missions that new technology and capabilities are needed.
- Technology gaps for Mars 2018 have been identified and an investment portfolio developed
- Mars Focused Technology program will invest in four critical areas:
 - *Contamination risk assessment*
 - *Surface sterilization and precision cleaning*
 - *Cross contamination prevention*
 - *Sample containment, sealing, sample integrity*