

Water vapor measurement and compensation in the near- and mid-infrared with the Keck interferometer nuller.

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Motivation: Why measure H₂O?

- * “Dry air” (molecules other than H₂O) contributes most of the overall refractive index across visible and infrared wavelengths
- * H₂O density can vary somewhat independently of the overall air density, on short timescales (“H₂O Seeing”)
- * H₂O is highly dispersive and often dominates the overall dispersion
 - => Fringe phase delay at 10 μm differs significantly from phase delay at 2 μm (“inter-band dispersion”)
 - => Phase delay varies significantly across the Nuller bandpass (“intra-band dispersion”)
- * These effects can substantially increase the leakage through the null
 - => For typical Mauna Kea conditions, the inter-band dispersion between the K and N bands is of the order of 1 μm . This corresponds to a V^2 loss of 28%, or a null leakage of 7%.
 - => Intra-band dispersion in the Keck Nuller is comparable

Method: How do we measure H2O?

* For a typical Nuller target, the N-band SNR is not adequate to measure the broadband fringe phase or the dispersion across the band quickly enough.

* The K-band SNR is much higher.

* However, there will be differences between N-band and K-band values due to non-common paths. These are expected to introduce slow relative drifts.

=> Use the K-band data to measure the differential H2O column on short timescales. Feed this information forward to the N-band system.

=> Use the N-band data itself to make measurements on long timescales.

* H2O differential column is proportional to the difference between the group delay (GD) and the unwrapped phase delay (PD)

=> Measure GD-PD in the K-band data

=> Compute N-band fringe position and GD (linear transformation)

=> Compute the optimal delay-line OPD and dispersion controller setting for N

Data: Phase and Group Delays for the K and N Bands

Measurements on Epsilon Eri

$$m_K = 1.7 \text{ (134 Jy)}$$

$$F_\nu(N) = 9 \text{ Jy}$$

$$\theta = 2.1 \text{ mas}$$

5 minutes of data taken on UT 19 Oct 2005, during a period of strong H₂O seeing

Simultaneous fringe measurements with

Primary MMZ (N-band beam combiner; 16 spectral channels, 8.0-12.5 μm)

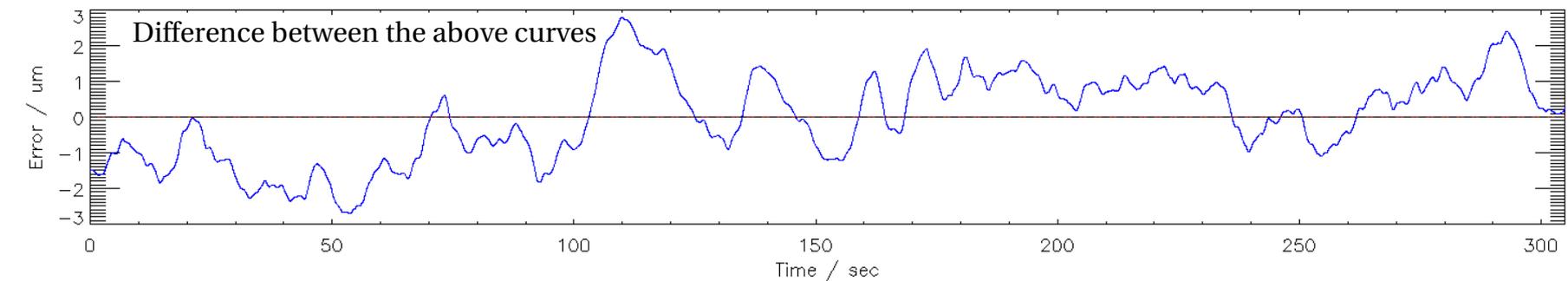
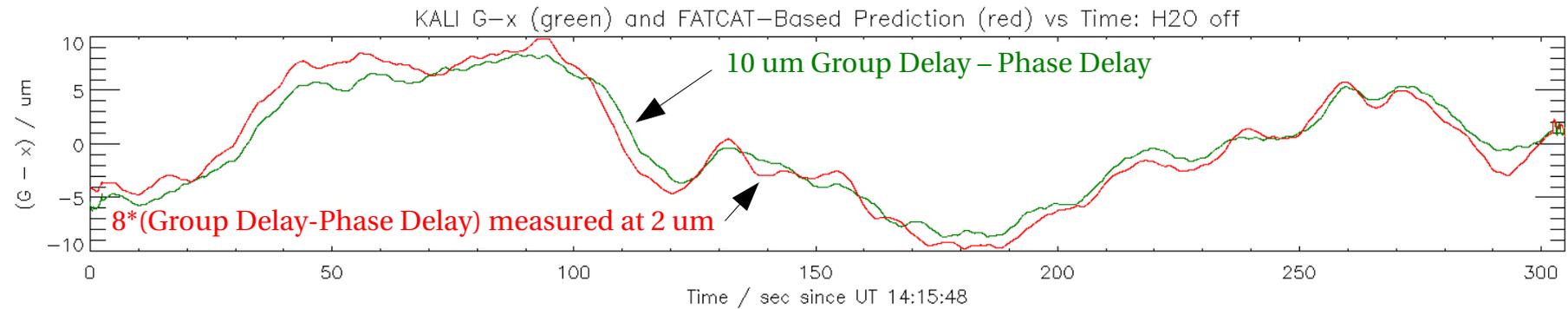
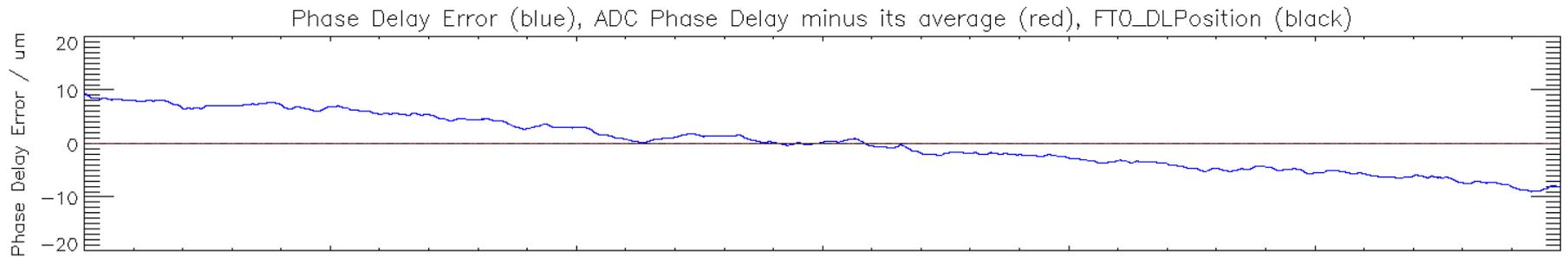
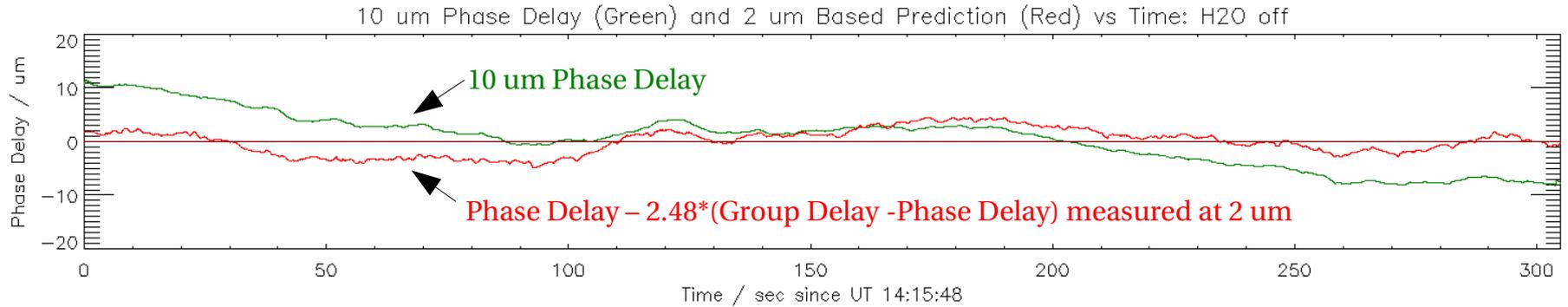
Primary FATCAT (K-band beam combiners; 4 spectral channels, 2.0-2.4 μm)

Phase and group delays were derived from the spectral data, and filtered to improve SNR

Phase was unwrapped using a “circular average filter” to avoid jumps due to unwrapping errors

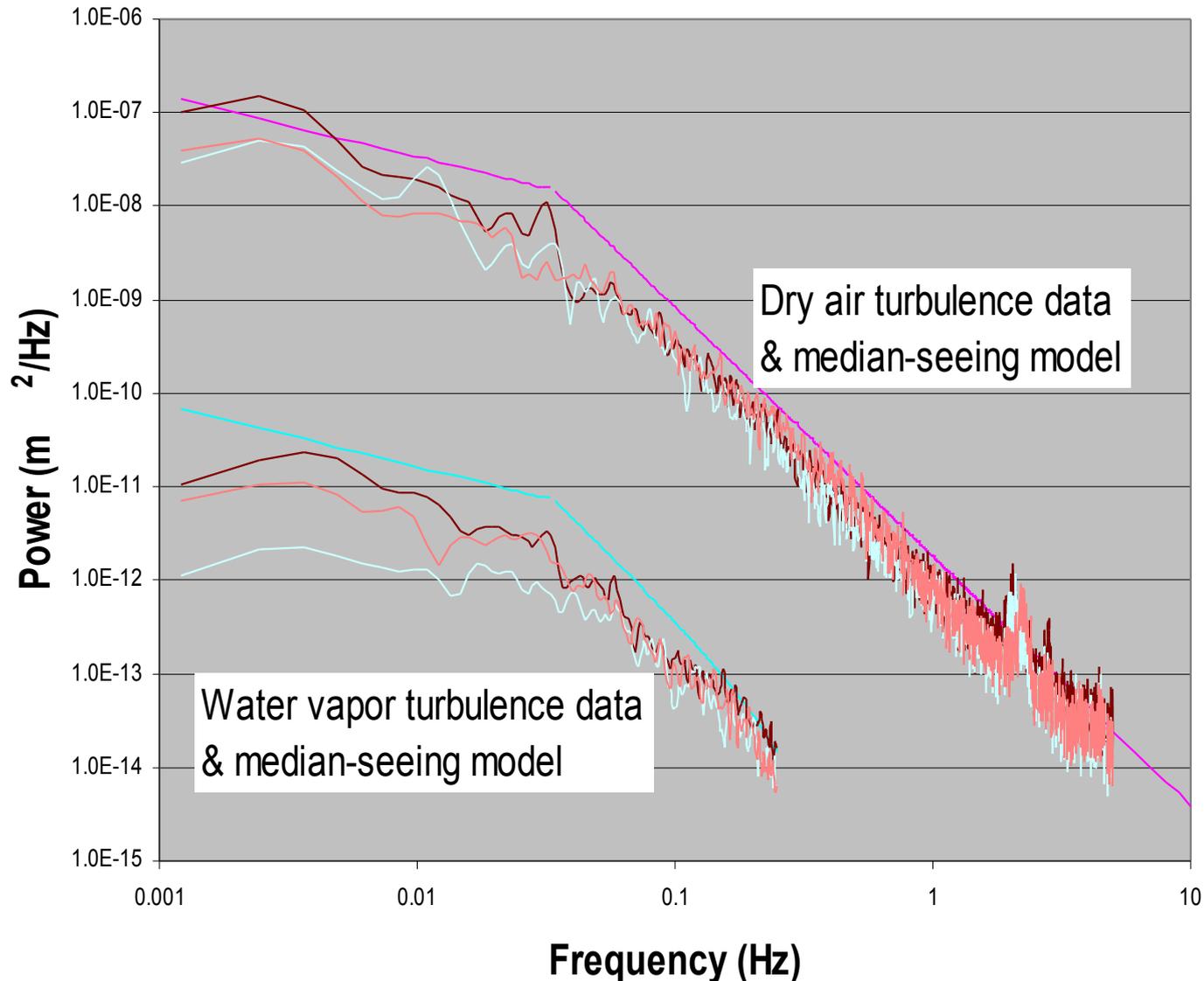
Phase and group delay in the N band were computed from their values in the K band, and the results were compared to the measured N-band values to validate the model

Predicted and Actual N-band Phase and Dispersion



Validation of Atmospheric Turbulence Models with KI Data

Dry-Air and Water-Vapor Power Spectra Data from Dec 2005



Colavita et al. (2004) estimated that the amplitude of the dispersion fluctuations due to H_2O is a small, roughly constant fraction of the “dry-air” phase fluctuations.

The top traces are the measured and model power spectra for the dry-air phase fluctuations.

The bottom traces are the corresponding observed and model power spectra for the dispersion (GD-PD) due to H_2O .

We conclude that the model is essentially consistent with the observations.

Conclusions

The dispersion in the K and N bands is due primarily to H₂O vapor.

- => Use the known refractivity of H₂O to relate the dispersion measured in the K band to the difference between the K-band and N-band OPDs, and to the N-band dispersion
- => Feedforward from the K-band (where SNR is high) to the N-band (where SNR is low) can improve the phase and group-delay tracking in the N-band

Simultaneous observations of K-band and N-band fringes demonstrate this

Still have a mysterious linear drift between the predicted and actual N-band phase