

Design considerations and validation of the MSTAR absolute metrology system

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Sponsor: NASA Cross-Enterprise Technology Development Program - Distributed Spacecraft



Outline

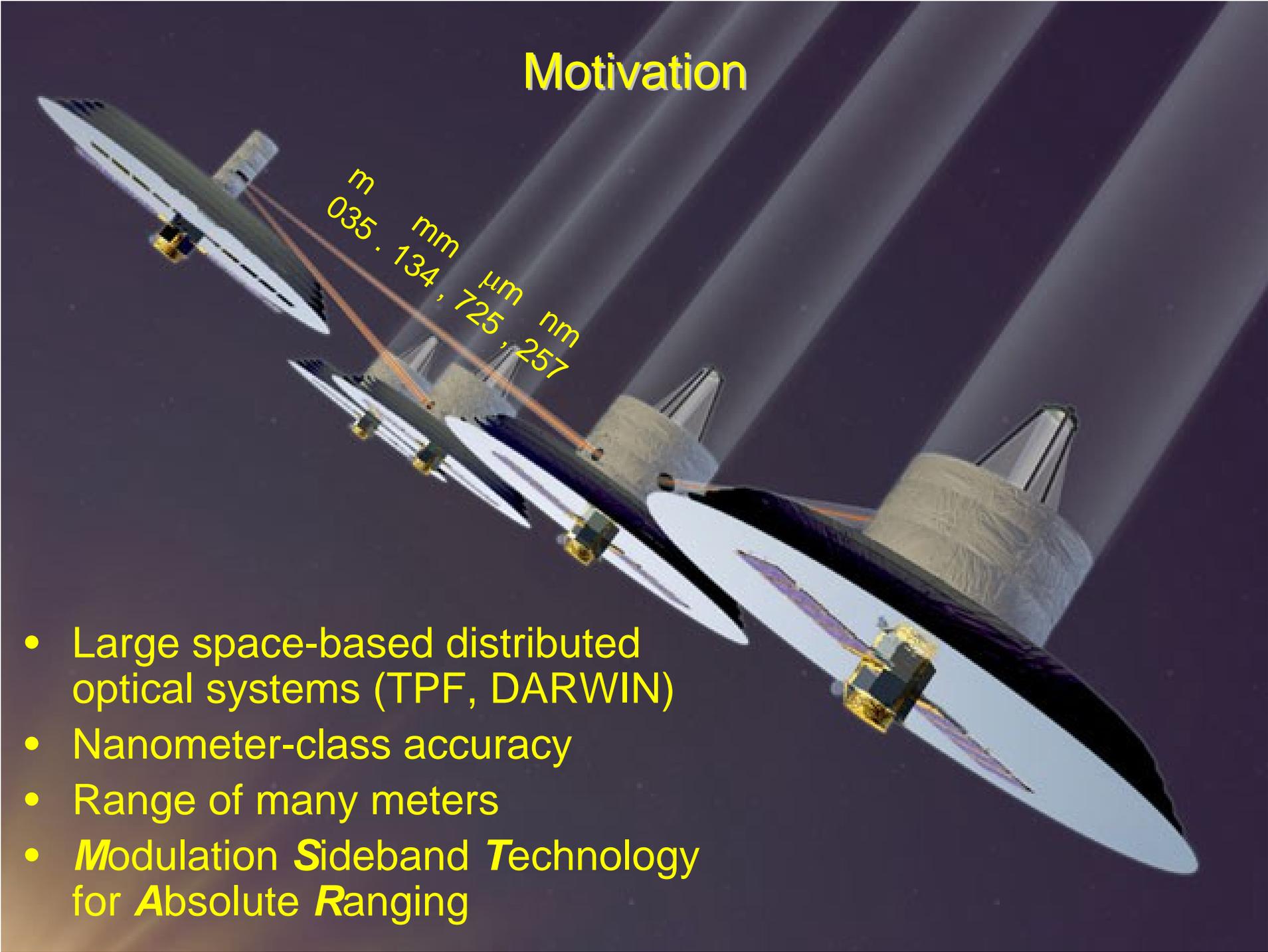


-
- **Motivation**
 - **Theory**
 - **Validation**
 - **Design considerations**
 - **Summary**

Motivation

m
035 . 134 , 725 , 257

mm
μm
nm



- Large space-based distributed optical systems (TPF, DARWIN)
- Nanometer-class accuracy
- Range of many meters
- **Modulation Sideband Technology** for **Absolute Ranging**

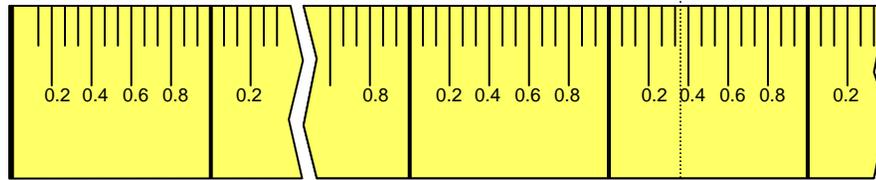


Main Technology Issue



before MSTAR

- Fine scale:
 - precise (nm)
 - but ambiguous

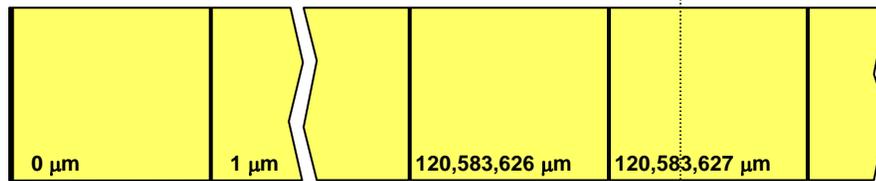


laser interferometer

???,???,???.351 μm



- Coarse scale:
 - 10 μm ranging accuracy (1σ)



time-of-flight or RF mod rangers

120,583,6???.??? μm



120,583,6???.351 μm

useless

- The 10 μm ranging accuracy of the existing coarse scale gauges is not sufficient to resolve the ambiguity of the existing fine scale gauges

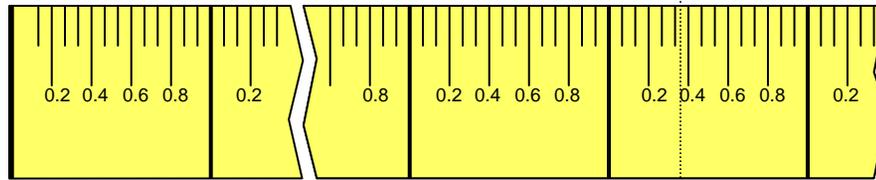


Main Technology Issue



with **MSTAR**

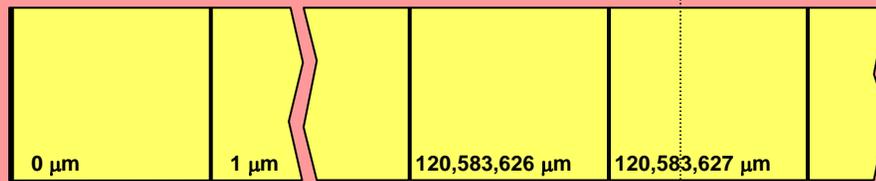
- **Fine scale:**
 - precise (nm)
 - but ambiguous



???,???,???.351 μm



- **Coarse scale:**
 - 0.1 μm ranging accuracy (1σ)



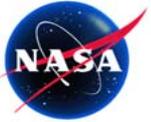
120,583,627.3?? μm



- **MSTAR:** -integrated sensor, -nm accuracy, -no ambiguity

120,583,627.351 μm

- The 0.1 μm **MSTAR coarse stage ranging accuracy** is sufficient to resolve the ambiguity of the built-in fine scale gauge



MSTAR architecture



- Existing techniques

- 2-color Interferometry (e.g. SIM)

- Using two or more lasers
- Performance limited by laser frequency stability and tuning range

- RF modulation (e.g. GEOSAR)

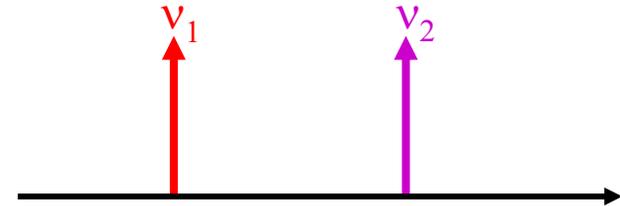
- Requires high-frequency modulation, detection and processing
- Performance limited by low sensitivity of high frequency detectors and electronics

- *MSTAR* is a hybrid

- Implements **2-color interferometry** with RF phase modulation of a **single laser**

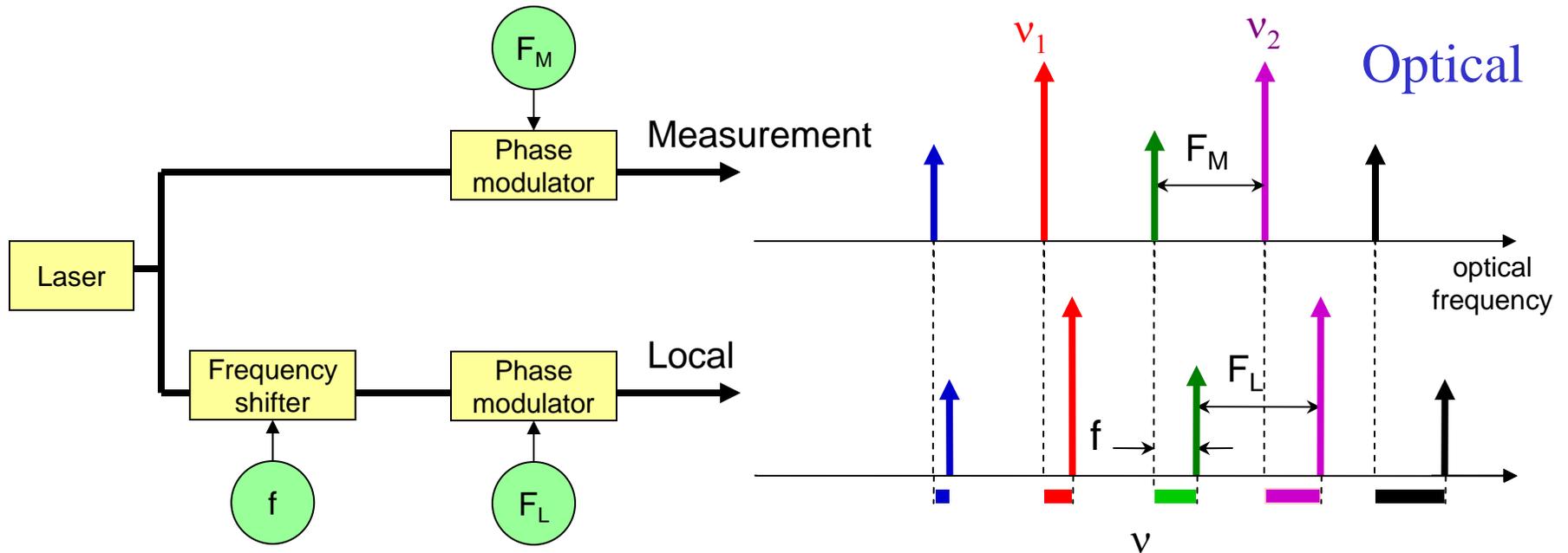
- Heterodyne detection does not require high-frequency detectors and processing

- Enabled our novel architecture and by availability of high-frequency phase modulators

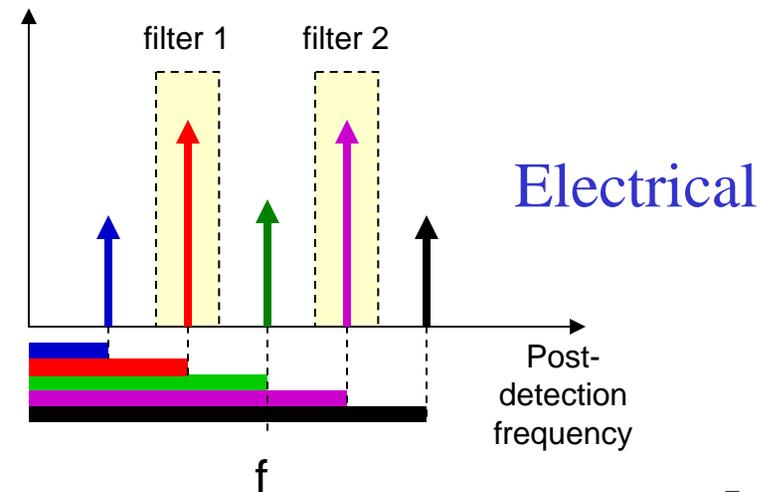




Modulation scheme

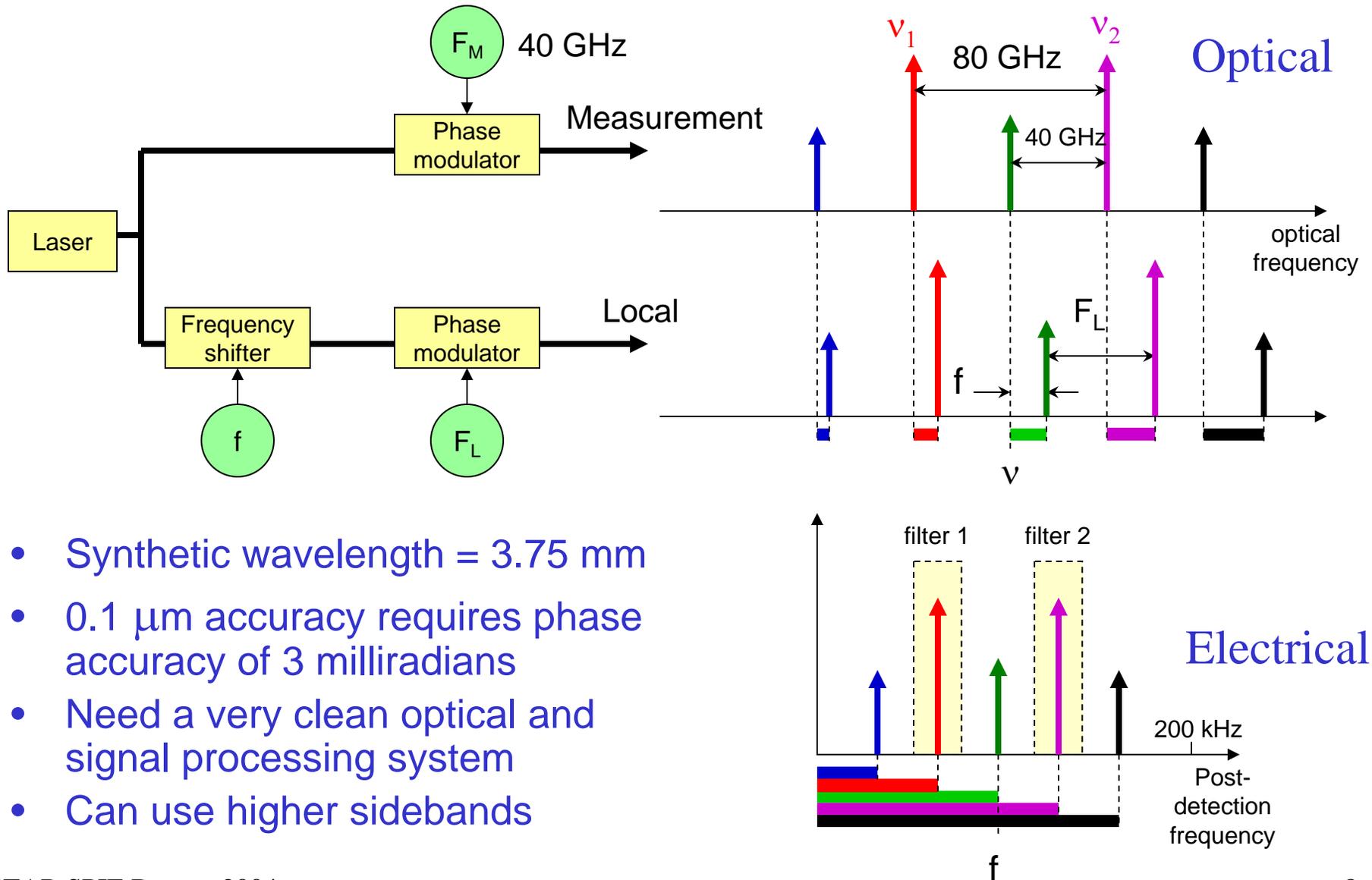


- Measurement and Local beams mix to produce a unique beat frequency for each sideband
- Electrical Spectrum is filtered to isolate beats resulting from desired optical sidebands





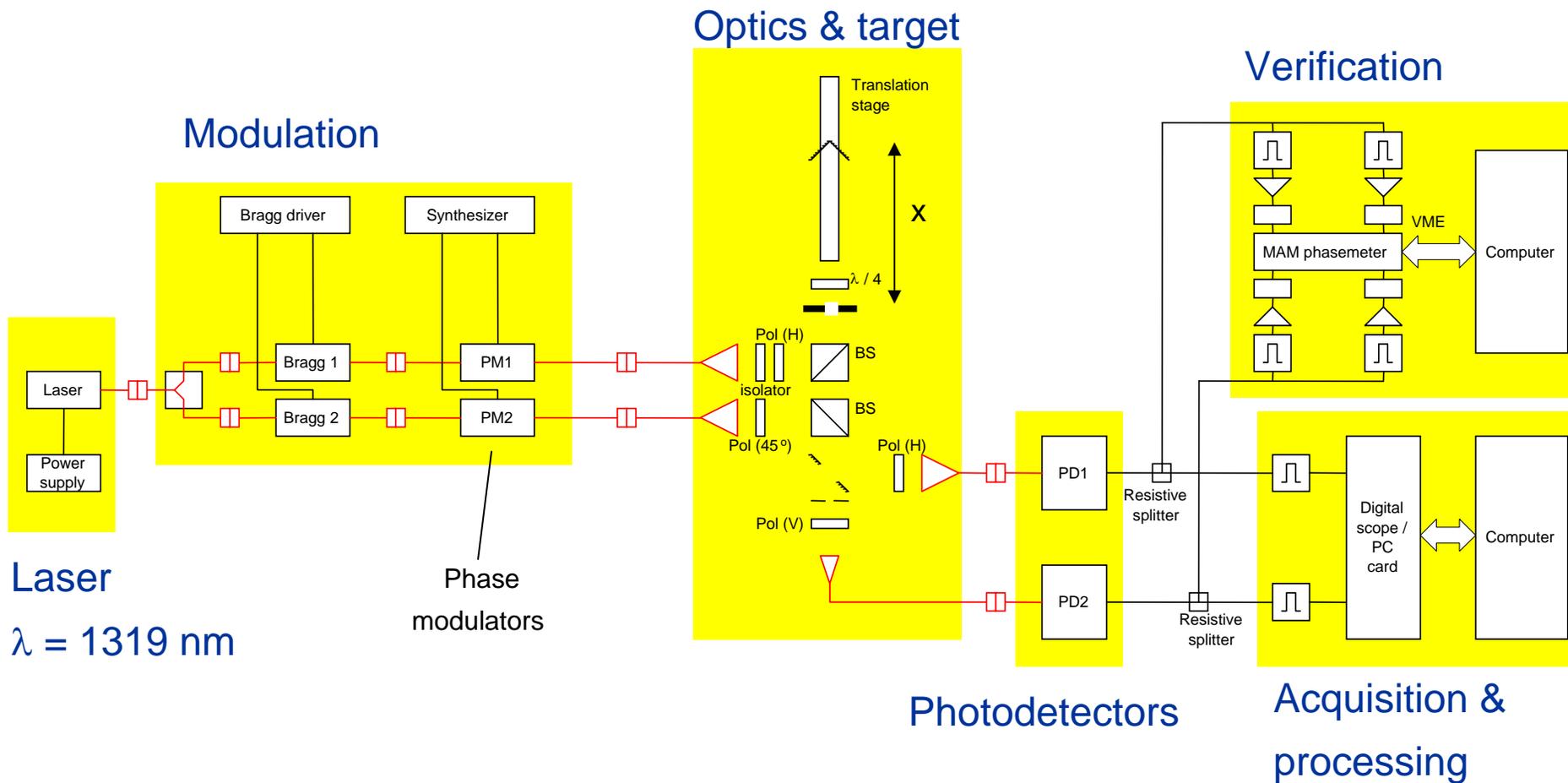
Modulation scheme



- Synthetic wavelength = 3.75 mm
- 0.1 μm accuracy requires phase accuracy of 3 milliradians
- Need a very clean optical and signal processing system
- Can use higher sidebands



MSTAR schematic

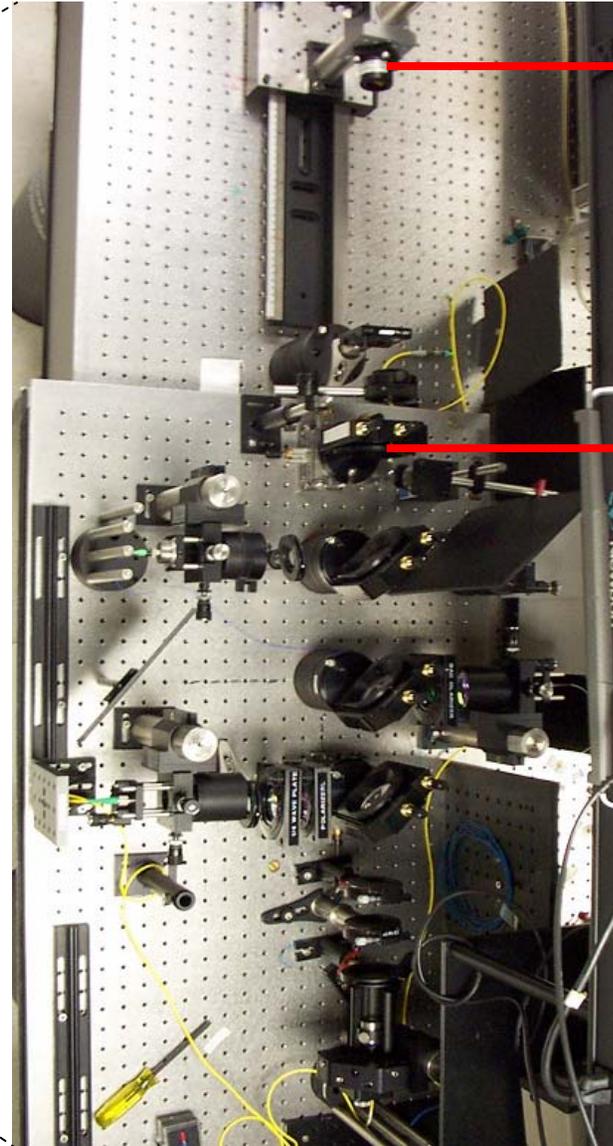
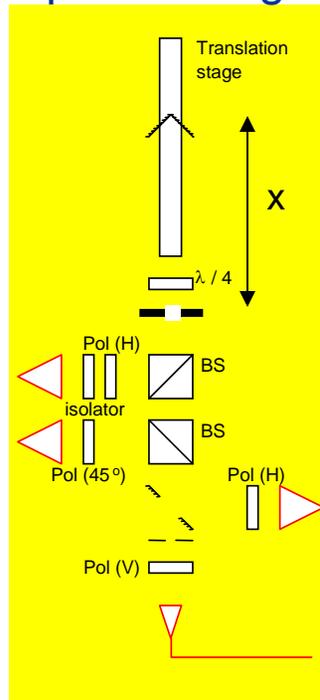


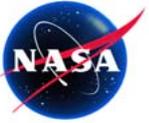


Lab set-up



Optics & target





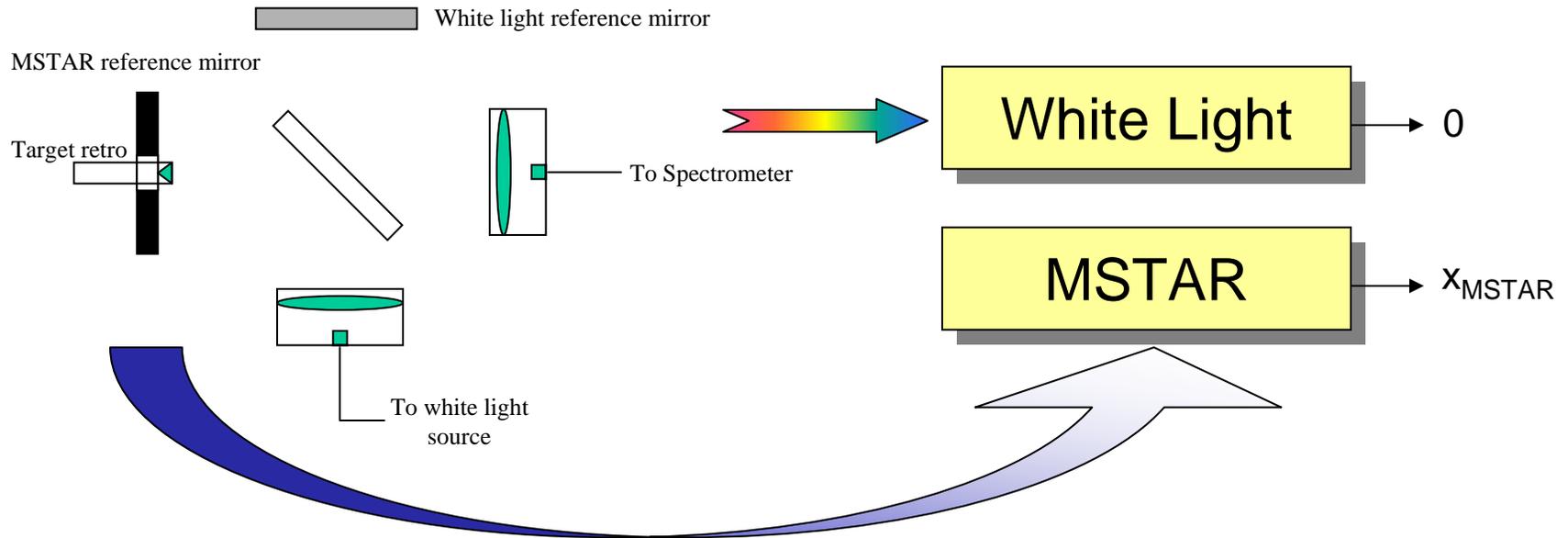
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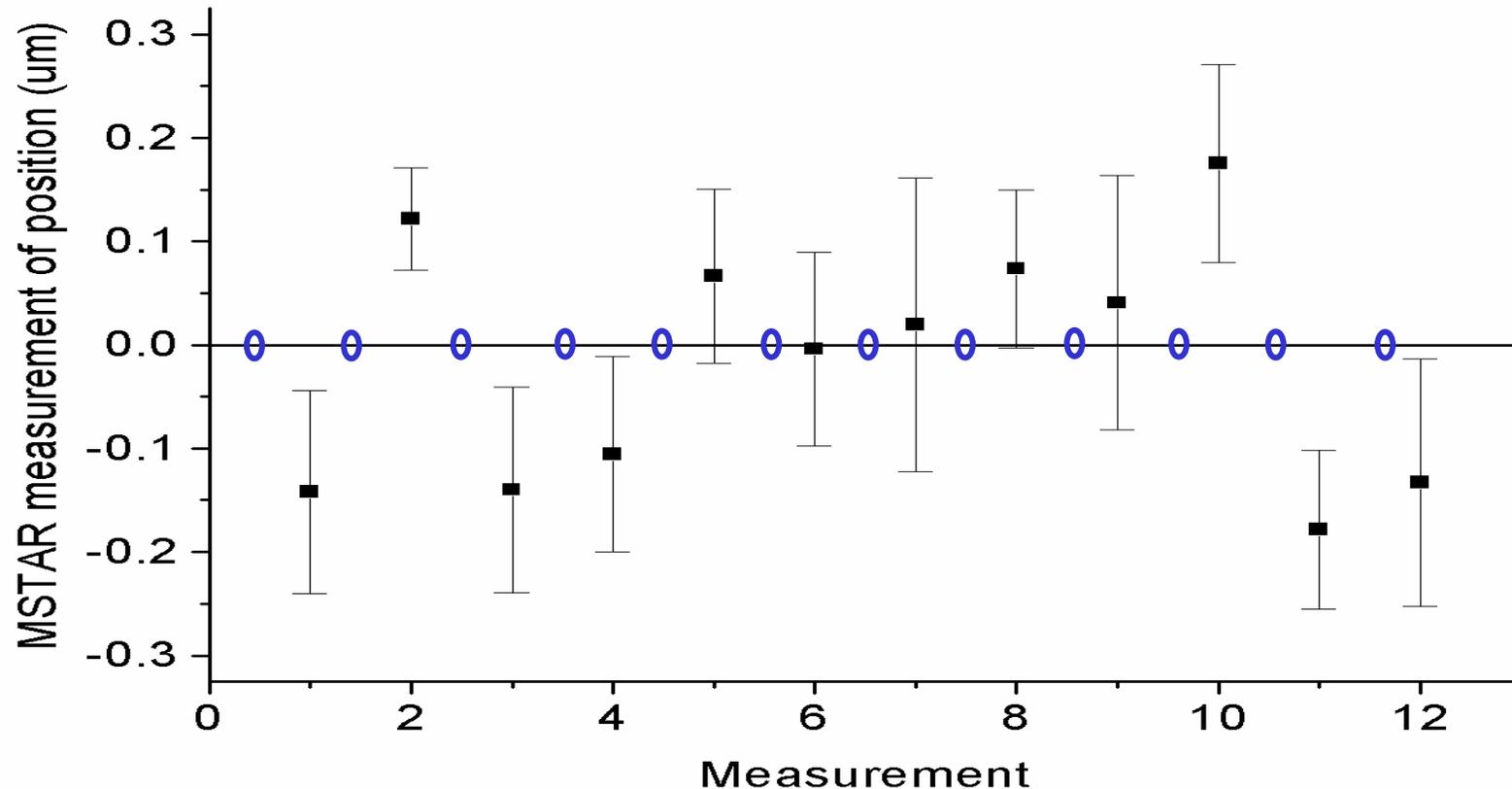
Setting the zero point



- Use white light Michelson interferometer to set zero point.
 - Match fringe pattern from target retro to MSTAR reference mirror
- Make measurement with MSTAR
- Repeat many times.



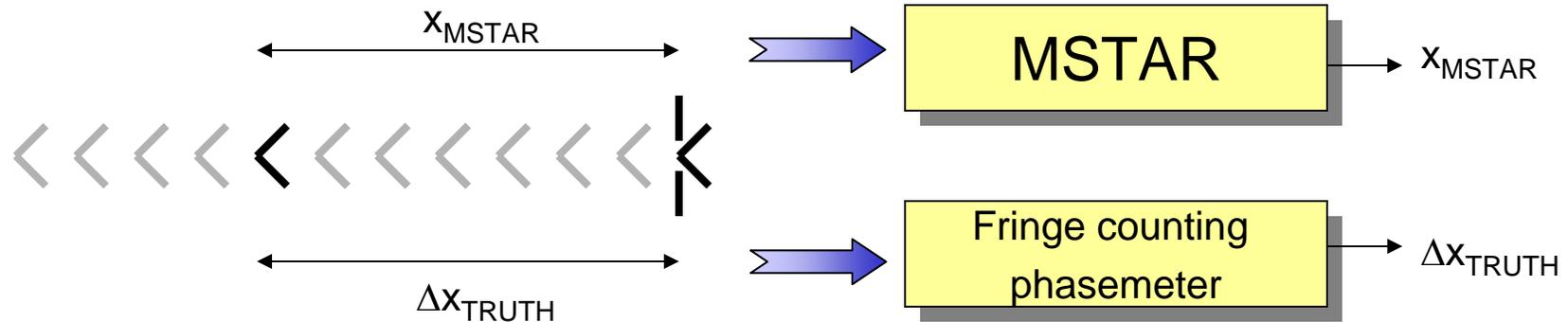
Zero Results



- Zero set with white light between each point.
- Average error 0.12 μm



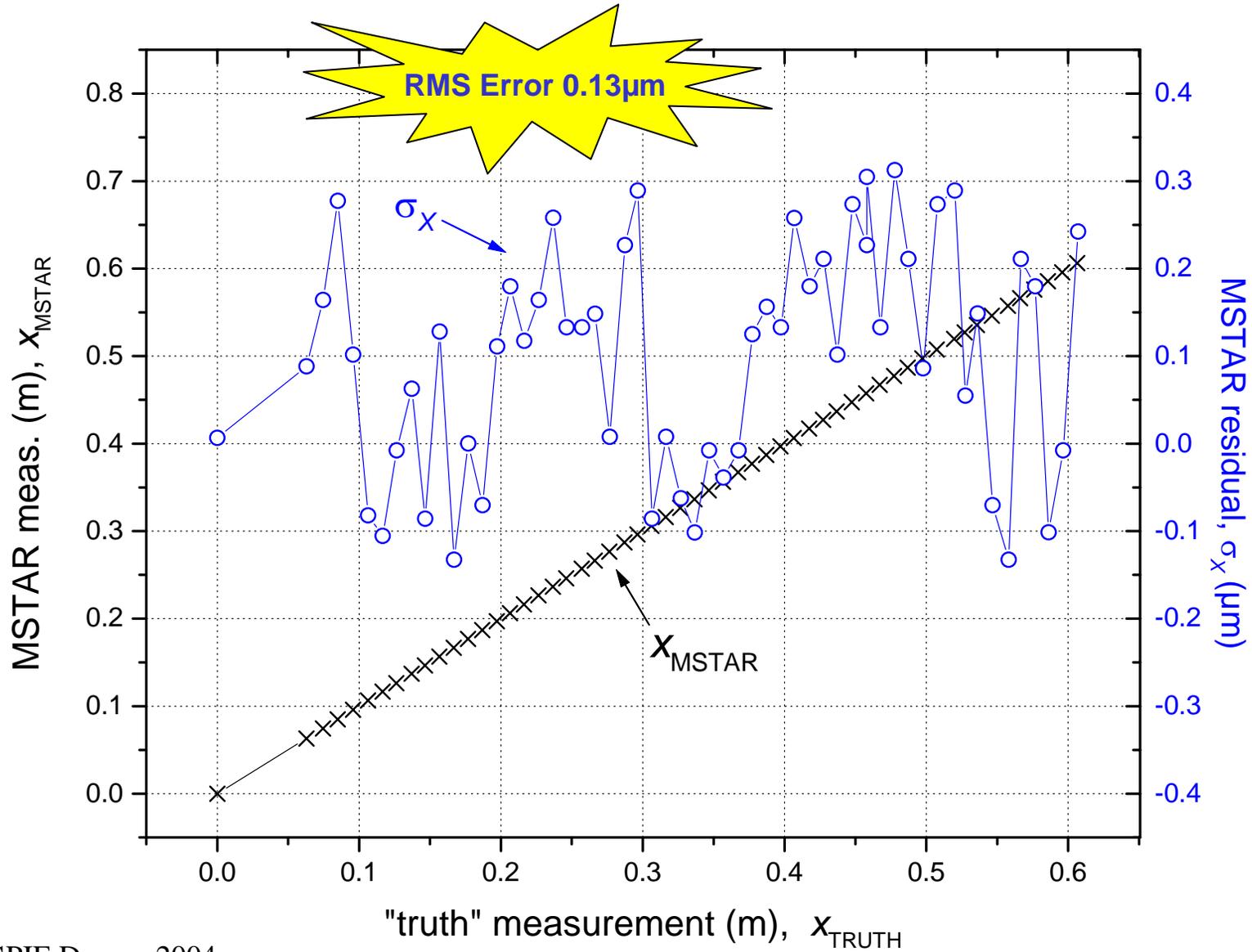
Displacement Test



- Start with target at zero.
- Measure absolute position with MSTAR
- Move target while tracking with phasemeter to measure displacement.
- Repeat many times.
- Plot MSTAR vs. phasemeter and calculate residual.



Displacement Results





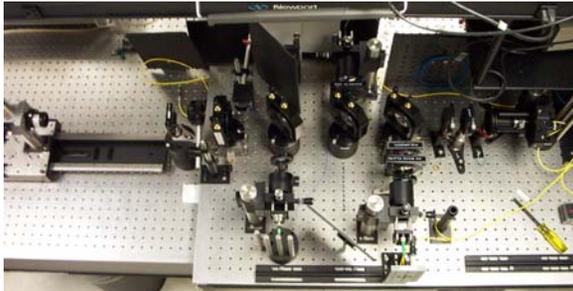
Outline



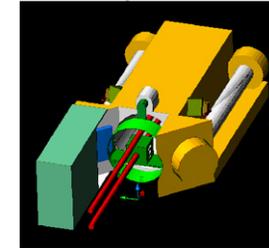
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Miniaturization



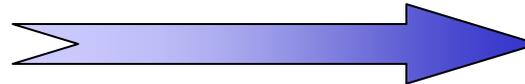
Lab breadboard to Space Interferometry Mission (SIM) type beam launcher



Size ~ 25x15x5 cm



Commercial Nd:YAG laser to SIM/StarLight developed laser



Brassboard exists



Experimental polymer 40GHz modulator to commercial telecom 40GHz modulator



Done



Frequency Stability



- Stability requirement given by σ_x/x
- Coarse (absolute) stage (required $\sigma_x= 0.1 \text{ um}$)
 - Based on the RF modulation frequency
 - For 100m separation, fractional uncertainty is 10^{-9}
 - Easily met by commercially available for RF references.
- Fine stage (e.g. $\sigma_x=30 \text{ nm}$)
 - Based on the laser frequency
 - For 100m requires a fractional uncertainty 3×10^{-10} (72kHz with a 1319 nm laser)
 - Laser locking systems have been developed which can meet this requirement



Moving Targets



- Use Carrier-Aided Smoothing
 - First developed for Global Positioning System
 - Allows for coherent averaging in the presence of moving targets
- Lab setup should track velocities up to 10 mm / s



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Summary



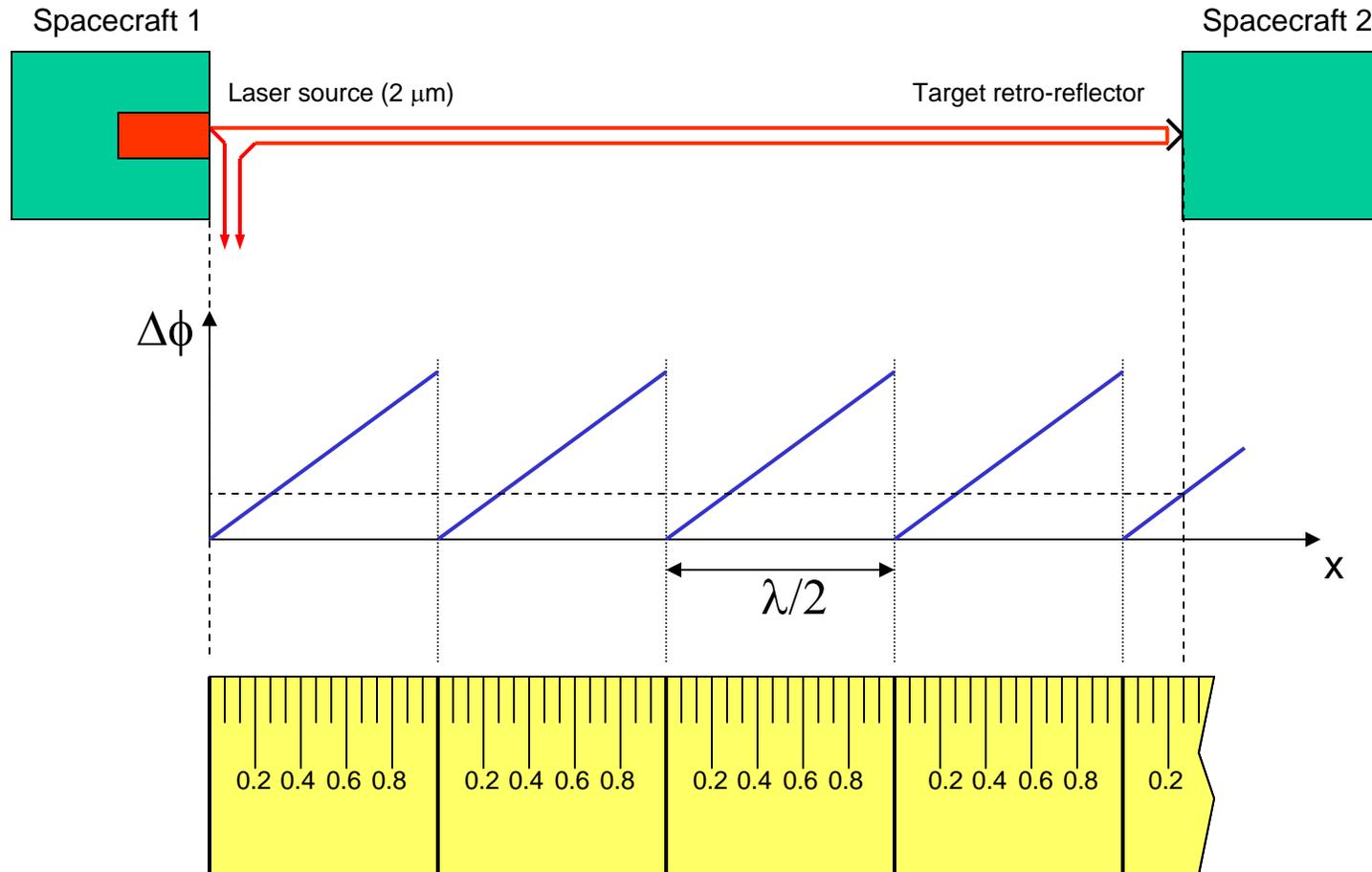
- ***M*odulation *S*ideband *T*echnology for *A*bsolute *R*anging**
- 0.1 μ m accuracy demonstrated over 1 meter.
- Resolves integer-cycle ambiguity: enables nm accuracy
- Standard heterodyne metrology gauge with 40 GHz phase modulation.
- Verified experimentally over 1 m
- Scalable to large distance (~100 m) and moving targets (~10 mm/s)



Backup Slides

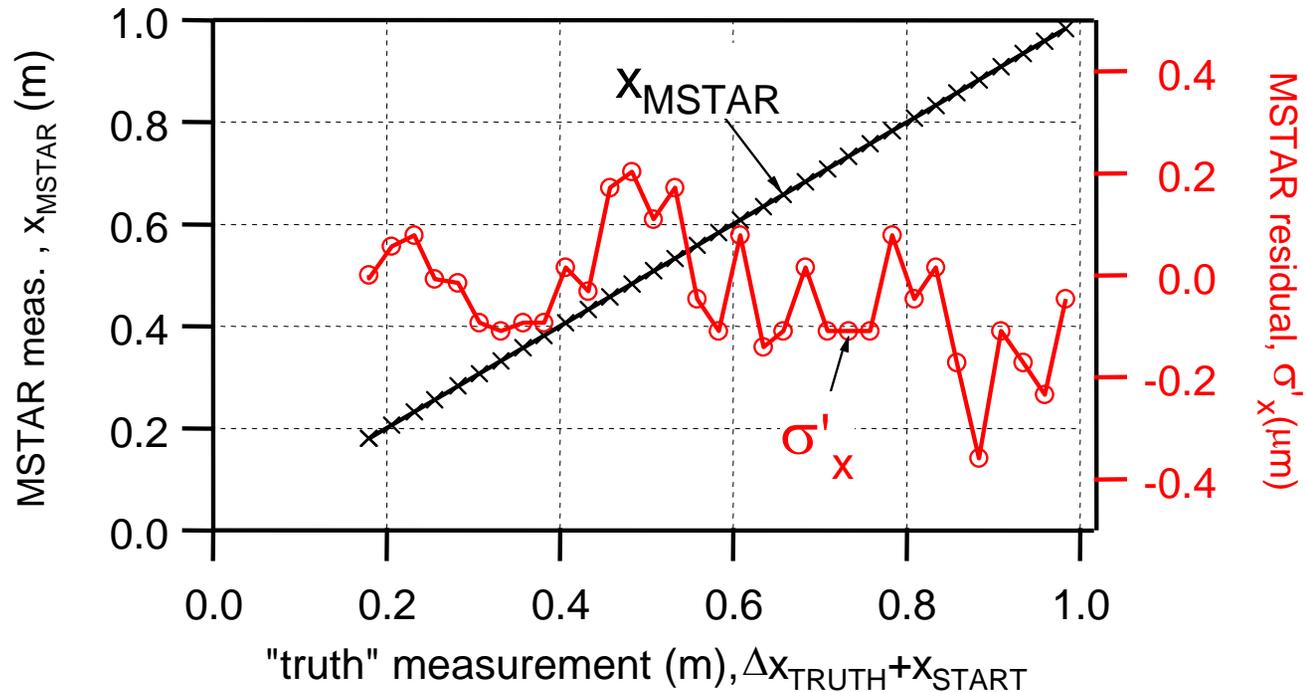


Laser Interferometer





First Displacement Results

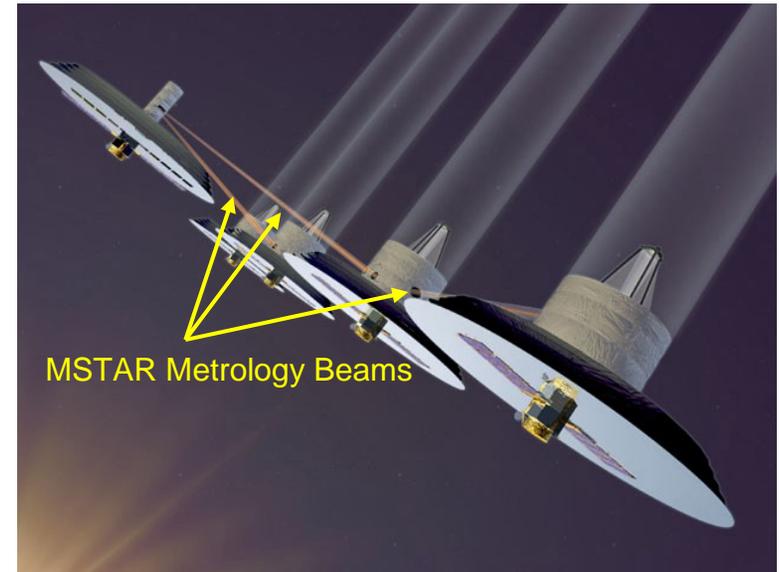


- Residual rms = $0.12 \mu\text{m}$

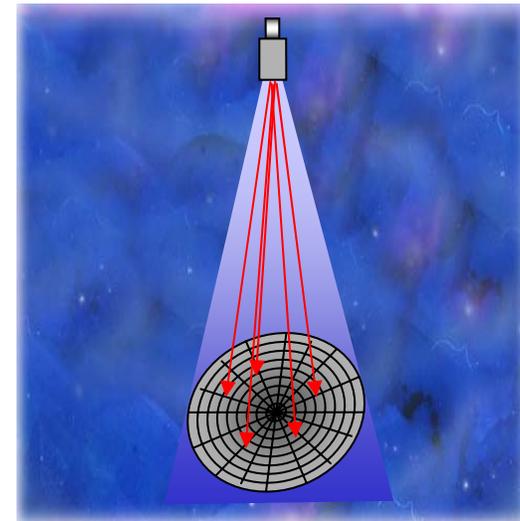
1st demonstration to resolve integer-wavelength ambiguity with this range in a practical sensor!



- Distributed Spacecraft Control
 - Single MSTAR sensor may be switched to measure multiple targets.
 - Not affected by momentary beam interruptions



- Large Single Aperture Telescopes
 - In flight surface figure checking
 - Scan single sensor to many targets on the surface
 - Multiple sensors to monitor a few key targets.
- And possibly many more...





Carrier-Aided Smoothing



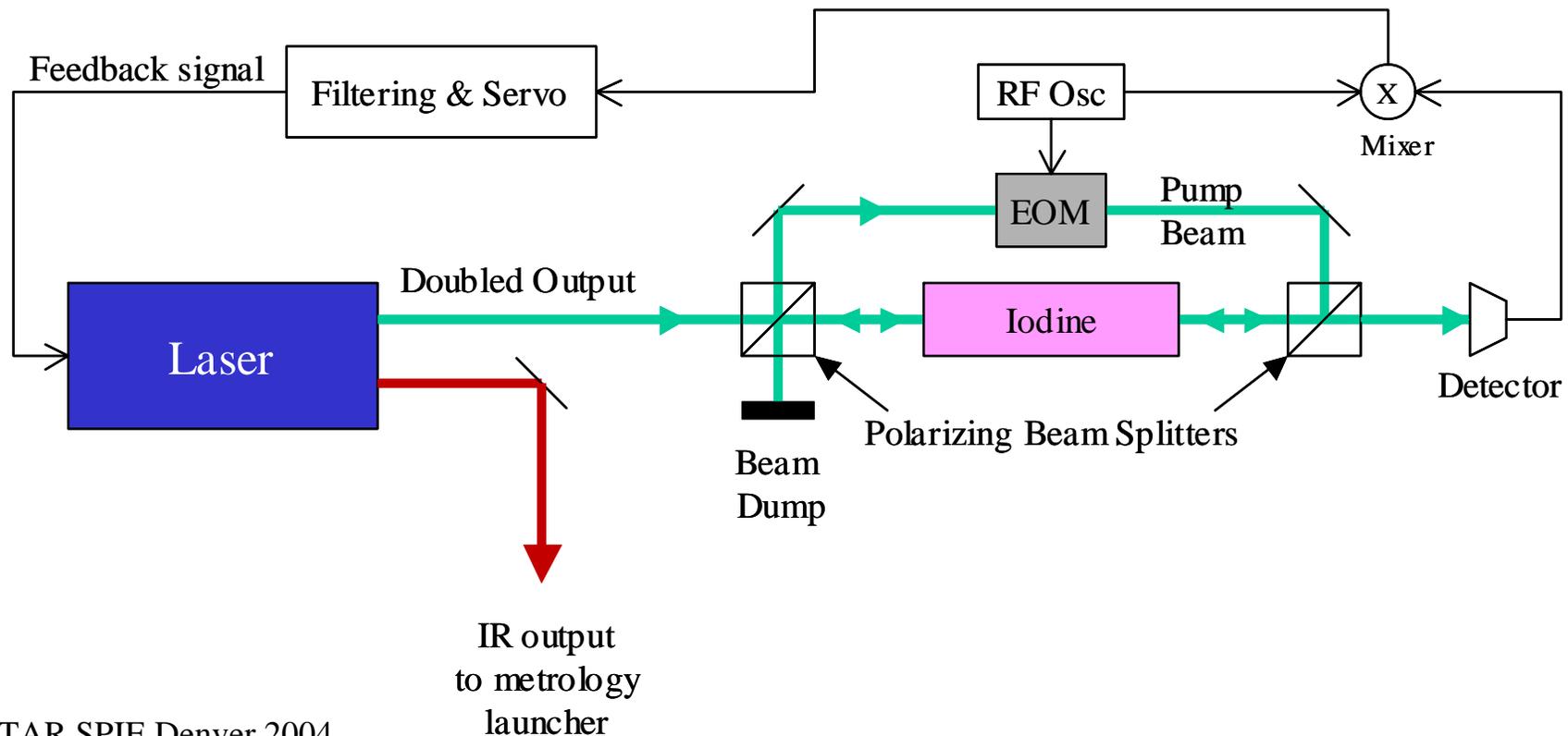
- Reference: R. Hatch, *The Synergism of GPS Code and Carrier Measurements*, Proceedings of 3rd International Geodetic Symposium on Satellite Doppler Positioning, DMA/NGS, pp. 1213-1232, Washington, D.C. (1982)
- Carrier phase is tracked from the start of the sideband-phase measurement.
- Carrier phase subtracted from the sideband-phase time series.
- Down-converted Doppler shifted frequency, $f = 2*v/\lambda$ where v = target velocity and λ = laser frequency.
- Limiting factor is bandwidth of filters around down-converted sidebands. (e.g. 15kHz of Doppler shift with $\lambda=1319$ nm $\Rightarrow v = 1.3$ mm/s).



Iodine locking system



- Modulation transfer spectroscopy (MTS) method for Doppler free locking.
- Commercially available from Innolight with 10^{-13} fractional stability





Publications and Patents



- S. Dubovitsky and Oliver P. Lay, “MSTAR: A high precision laser range sensor,” NASA Tech Briefs and New Technology Disclosure, NPO-30304, 2001
- S. Dubovitsky and Oliver P. Lay, “MSTAR: A high precision laser range sensor,” NASA patent pending
- O. P. Lay, S. Dubovitsky, R. D. Peters, J. P. Burger, S.-W. Ahn, W. H. Steier, H. R. Fetterman, Y. Chang, “MSTAR:a submicrometer absolute metrology system”, Opt. Lett., vol 28, no 11, June 2003, pp. 890-892.
- Seh-Won Ahn, Min-Cheol Oh, William H. Steier, Yin-Hao Kuo, Hyung-Jong Lee, Cheng Zhang, and Harrold R. Fetterman, "Integration of electro-optic polymer modulators with low-loss Fluorinated polymer waveguides" Opt. Lett.27, 2109, December 2002
- O. P. Lay, Serge Dubovitsky , Robert D. Peters , Johan Burger , Seh-Won Ahn , William H. Steier , Harrold R. Fetterman , Yian Chang , “Absolute distance measurement with the MSTAR sensor”, SPIE International Symposium on Optical Science and Technology, SPIE's 48th Annual Meeting, August 2003, San Diego, California USA
- S. Dubovitsky ,Oliver P. Lay, Robert D. Peters, Johan P. Burger, “MSTAR: A sub-micron absolute metrology sensor for space-based applications”, accepted for presentation at ICSO 2004, 5th International Conference on Space Optics, March 2004