

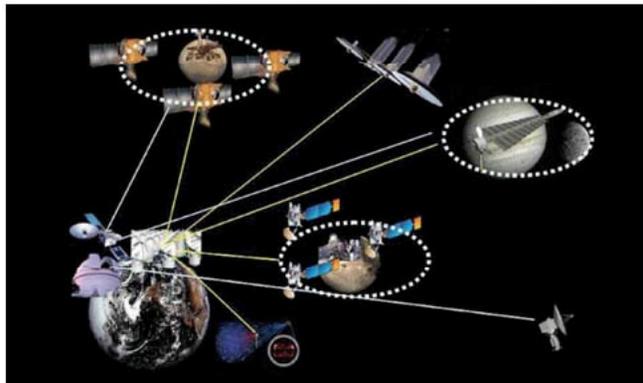
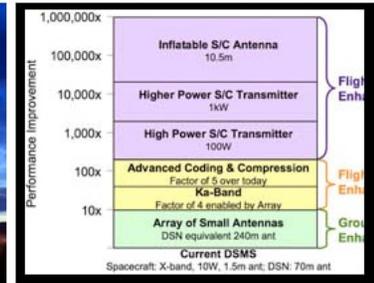
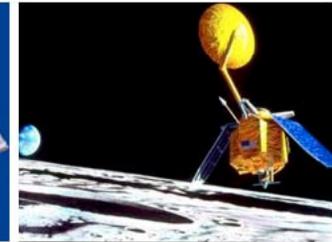
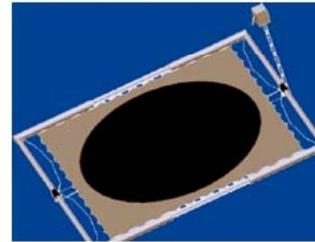


Jet Propulsion Laboratory
California Institute of Technology

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Asynchronous Message Service for Deep Space Mission Operations

Scott Burleigh





Asynchronous Message Service Motivation

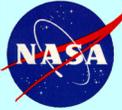


- **CCSDS File Delivery Protocol (CFDP) helps standardize deep space mission ops, but not all mission information is in files:**
 - Continuous telemetry.
 - Real-time commanding.
 - Inter-spacecraft coordination.
- **As software grows in capability it tends to become more complex.**
 - Increasing complexity tends to increase risk and therefore cost.
 - Modular design can reduce software complexity, but resulting growth in inter-module message exchange increases system complexity.
 - Standardizing inter-module messaging can reduce system complexity.
- **“Publish-subscribe” asynchronous message exchange can simplify system operations and improve both message delivery latency and bandwidth efficiency, but there is no broadly used open international standard for it.**
- **So CCSDS has undertaken development of such a standard: CCSDS Asynchronous Message Service (AMS).**

Asynchronous Message Service Overview of AMS



- **Core “message bus” model: each application software node subscribes to (and consumes) the information it needs, and publishes the information it produces, without knowing which other modules are currently running.**
 - **Explicit awareness of other node is provided as well, as needed.**
 - **Private message transmission to specific nodes, including replies to published messages, is supported as needed.**
 - **Synchronous (client/server) communication is supported as needed.**
- **Purpose: reduce cost and risk by enabling message exchange that is...**
 - **Simple to use**
 - **Highly automated**
 - **Flexible**
 - **Robust**
 - **Scalable**
 - **Efficient**



Asynchronous Message Service Abstract “UT layer”



- **Like CFDP, AMS is designed to run over transport systems that provide the necessary connectivity and quality of service.**
 - Buses (e.g., 1553)
 - Message queues
 - Internet paths
 - CCSDS-conformant links
- **Advantages of UT layer abstraction in deep space operations:**
 - Simple migration of software between flight and ground
 - Scaling from on-board to interplanetary environments
- **Advantages in ground operations:**
 - Stable installed base of standard terrestrial network protocols
 - Simple integration with existing systems
- **Advantages in on-board operations:**
 - Leverage from real-time QOS features of on-board infrastructure

Asynchronous Message Service Quality of Service



- **AMS itself doesn't implement QOS measures; it relies on the measures provided by UT-layer protocols.**
 - Makes AMS itself smaller.
 - Enables use of AMS in an unlimited variety of environments.
- **But AMS is still sensitive to QOS requested by the application:**
 - Application can specify transmission *mode* to AMS, causing AMS to select an underlying transport protocol with the desired characteristics.
 - Assured or best-effort message delivery.
 - Delivery in arrival order or preservation of transmission order in delivery order.
 - Application can specify *priority* and *flow label* to AMS. These parameters are opaque to AMS; AMS simply passes their values through to the selected underlying transport protocol.



Asynchronous Message Service Constraining transmissions



- **Transmission constraints can be specified in subscriptions (selecting publishers) and in announcements (selecting recipients).**
 - **Constrain to all – and only – nodes registered in a specified zone or in any zone that’s wholly contained within the specified zone.**
 - **Constrain to all – and only – nodes declared at registration to be performing a specified *role* in the application.**
 - **Constrain to all – and only – nodes operating within a specified continuum.**
- **This fine-grained control over message publication enables a balance to be struck between latency and bandwidth utilization.**
 - **Information is pushed rather than pulled, so there is no query/response round trip delay.**
 - **But information need never be pushed to nodes that aren’t interested in it.**

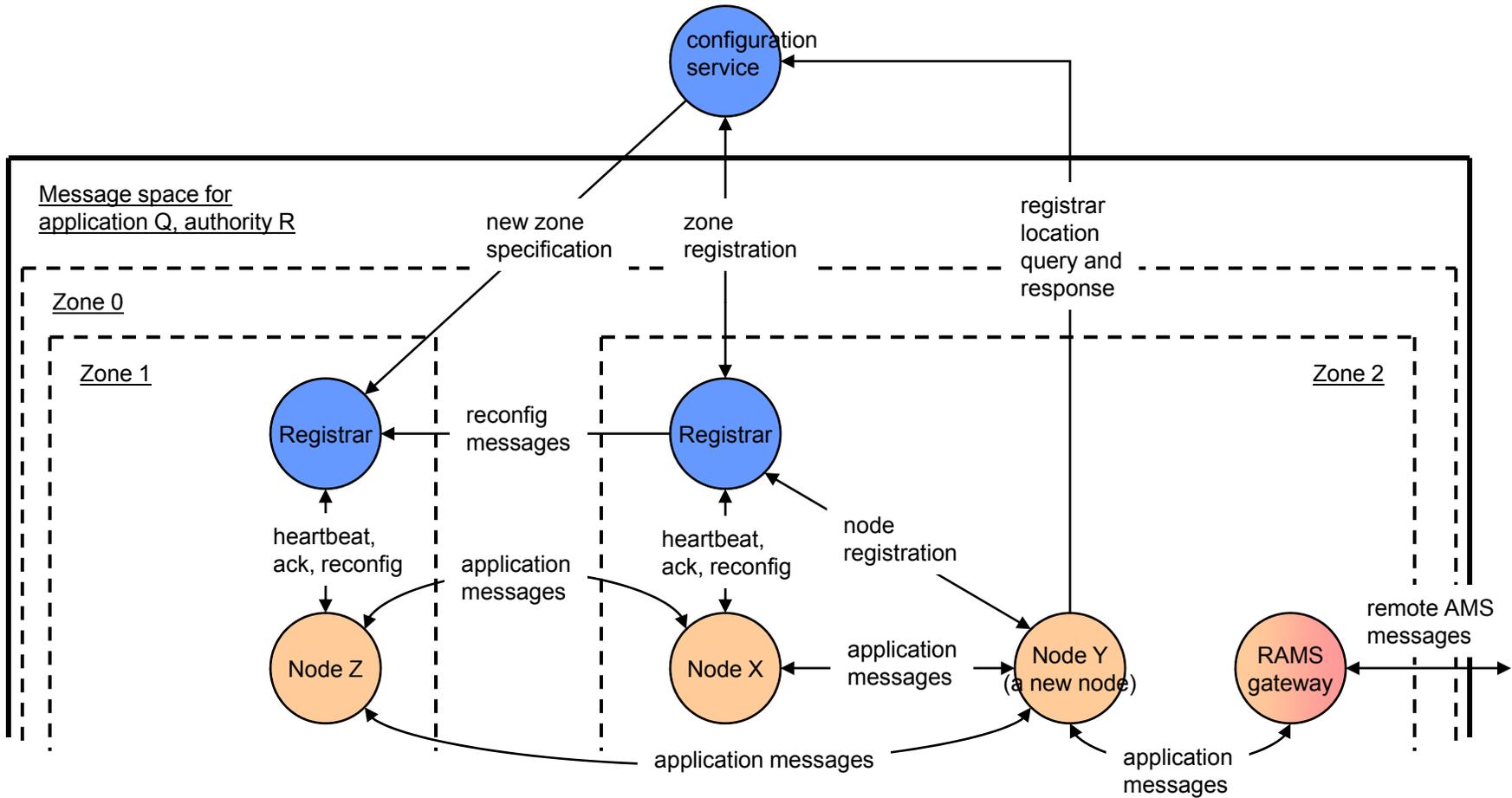
Asynchronous Message Service

Additional features



- **Security**
 - Access control
 - Authentication
 - Encryption
- **Fault tolerance**
 - Preventive maintenance
 - Inference of remote node failures
 - Failover
 - Autonomous recovery
- **“Announcement” of data to anonymous nodes**
- ***Remote AMS (RAMS)* aggregates message publication to minimize bandwidth consumption on constrained links.**
 - Designed to enable dynamic publish/subscribe functionality over interplanetary distances

Asynchronous Message Service Operations: a single AMS continuum

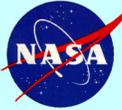


Asynchronous Message Service

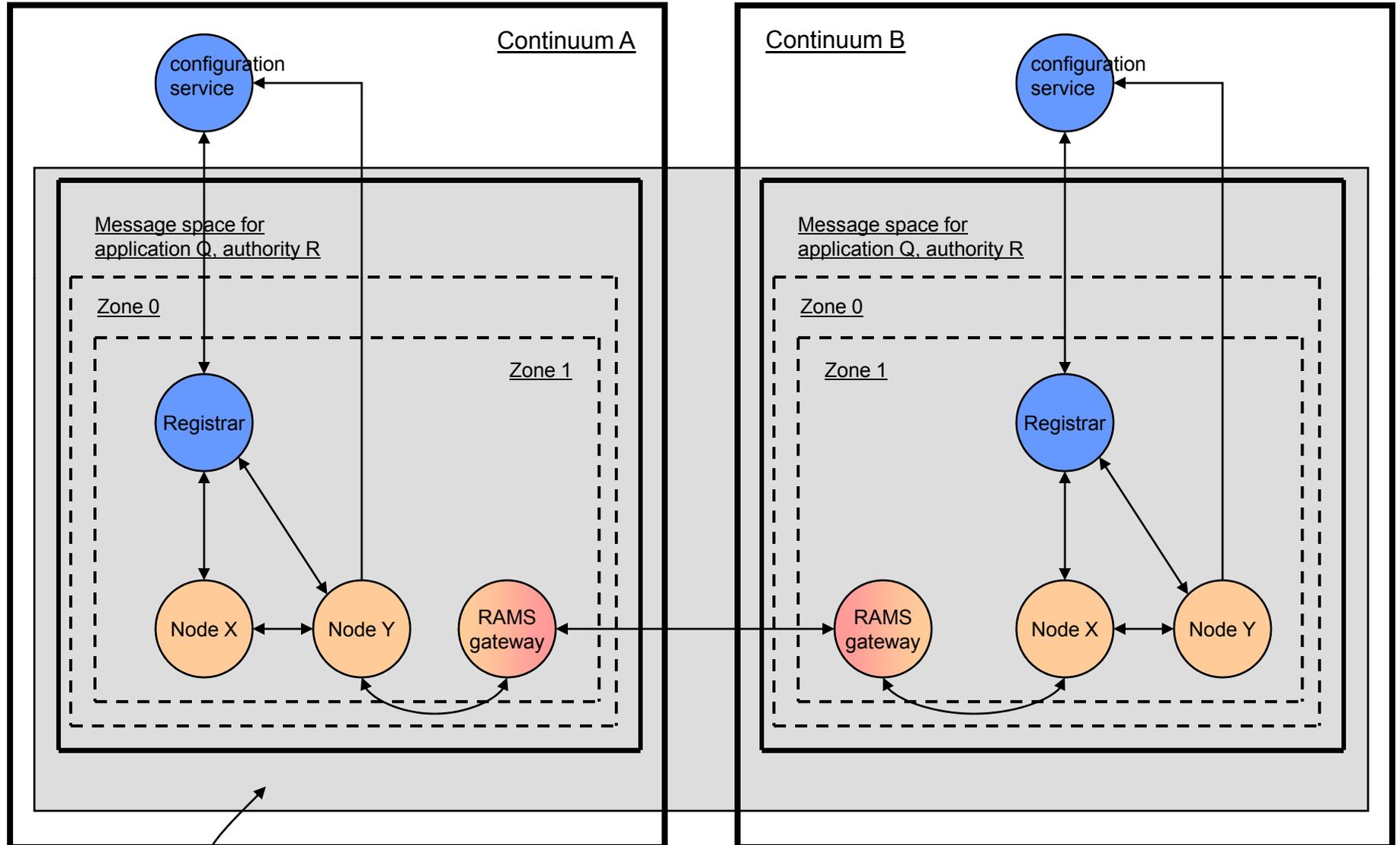
The AMS Protocol Suite



- **Meta-AMS**
 - **Discovery, self-configuration (including subscriptions and unsubscriptions), fault detection, failover, recovery.**
 - **Messages are exchanged between nodes and configuration servers, between nodes and registrars, between configuration servers, between registrars, and between registrars and configuration servers.**
- **AMS**
 - **Application data transmission; queries, replies, announcements.**
 - **Messages are exchanged between nodes (including RAMS gateways, which function as AMS nodes).**
- **Remote AMS**
 - **Assertions and cancellations of “petitions”; aggregated application data transmission.**
 - **Messages are exchanged between RAMS gateways.**



Asynchronous Message Service Operations: a multi-continuum “venture”



Concatenated application instance (“venture”) for application Q, authority R.



Asynchronous Message Service

Performance of Prototype Implementation



<i>Number of messages sent</i>	<i>Size of each message (bytes)</i>	<i>Messages exchanged per second</i>	<i>Data rate (Megabits/sec)</i>
10,000	20,000	5,337	814
100,000	2,000	25,739	393
1 million	200	107,910	165
10 million	20	154,335	23

Highly preliminary performance measurements, from JPL's Protocol Test Laboratory. Message exchange between a single publisher and a single subscriber on a Gigabit Ethernet. Each node was hosted on a dual-core 3Ghz Pentium-4 running Fedora Core 3. (Don't expect this kind of performance in normal operations!)

Asynchronous Message Service Conclusion



- **AMS is in early stages of standardization.**
 - CCSDS “white book” (Proposed Standard) has been published.
 - A single implementation has been developed and is being tested.
- **No major obstacles encountered so far.**
 - Protocol has changed since original concept paper, but not radically.
 - Design concepts seem to be sound.
- **AMS capabilities seem to be broadly applicable.**
 - On-board, proximity, and deep-space communications for spacecraft.
 - Suitable underlying messaging protocol for proposed CCSDS Spacecraft Monitor and Control protocols.
 - Terrestrial applications designed for operation over a message bus.
- **AMS Working Group within CCSDS is on schedule, so far.**