



Towards a Framework for Modeling Space Systems Architectures

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Topics

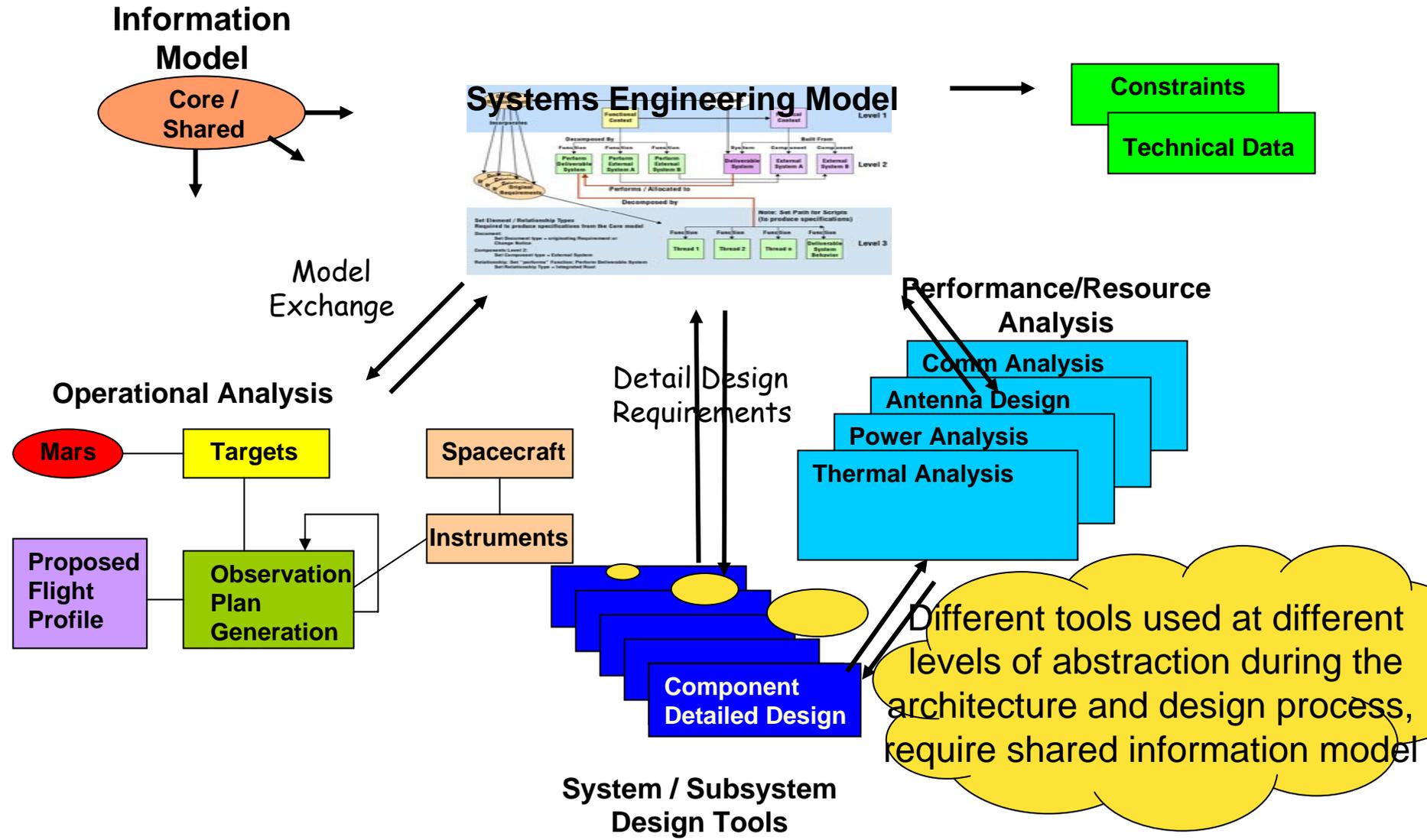
- Statement of the problem
 - Space system architecture is complex
 - Existing terrestrial approaches must be adapted for space
 - Need a common architecture methodology and information model
 - Need appropriate set of viewpoints
- Requirements on a space systems model
- Model Based Engineering and Design (MBED) project
 - Evaluated different methods
 - Adapted and utilized RASDS & RM-ODP
 - Identified useful set of viewpoints
 - Did actual model exchanges among selected subset of tools
- Lessons learned & future vision



Architecting and Engineering Space Systems is Hard

- **Many Stakeholders**
 - Organizations (NASA, international partners, contractors)
 - Competing requirements (cost, schedule, risk, science, technology, survivability, maintainability, buildability)
- **Many different system aspects**
 - Logical (functionality, information, control)
 - Physical (hardware, software, environment) *...motion*
 - Interoperability and cross support
 - Science & operational capabilities
 - Autonomous and human mediate operations
- **Long and complex system (of systems) lifecycle**
 - Development phases
 - Requirements, design, implement, I&T, V&V
 - Operations and sustaining
 - Cradle to grave lifecycle

Integration of Architecture Views through Common Shared Models





System Architecture Model Objectives

- Provide a clear unambiguous views of the design
- Show relationship of design to requirements and driving scenarios
- Separate design concerns in the model to maintain degrees of freedom to do trades
- Detail the model views to the level appropriate for further systems engineering
- Provide executable models of the interactions
- Enable concurrent design of spacecraft, ground systems, science operations, control systems, and components
- Establish system engineering (SE) controls over the allocations and interfaces



Existing System Architecture Methods Inadequate

- Existing methods assume modeled objects are fixed in space and are usually in continuous and instantaneous communication
 - DoDAF, RM-ODP, TOGAF, FEAF, ...
- Space systems tend to violate those assumptions
- Therefore, any of these modeling methodologies must be adapted to describe space systems
- Viewpoints must accommodate complex logical and physical interactions
 - UML, SysML are about design diagrams, do not directly support the needed viewpoints
- Specific engineering discipline modeling tools must be able to interact with core model, and extend it within their own domains



MBED Approach for Developing Architectural Model

- Identify commonalities, overlaps & gaps in different architectural and system engineering methods
- Determine that RM-ODP, and RASDS extensions, are a suitable starting point
- Define needed extensions to RM-ODP & RASDS for modeling space systems, beyond just the data systems elements
 - Physical Viewpoint extensions
 - Engineering and Technical Viewpoints
- Use these model concepts to develop system model and drive information model and tool integration

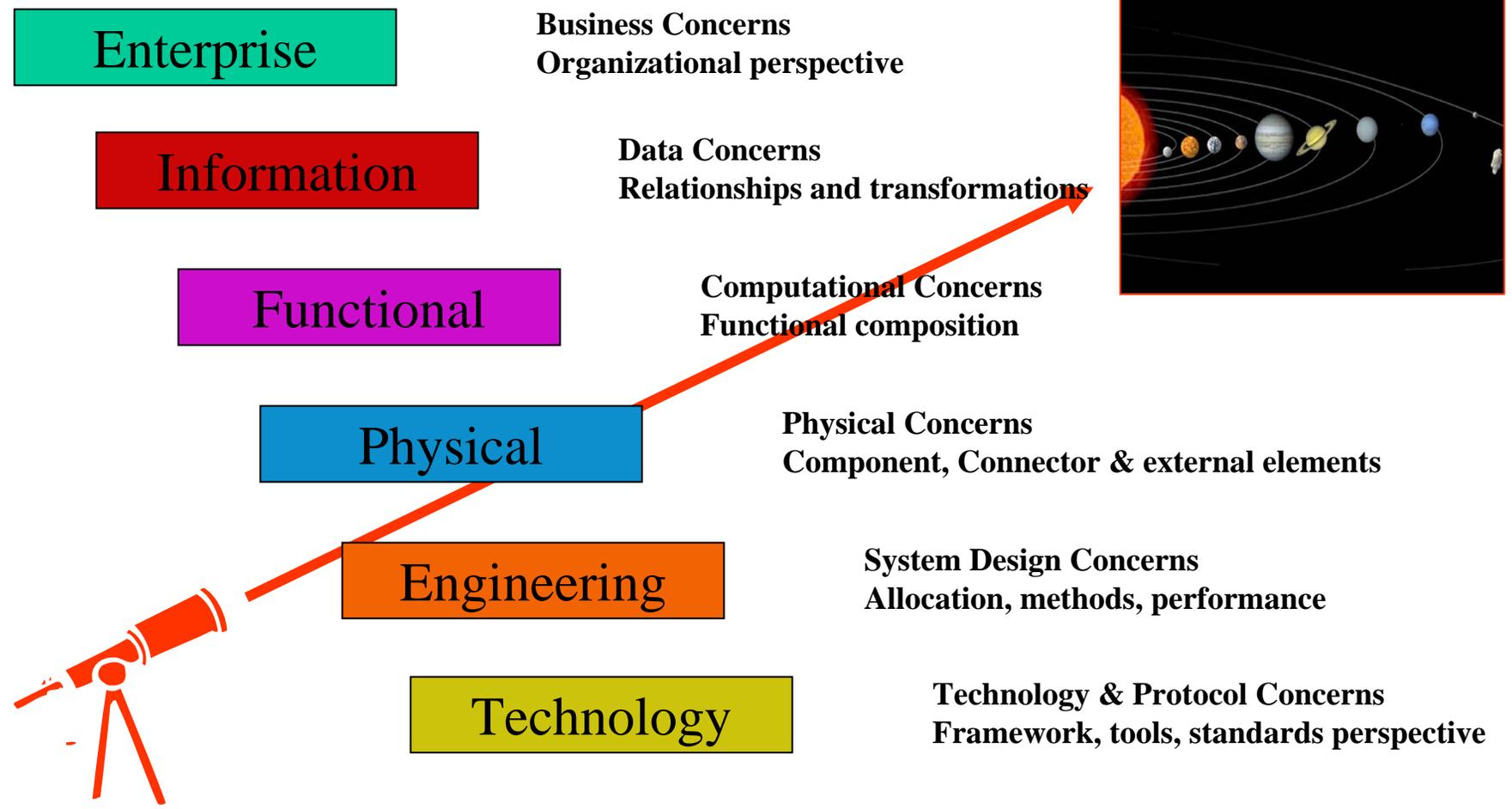


RM-ODP & RASDS Characteristics

- The specification of a complete system in terms of **viewpoints**.
- The use of a **common object model** for the specification of the system from every viewpoint.
- The use of **views** to tailor user or domain specific analyses of the system.
- The definition of a **modeling infrastructure** that provides support services for system applications, hiding the complexity and problems of defining mission specific models.
- The definition of a set of **common transformation functions** that provide general services needed during the design and development of space systems.
- A **framework** for the evaluation of conformance of models and designs based on conformance points.



Extended RASDS Space System Domain Architectural Viewpoints



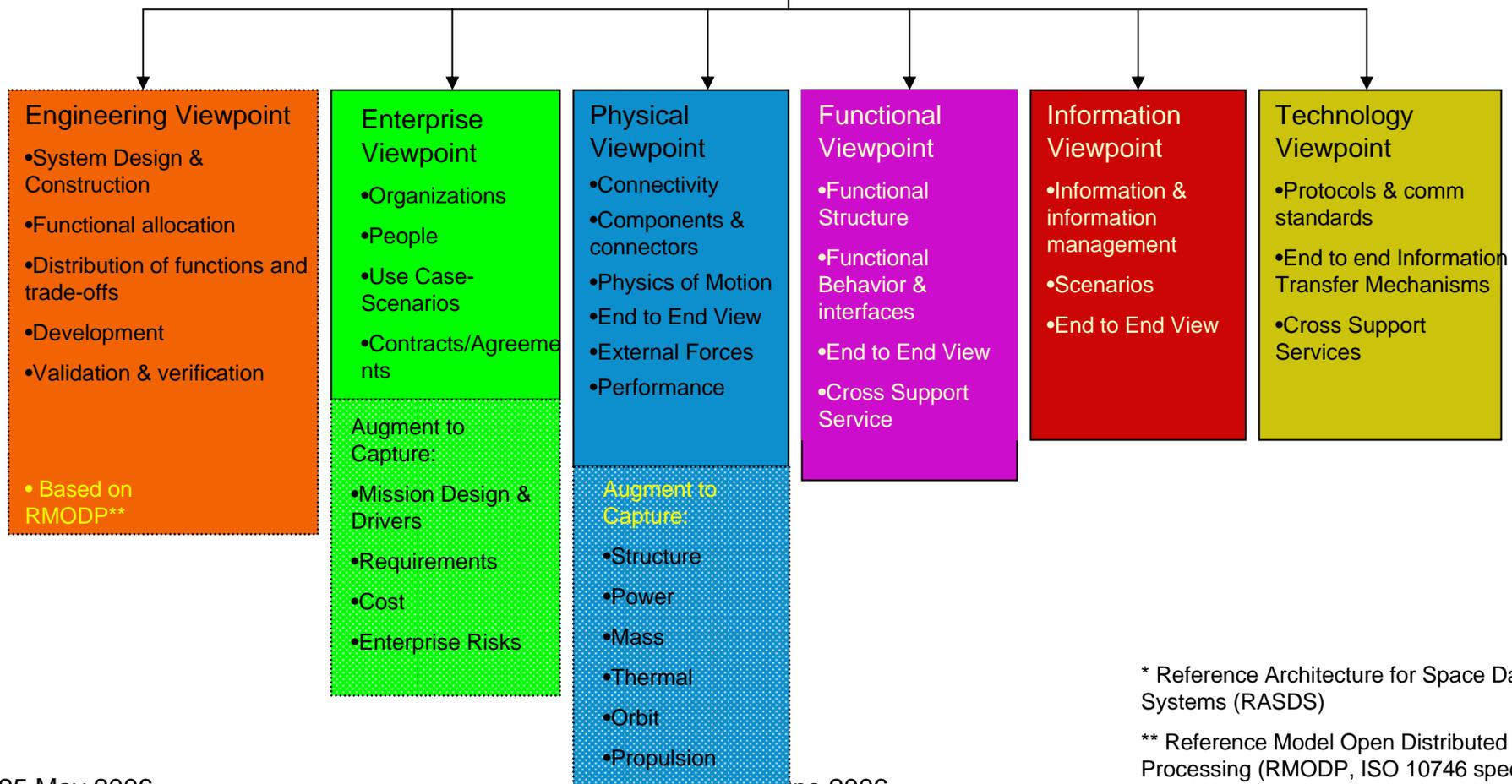
Derived from: CCSDS RASDS, RM-ODP, ISO 10746 and compliant with IEEE 1471



Extended RASDS Semantic Information Model Derivation



RASDS as Architectural Framework *

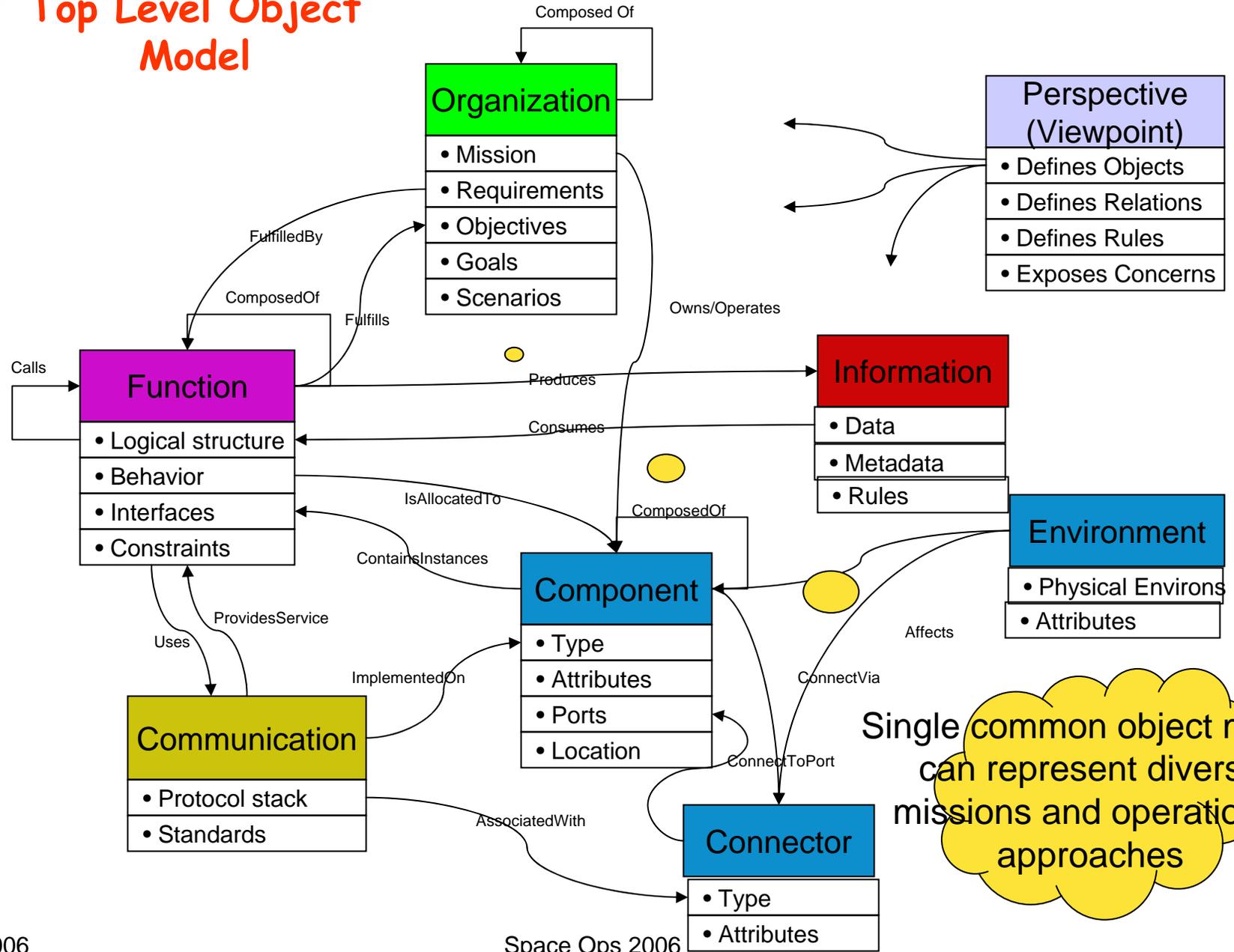


* Reference Architecture for Space Data Systems (RASDS)

** Reference Model Open Distributed Processing (RMODP, ISO 10746 spec)



Extended RASDS Top Level Object Model



Single common object model can represent diverse missions and operational approaches



Viewpoint Elements - Functional Example

- **Stakeholders:** system engineers, acquirers, developers, users, and maintainers
- **Concerns:** the functions that are required for the system to meet its requirements and execute its scenarios
- **Modeling Language:** functional objects and relationships, interfaces, behaviors, constraints
- **Consistency & Completeness Methods:** every requirement maps to at least one function, no requirement is not mapped to a function, no function is not mapped to a requirement, and there is structural data and control flow consistency



Typical Functional Views

- **Functional Dataflow** view – An abstract view that describes the functional elements in the system, their interactions, behavior, provided services, constraints and data flows among them. Defines which functions the system is capable of performing, regardless of how these functions are actually implemented.
- **Functional Control** view – Describes the control flows and interactions among functional elements within the system. Includes overall system control interactions, interactions between control elements and sensor / effector elements and management interactions.



Viewpoint Elements - Physical Example

- **Stakeholders:** system engineers, sub-system engineers, acquirers, developers, operators, users, and maintainers
- **Concerns:** the physical structures of the system, their connections, and how they interact with the environment
- **Modeling Language:** physical objects (components) and their connections, physical behavior, motion and interactions, the environment, constraints
- **Consistency & Completeness Methods:** every functional element maps to at least one physical element, no functional element is not mapped, no physical element is not mapped to a function, and there is structural integrity and consistency



Typical Physical Views

- **Data System** view – Describes instruments, computers, and data storage components, their data system attributes and the communications connectors (busses, networks, point to point links) that are used in the system.
- **Telecomm** view – Describes the telecomm components (antenna, transceiver), their attributes and their connectors (RF or optical links).
- **Navigation** view – Describes the motion of the major elements of the system (trajectory, path, orbit), including their interaction with external elements and forces that are outside of the control of the system, but that must be modeled with it to understand system behavior (planets, asteroids, solar pressure, gravity)
- **Structural** view – Describes the structural components in the system (s/c bus, struts, panels, articulation), their physical attributes and connectors, along with the relevant structural aspects of other components (mass, stiffness, attachment)
- **Thermal** view – Describes the active and passive thermal components in the system (radiators, coolers, vents) and their connectors (physical and free space radiation) and attributes, along with the thermal properties of other components (i.e. instruments as thermal sources (or sinks), antennas or solar panels as sun shade)
- **Power** view – Describes the active and passive power components in the system (solar panels, batteries, RTGs) within the system and their connectors, along with the power properties of other components (data system and propulsion elements as power sinks and structural panels as grounding plane)
- **Propulsion** view – Describes the active and passive propulsion components in the system (thrusters, gyros, motors, wheels) within the system and their connectors, along with the propulsive properties of other components

Physical Views use different subsets of the same physical objects, but are examined from different perspectives and use different attributes



Physical Viewpoint - Component / Connector Examples

- **Data System**
 - Components (CPU, instruments, SSR)
 - Connectors (network, data bus, serial lines, backplane)
- **Telecomm**
 - Components (transmitter, receiver, antenna)
 - Connectors (RF link, optical link, waveguide)
- **Power**
 - Components (solar panel, battery, RTG, switches, power attrib of other components)
 - Connectors (power bus)
- **Thermal**
 - Components (cooler, heater, thermal attrib of other components)
 - Connectors (heat pipe, duct, free space radiation)
- **Structural**
 - Components (S/C bus, physical link, arm, struct attrib of other components)
 - Connectors (joint, bolt (incl explosive), weld)
- **Propulsion**
 - Components (motor, wheel, thruster)
 - Connectors (contact patch, gravity)



Future Modeling Environment

Formal Model of Space Missions

Model of System Engineering

Model of Cost Analysis

Multiple models at several levels of abstraction, used by different tools for different purposes, are integrated into common model

Model of Mission & Scenarios

Model of Engineering Subsystems

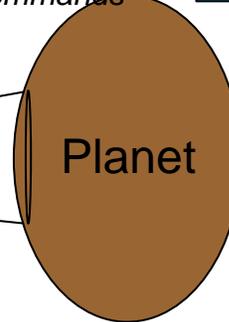
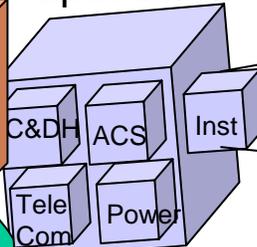
Mission timeline & scenario
Requirements
Science Objectives
Validation criteria
Level 1-2 SE design
Pseudo-Commands

Modeling Tools

Requirements
Science Objectives
Trajectory
Ops validation criteria
Pseudo-Commands

Model of Risk Analysis

Spacecraft



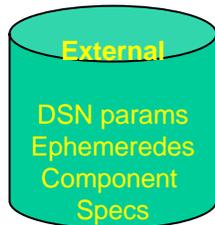
Subsystem SEs



Analysis results
Design updates
Mission Feasibility

Science Scenario Generator (Meemong Lee)

DSN



Observation Scenarios
Operational Feasibility

Requirements
Detailed Design
Trajectory
Mission validation criteria

Subsystem Performance Models (Mark Kordon)



MBED Lessons Learned

- Space system architectures must be described from multiple views to meet different stakeholder concerns
- Existing architectural methods must be adapted to describe space systems
- A variety of tools for system architecture and engineering must be able to produce vendor independent models
- All tools are required to integrate into the common information model
- Tool integration requires an agreed method of information exchange, preferably XML based
- Performing and verifying model interchange is not (yet) a simple task because of semantic and syntactic issues
- System behavioral / performance modeling is not yet within reach and still very much a challenge



Next Steps

- Define extended space system model within a formalized modeling environment
 - Use UML/SysML to develop a “Space System Profile”
 - Can leverage existing UML4ODP and DoDAF profiling efforts
 - Requires real organizational commitment of resources
- Evaluate method on a suitable project
 - Spacecraft or ground data system
 - DSMS / DSN evaluation underway ...



BACKUP



Architecture and Architecting

- **Architecture** - The concepts and rules that define the structure, semantics, behavior, and relationships among the parts of a system, a plan of something to be constructed. It includes the elements (entities) that comprise the thing, the relationships among the elements, the constraints that affect those relationships, a focus on the parts of the thing, and a focus on the thing as a whole.
- **Architecting** - The process of defining, documenting, maintaining, improving, and certifying proper implementation of an architecture. It is both a science and an art.



Architectural descriptions are used for ...

- a) Expression of the system and its evolution
- b) Communication among the system stakeholders
- c) Evaluation and comparison of architectures in a consistent manner
- d) Planning, managing, and executing the activities of system development
- e) Expression of the persistent characteristics and supporting principles of a system to guide acceptable change
- f) Verification of a system implementation's compliance with an architectural description
- g) Recording contributions to the body of knowledge of software-intensive systems architecture



Model Driven Design

- **All Engineering Disciplines are based upon models**
 - And simulators, which are different ...
- **Concepts:**
 - Integrated architectural views of the system(s)
 - Specialty Engineering Disciplines and Models
 - Integrated with Common Models and Data
 - Transformations are done on the models

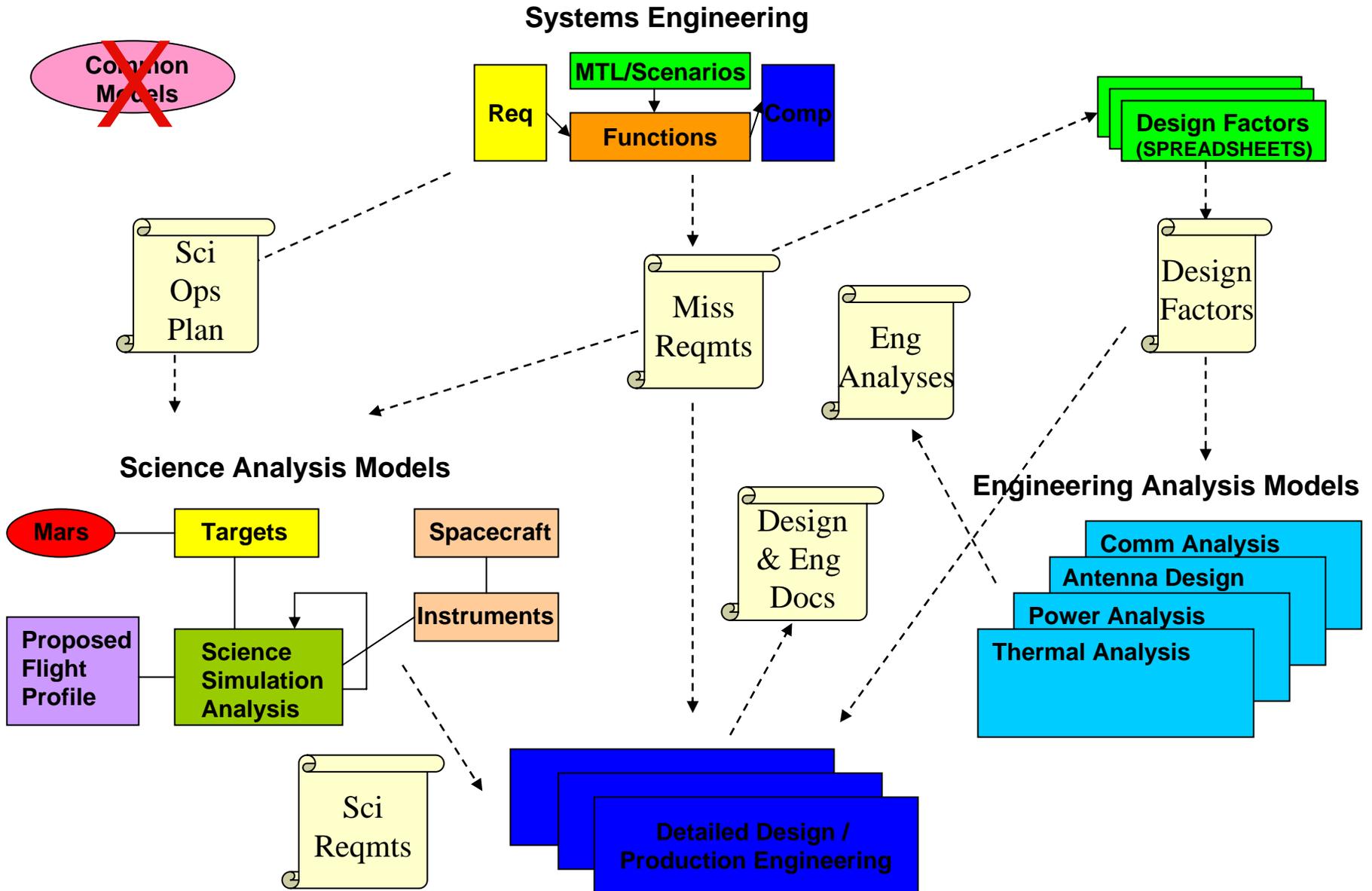


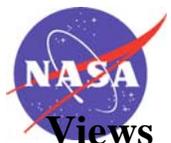
Why Is an Integrated Model Approach Required?

- **Traditional Approach: Document Centric**
 - Requirements in DOORS
 - Components / Functions / Interfaces detailed in various documents and tools
 - Provides little integration, traceability, or integrity assistance between tools and documents
- **Model Driven Approach: Model Centric**
 - Models are constructed according to defined schema
 - Models are checked for completeness, consistency and integrity
 - Documents are produced from the model
 - Insures consistency and traceability between model elements and views

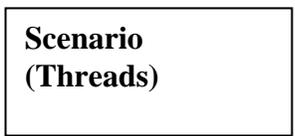
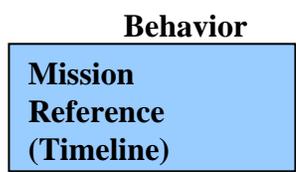
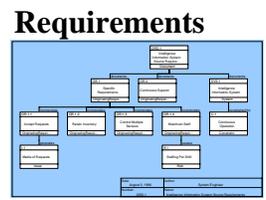


Current Approach: Passing Data as Documents Between Engineering Disciplines

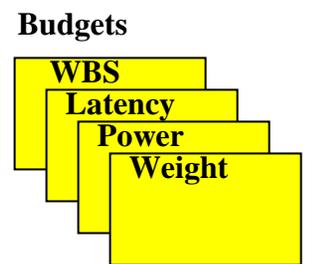
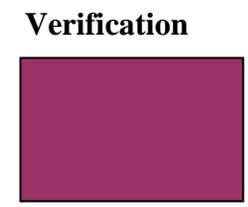
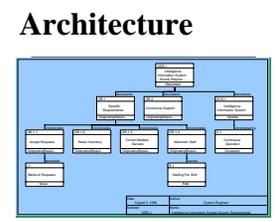




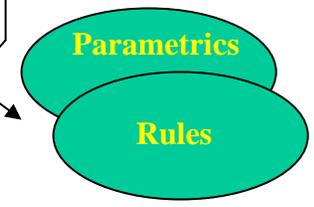
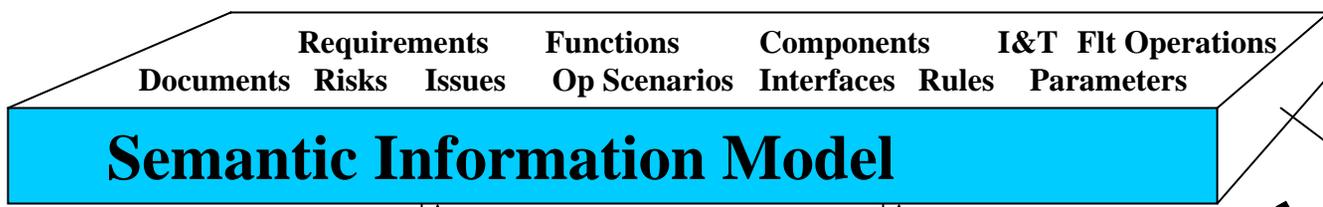
**Views
(projections)**



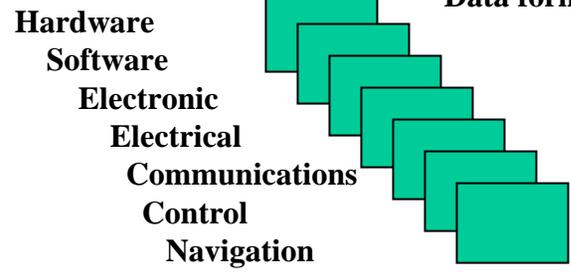
Model Driven Design: The Big Picture



Systems Model



Component Models



Specialty Eng Studies



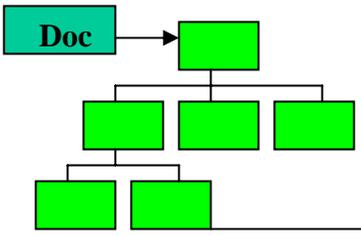
(Map, Tools, post results)

Consistency and Integrity Checks



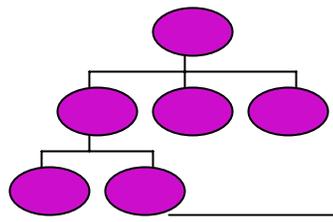
Horizontal Integrity

Requirements Hierarchy



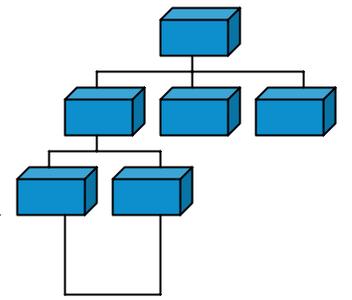
“trace to”

Functional Hierarchy



“allocated to”

Component Hierarchy



Interface

SysML Terms:

Function = Activity Diagrams

Components = Structure

Component Hierarchy is a part of the Product Data Model (Config Mgt and Change Control)

Vertical Integrity

System Level Views:

- Hierarchies
- Enhanced FFBD
- FFBD
- IDEF
- SysML

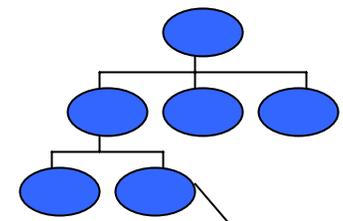
Activity Diagrams
 Sequence Charts
 Class Diagrams

- State Charts

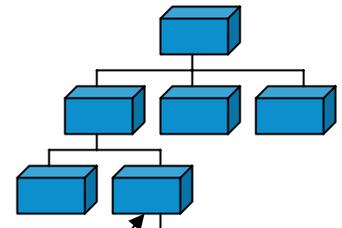
Component Level Views

- CAD Models
- Mentor Graphics Models
- Rational Rose Models
- SOAP Models
- STK Models
- MATLAB Models
- Gadget Models (spreadsheets)

Functional Architecture



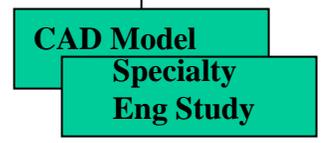
Component Architecture



"allocated to"

Notes:

- Component Architecture part of PDM
- Component Model "maps" to component level models





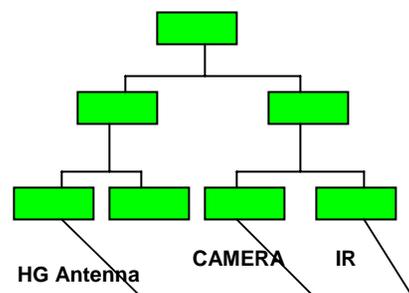
Integration of Three Different Models at Different Levels of Abstraction

- **Systems Engineering Models**
 - Integrity of systems and components at a high level
 - Establish Interface controls
 - Produce gate documents
- **Science Operations Models**
 - Integrity of orbits, footprints, and time (orient spacecraft and instruments)
 - Integrity of data capture, throughput, compression, and data override algorithms
- **Detailed Design Models**
 - Insure consistency and integrity of design factors



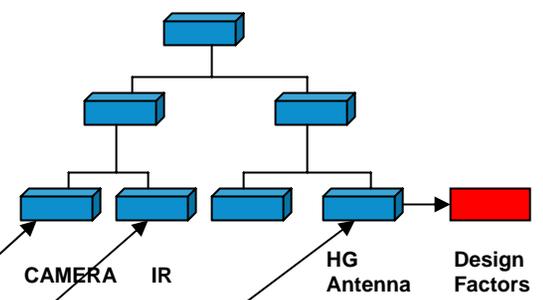
Odyssey SE Model

Requirement Hierarchy

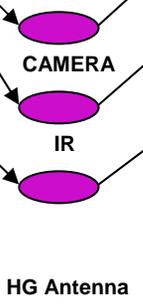


Scenarios (Executable)

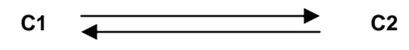
Component Hierarchy



Functions (Intrinsic)



Interfaces (Connects Components)



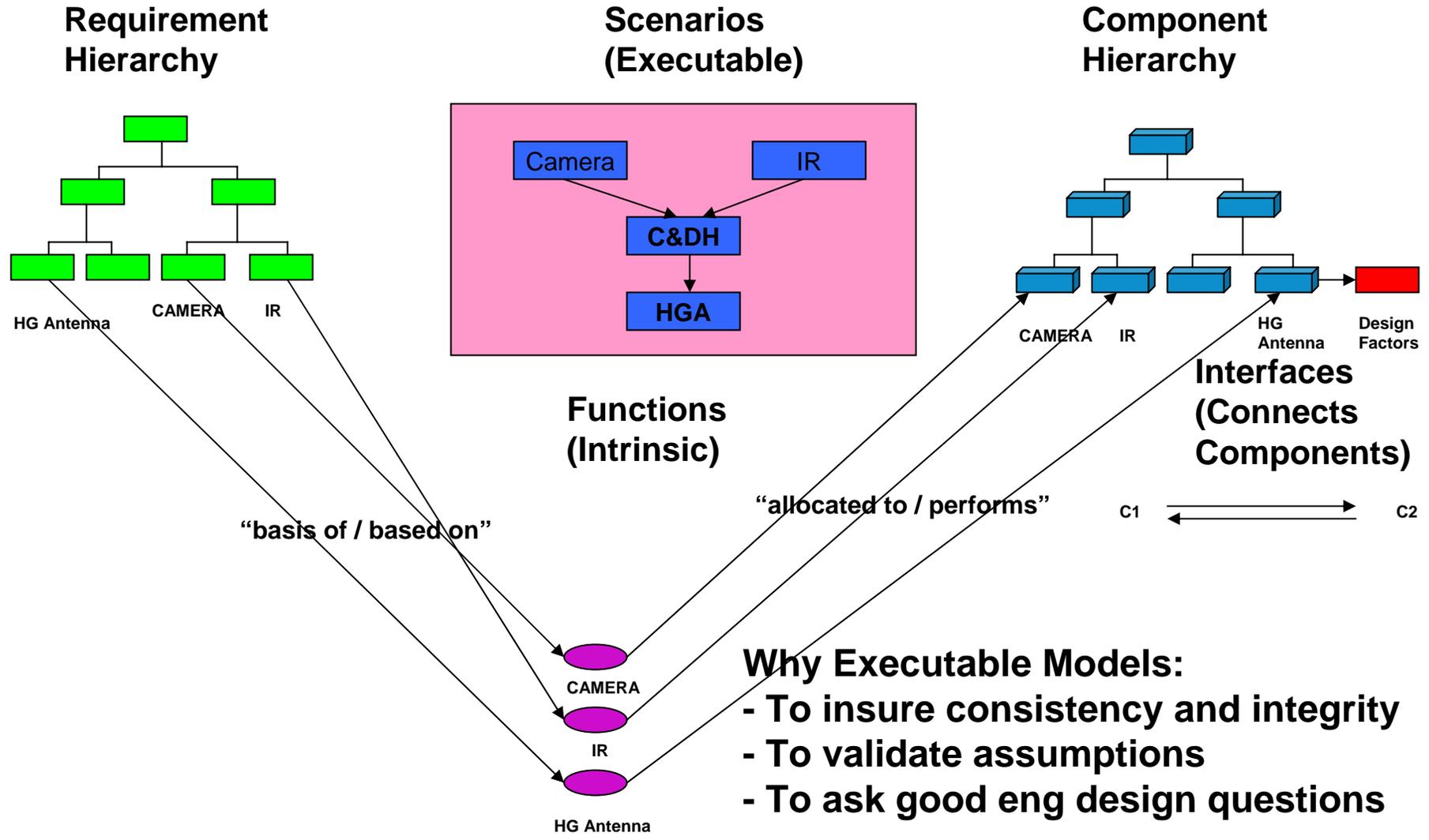
“basis of / based on”

“allocated to / performs”

SE Tools:

- Classes / Attributes / Relationships
- User extensible schema
- Stores data and schema in XML Format
- Data is accessible to other programs

Odyssey Executable Scenarios



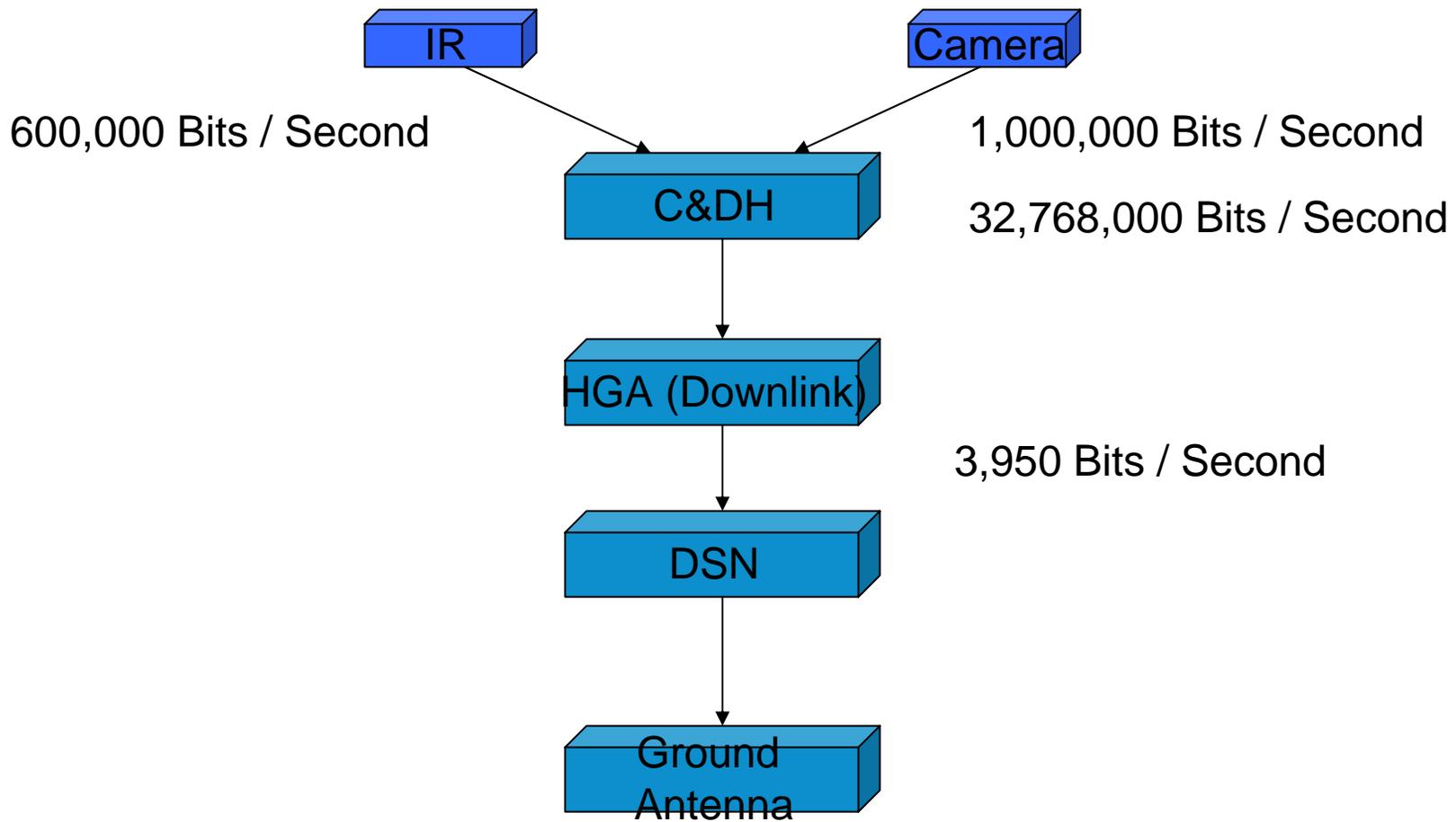
- Why Executable Models:**
- To insure consistency and integrity
 - To validate assumptions
 - To ask good eng design questions



Scenario 1: Focus Upon Interfaces

- Science Instruments
 - IR - compressed: 0.6 Mega Bits/Sec (600000)
 - Camera - compressed: 1 Mega Bits/Sec (1000000)
- C&DH Computer
 - Buffer Size
 - Non volatile Memory: 409,600,000 bytes
 - Volatile: 4,096,000 bytes
- HG Antenna
 - Data Throughput (min): 3,950 Bits / Sec
- Key Point:
 - Simulation lets us ask detailed engineering questions

Graphic Representation of Interfaces

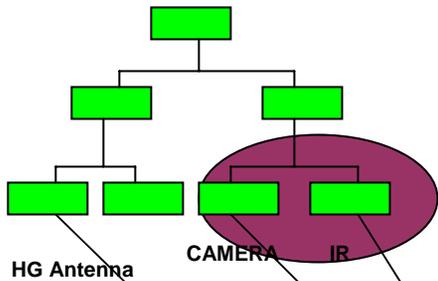




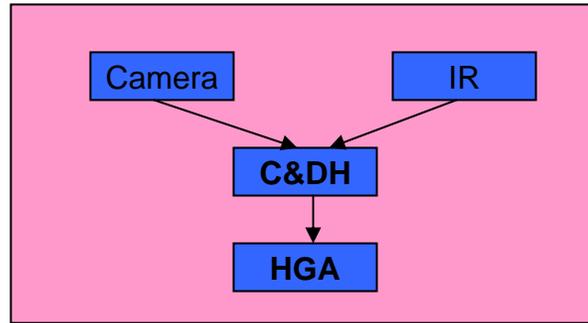
SE Models: Concurrent Development with

(1) Science Operations and (2) Component Models

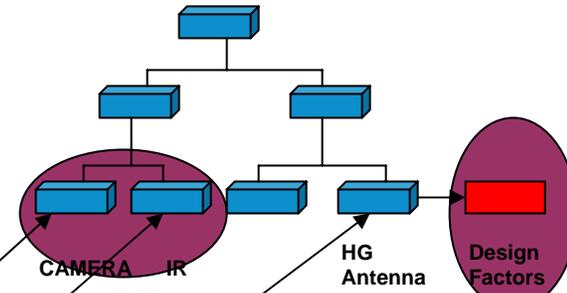
Requirement Hierarchy



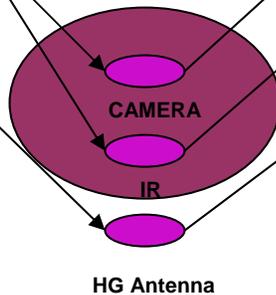
Scenarios (Executable)



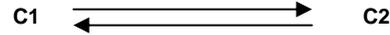
Component Hierarchy



Functions (Intrinsic)



Interfaces (Connects Components)



“basis of / based on”

“allocated to / performs”

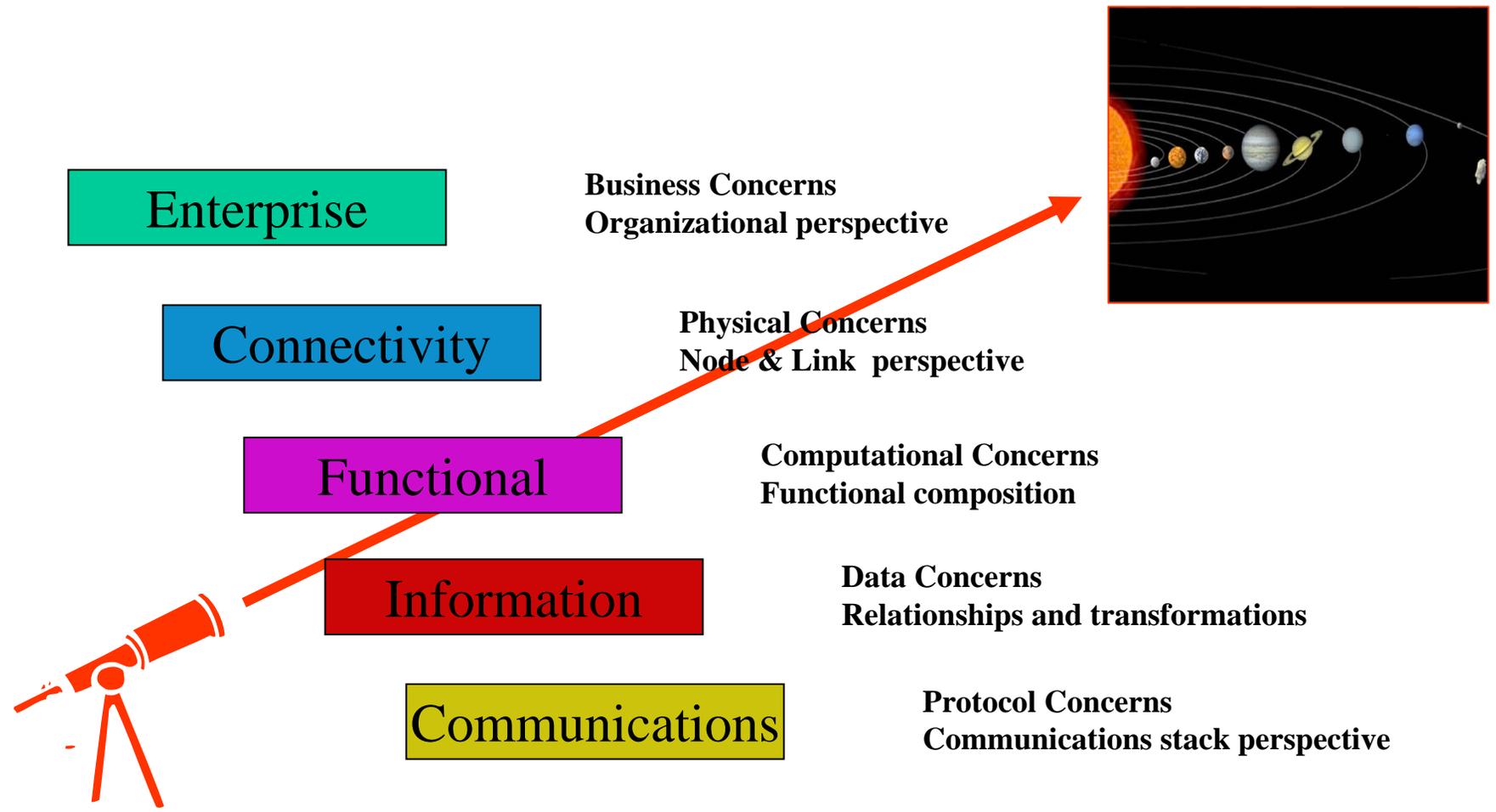
To Science Ops
For Concurrent
Develop of
Instruments and
Spacecraft
(style sheets)

To MM Models
For Validation of
Design Factors

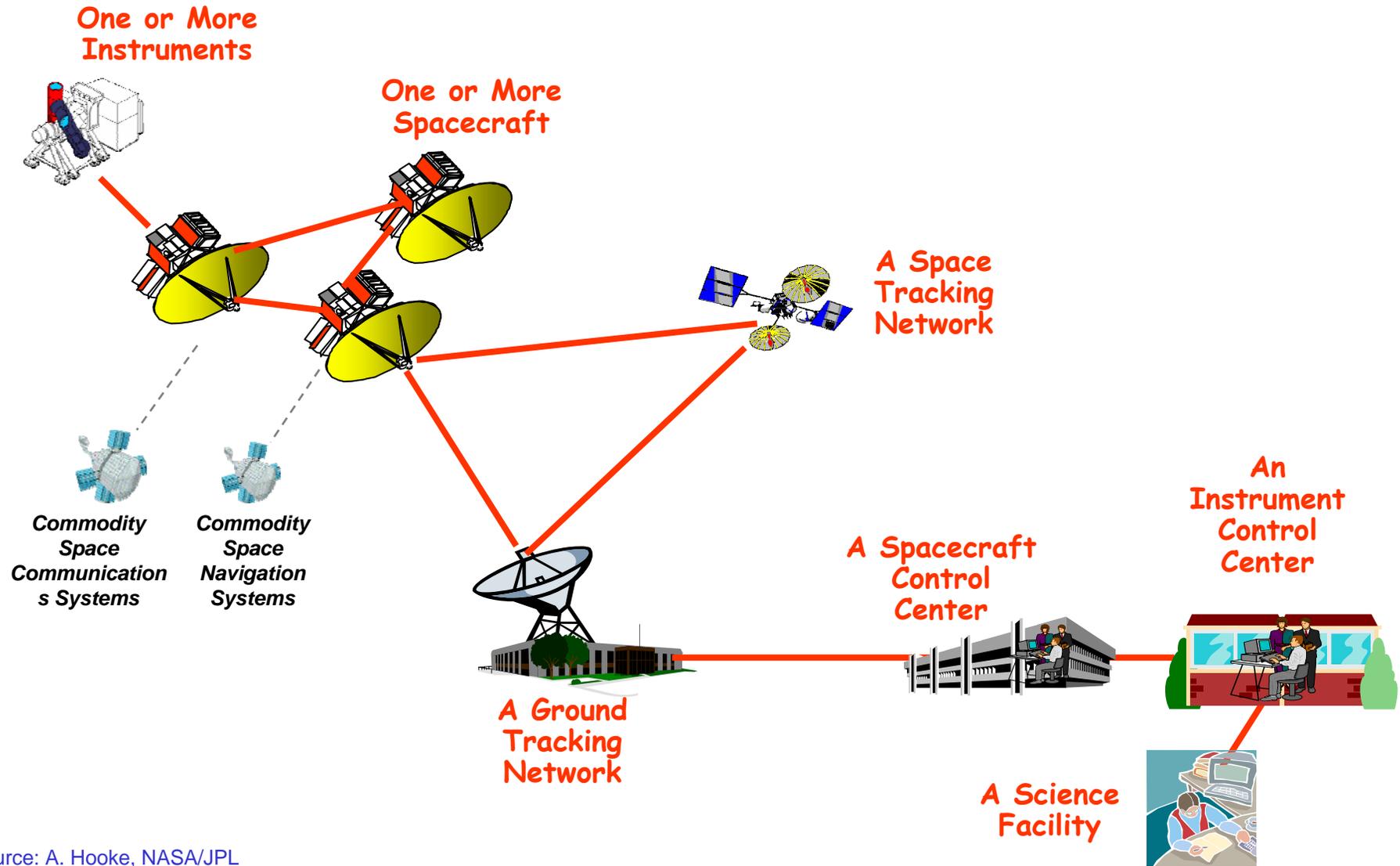




RASDS Space Data System Architectural Viewpoints

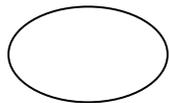


A Physical View of a Space Data System

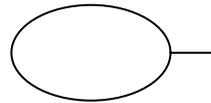


Source: A. Hooke, NASA/JPL

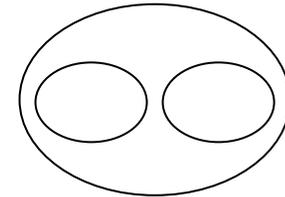
Space Data System Architectural Notation



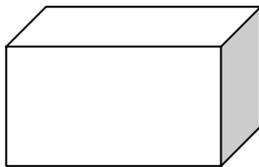
Object



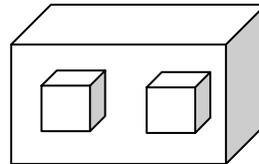
Object with Interface



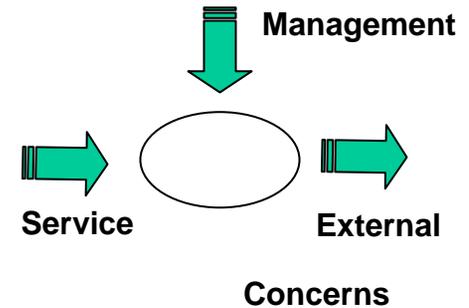
Object Encapsulation



**Node
(physical location)**



**Node Encapsulation
(physical aggregation)**



Logical Link



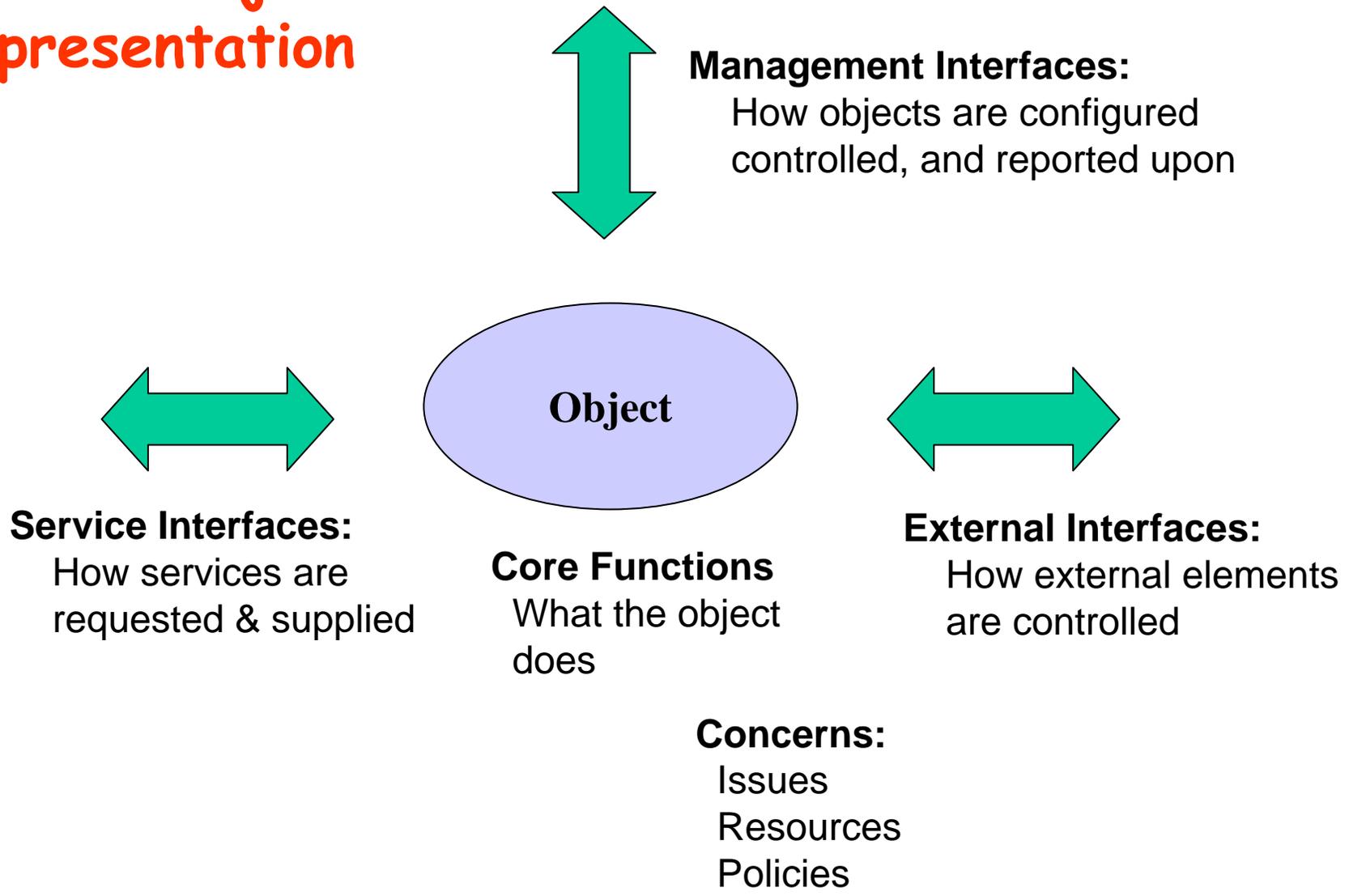
Physical Link



**Space Link
(rf or optical)**



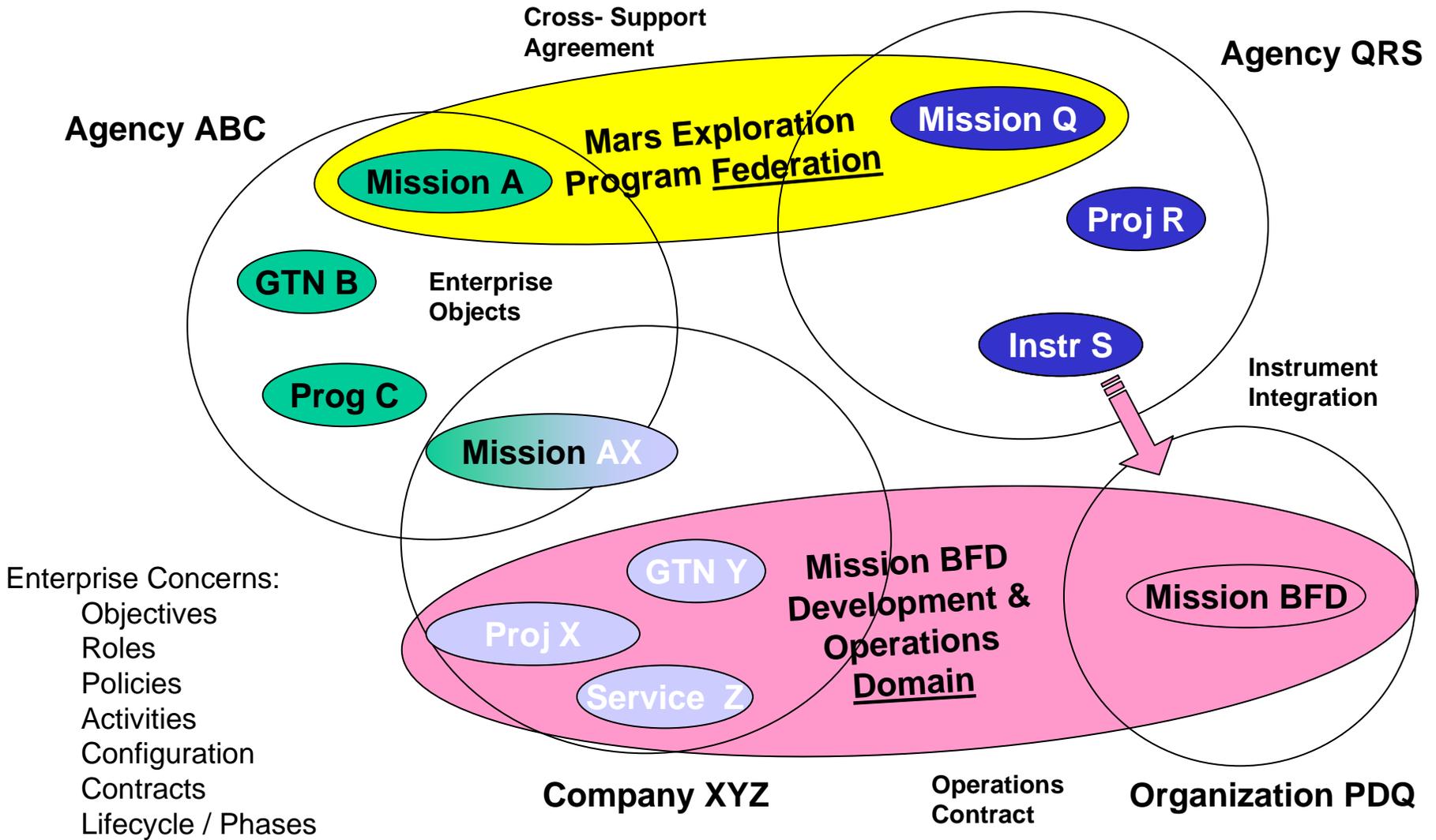
Unified Object Representation





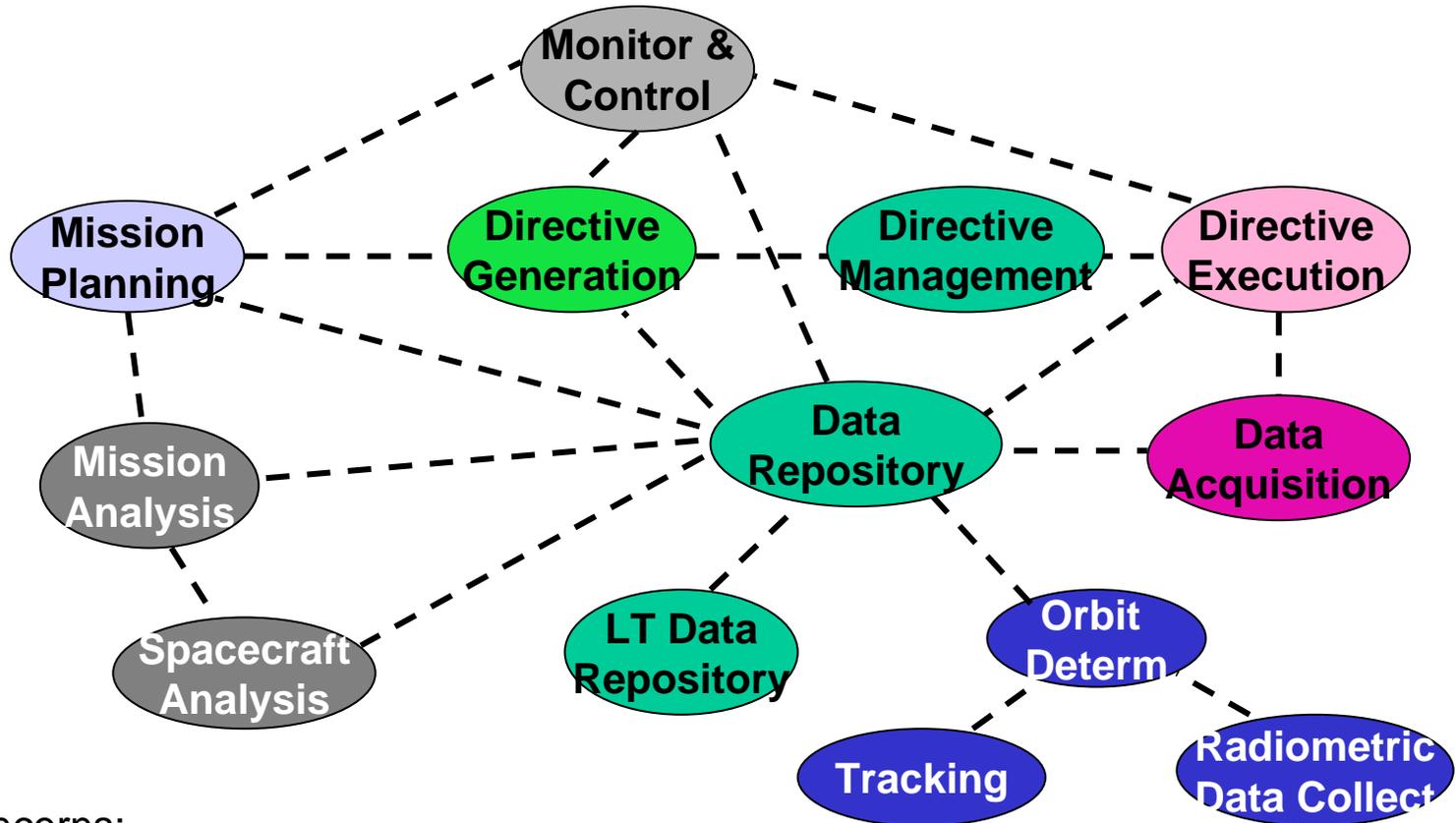
Enterprise View

Federated Enterprises with Enterprise Objects



Functional View

Example Functional Objects & Interactions

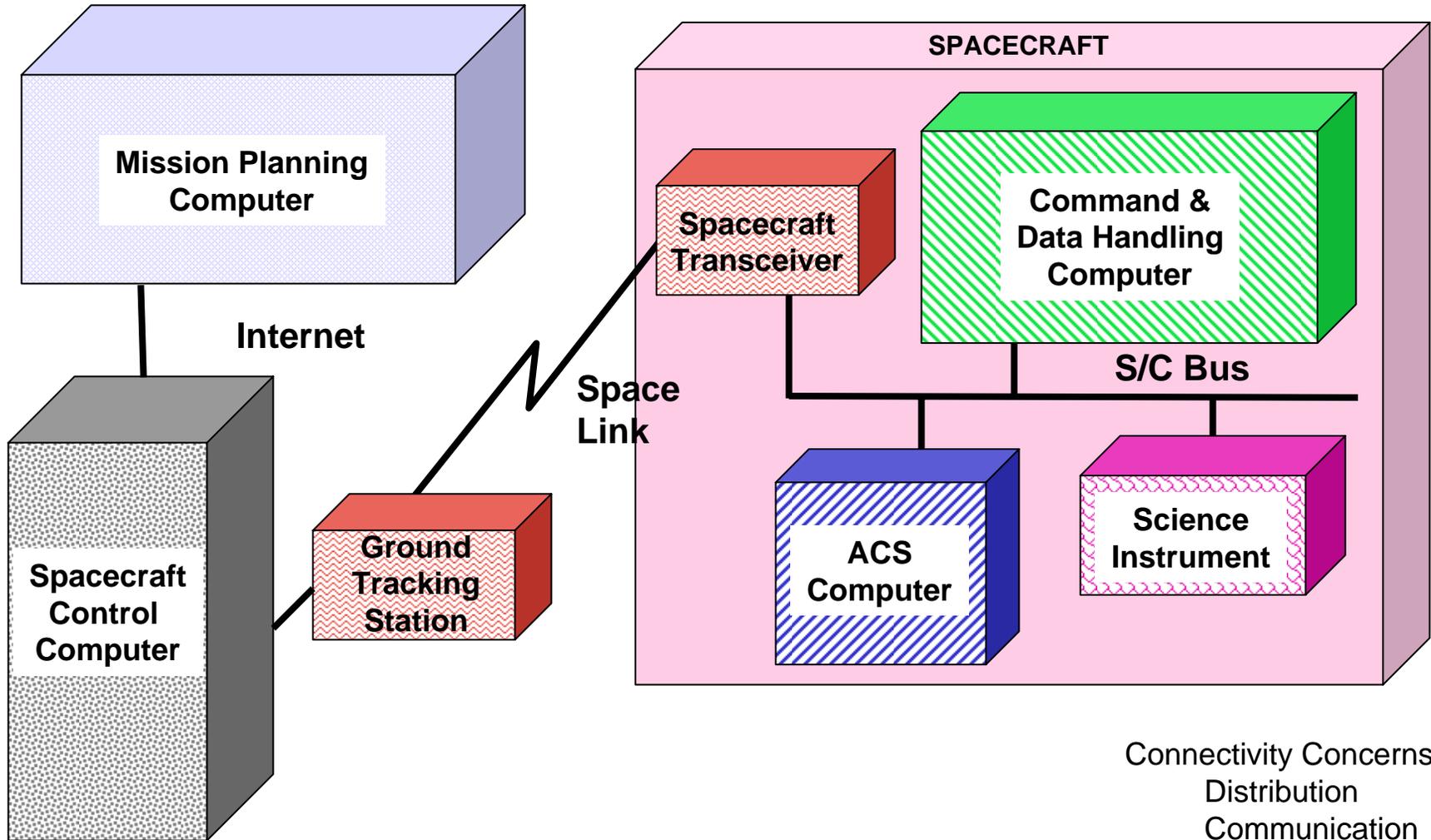


Functional Concerns:

- Behaviors
- Interactions
- Interfaces
- Constraints



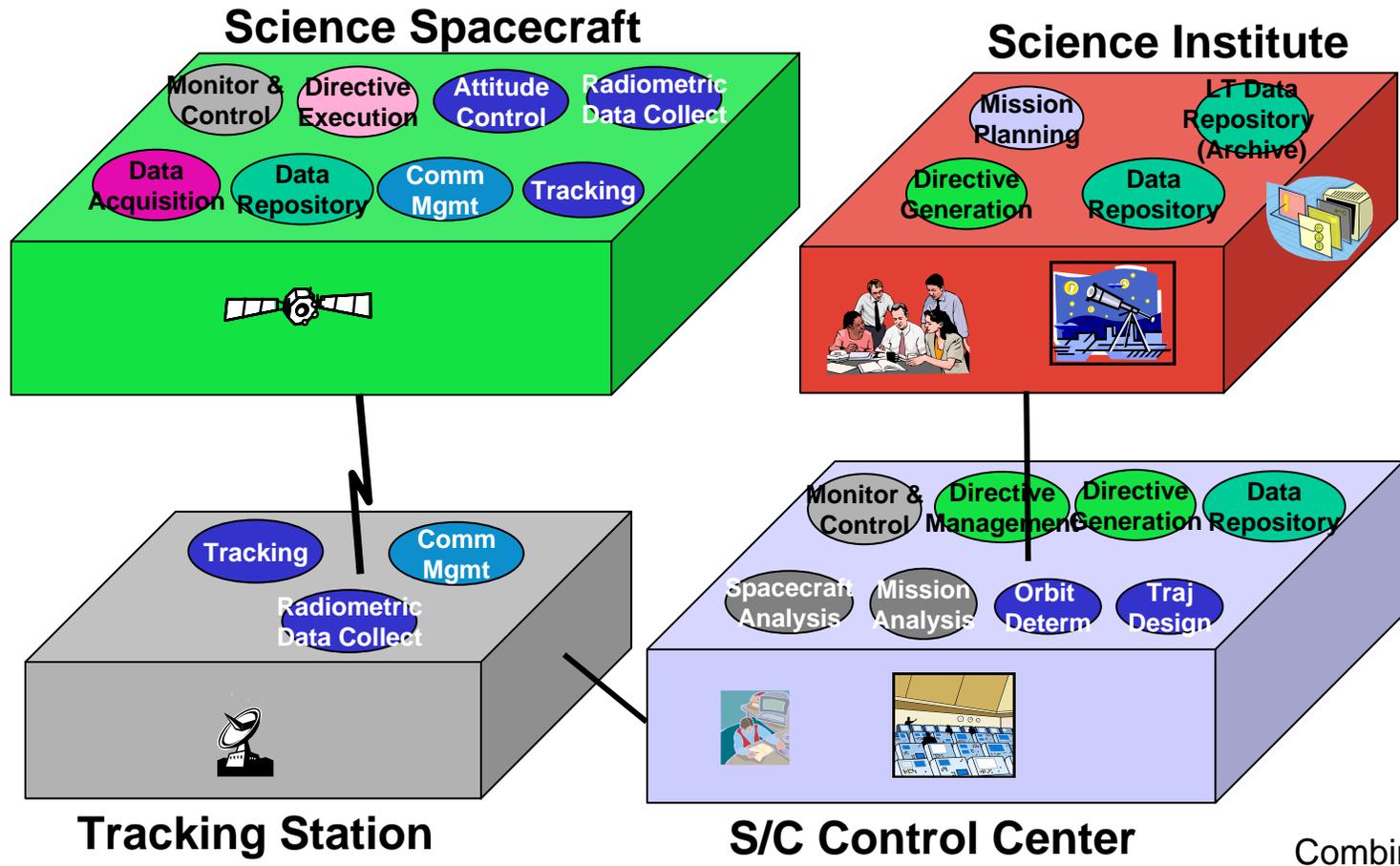
Connectivity View Nodes & Links



- Connectivity Concerns:
- Distribution
 - Communication
 - Physical Environment
 - Behaviors
 - Constraints
 - Configuration

Connectivity View

Mapping Functional Elements to Nodes



Combined View:
 End to End Behavior
 Performance
 Throughput
 Trade studies



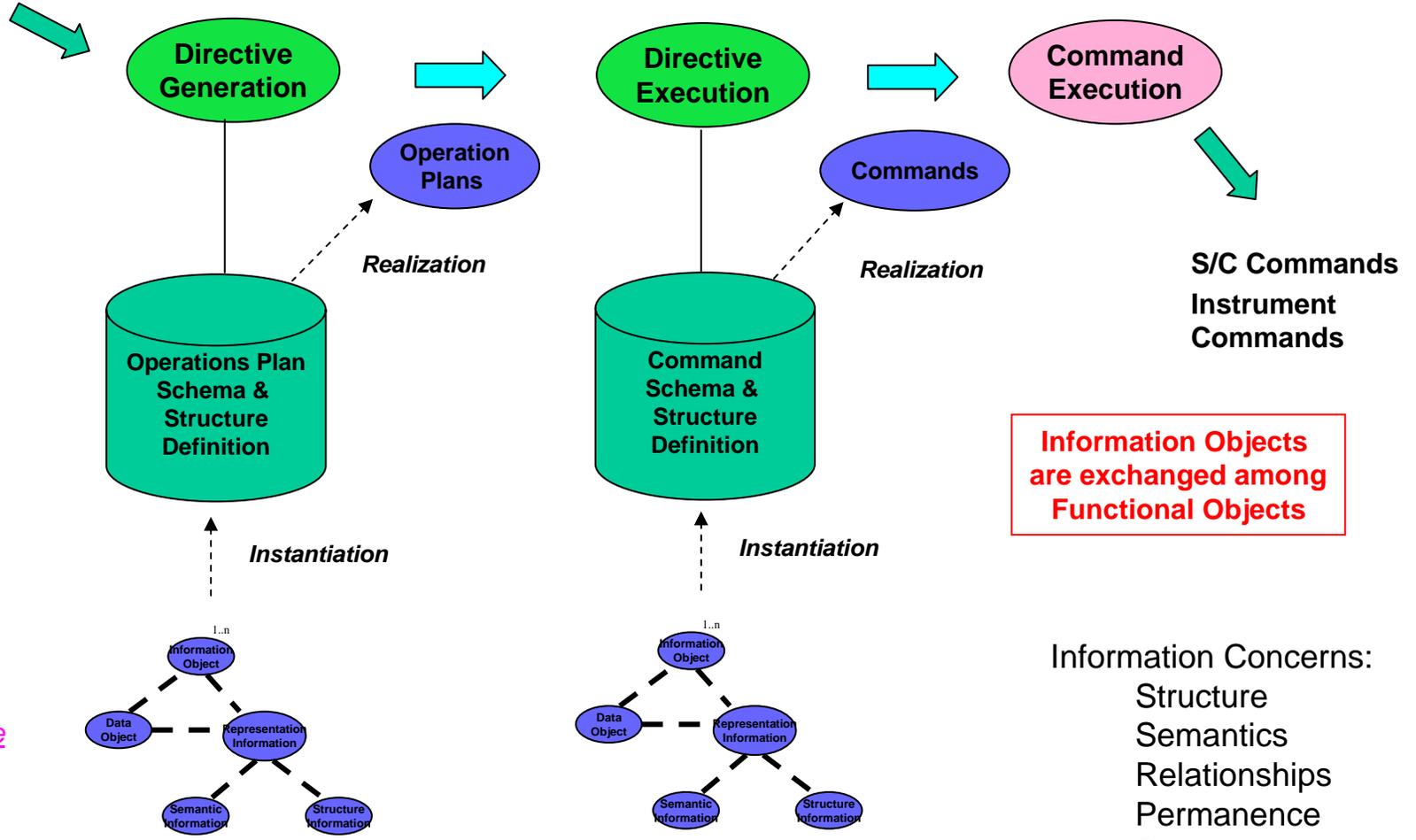
Information Objects Relationship to Functional View

S/C Event Plans
Observation Plans

Actual Data Objects

Data Models

Abstract Data Architecture Meta-models

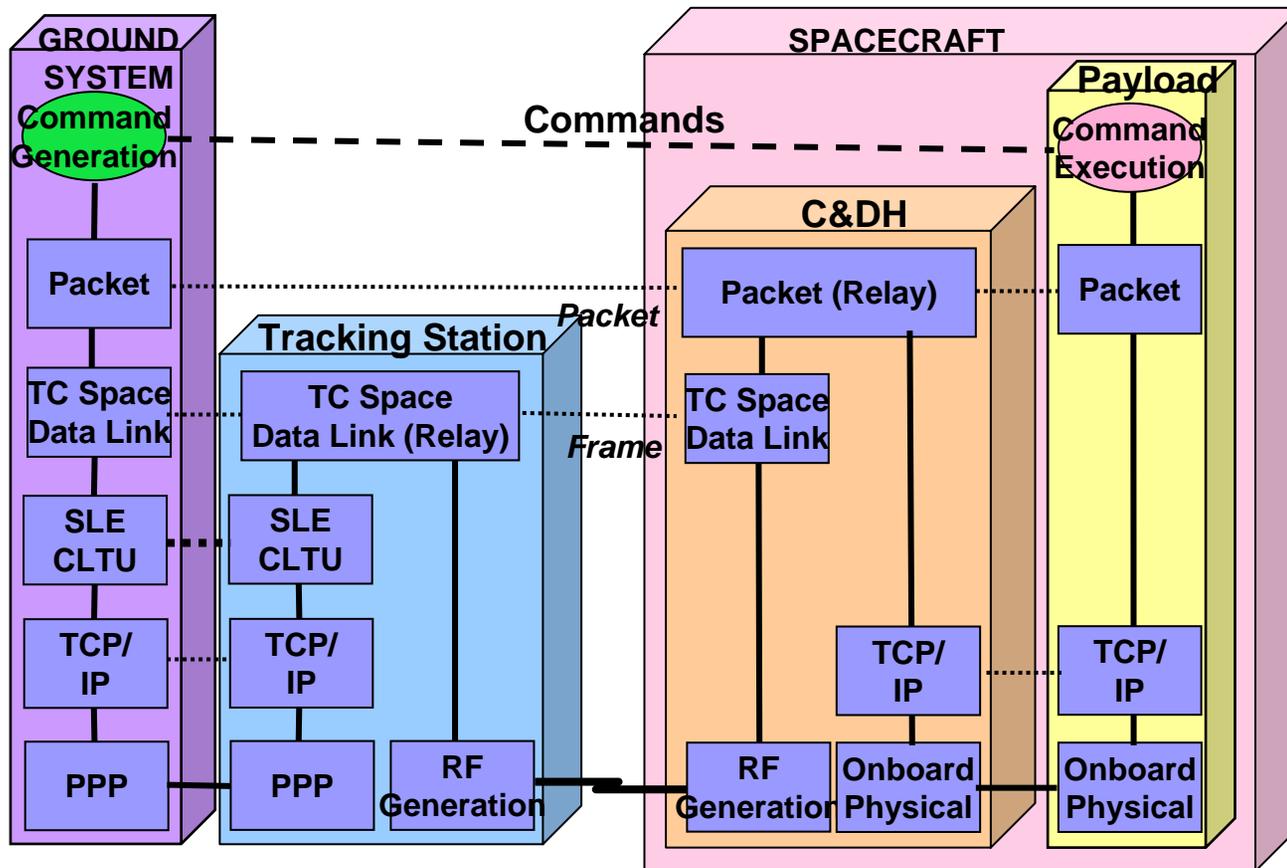


Information Objects are exchanged among Functional Objects

- Information Concerns:
- Structure
 - Semantics
 - Relationships
 - Permanence
 - Rules



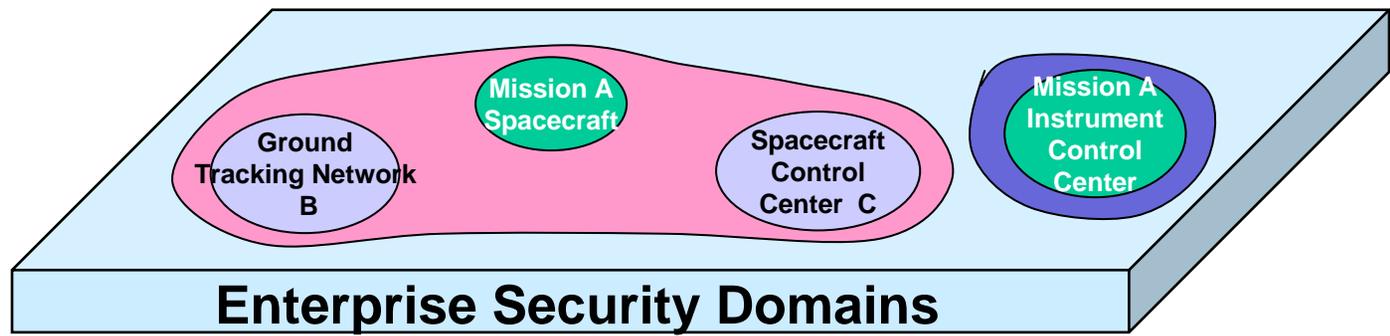
Communications Viewpoint Protocol Objects End-To-End Command Processing



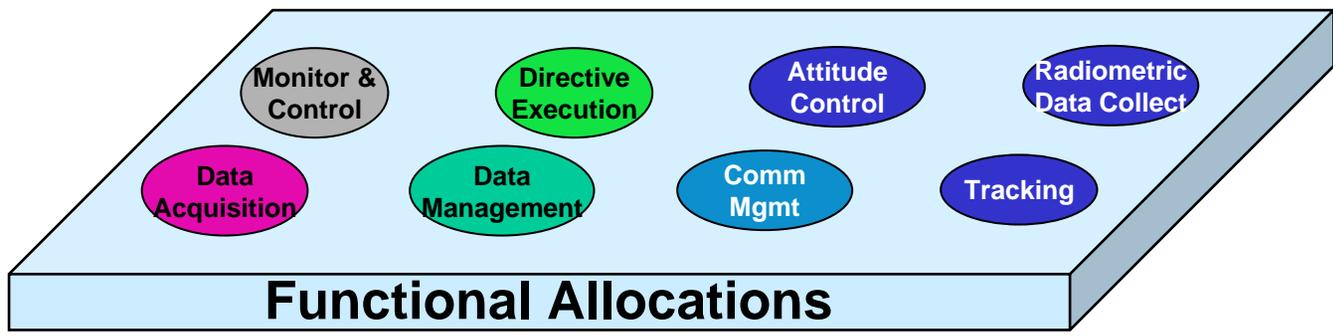
- Communications Concerns:
- Standards
 - Interfaces
 - Protocols
 - Technology
 - Interoperability
 - Suitability



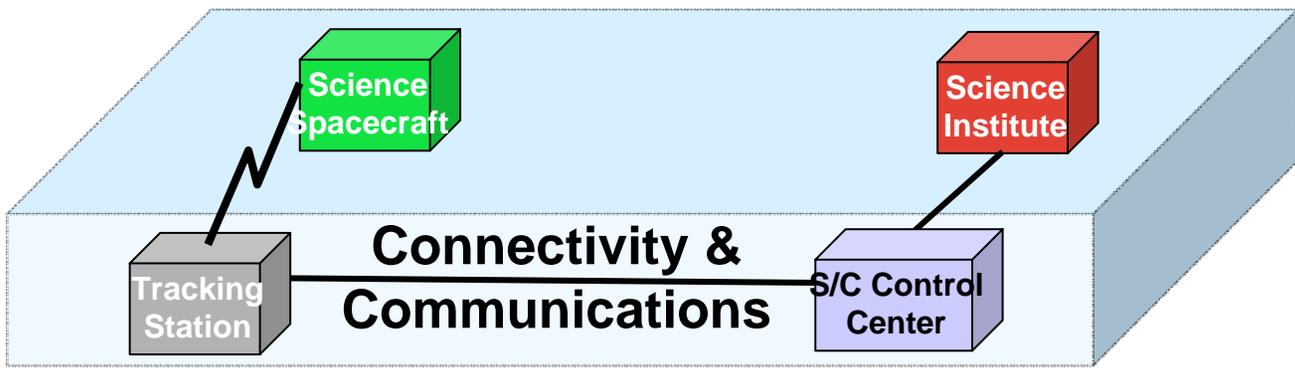
Security Analyses Multiple Viewpoints & Relationships



*Trust relationships
Policies
Privacy / proprietary issues*



*Access control
Authentication*



*Firewalls
Encryption
Boundary access points*

Combined View:
Relationships
Allocations
Performance
Trade studies