

## MEASURING FILM THICKNESS AND MASS PROPERTIES OF ELECTROACTIVE THIN-FILM POLYMERS USING PLATEWAVE DISPERSION DATA

A. El-Azab, Ajit K. Mal

Mechanical and Aerospace Engineering Department

University of California, Los Angeles, California 90095-1597

Yoseph Bar-Cohen, Shyh-Shin Jih

Jet Propulsion Laboratory, California Institute of Technology

Pasadena, CA 91109

### INTRODUCTION

Electroactive thin-film polymers are candidate sensors and actuators materials [1,2]. They are also finding a significant potential for applications in muscle mimetics and micro-electro-mechanical systems (MEMS). In these applications, polymer thin films of thickness varying between 20 and 300 micrometer are utilized. Activation of these polymers is attributed to piezoelectric, electrostrictive or electrostatic effects. Recent investigations suggest that polymers may produce striation which can be stronger than that delivered by electroactive ceramics. Such response may be produced by polymers with isotacticity or syndiotacticity molecular structure, where tacticity is the position of a pendant polymer group with a strong dipole moment that is mounted on a backbone polymeric chain.

Polymer thin films undergo thickness changes under the action of electric field. These changes are linear if the material's response is piezoelectric and are quadratic under electrostrictive or electrostatic actuation. In addition to thickness changes, the film vibrates as a plate structure [3] and in some electrostrictive polymers the elastic properties are dependant upon the electric field itself. Measuring the film thickness and its changes during activation while distinguishing between the thickness value and the amplitude of film vibration is a difficult task. Techniques such as interferometry, eddy-current and capacitance yield information about the location of the top surface of the film assuming that the rear surface stays stationary. Ultrasonic pulse-echo offers an ideal tool for simultaneous determination of the location of the top surface, i.e., vibration amplitude, and the film thickness. However, to obtain an acceptable resolution for 50 to 100-micrometer thin films it is necessary to use frequencies in the range of 50-MHz or above, which is beyond the capability of conventional ultrasonic systems.

Plate wave measurements offer the capability to determine the thickness of thin films using much lower frequencies and to obtain significantly higher resolution than that can be obtained by pulse-echo technique at similar frequencies. Furthermore, using dispersion curve measurements one can also determine the elastic constants of the film, thus allowing investigation of the electrostriction behavior of polymer and determination the activation force that the polymer induces.

The authors are currently studying the potential use of plate wave dispersion curve measurements as an effective gauging tool for electroactive thin film polymers. In this communication, we briefly describe application of this technique to measure the moduli and thickness of electroactive polymer thin films and discuss some of the preliminary results. A series of polymer thin films are used in the present study; a 1  $\mu\text{m}$  s-PVMA film, and 80 $\mu\text{m}$  and 230 $\mu\text{m}$  thin polyethylene terephthalate films. The dispersion curves are measured for these materials and an inversion algorithm is applied to determine the thickness and elastic constants.

## EXPERIMENTAL

The experimental technique is based on leaky Lamb wave (LW) theory. The overall experimental setup is described in prior publications [4], and is briefly summarized here. The technique employs a pair of transmitting and receiving transducers in a pitch-catch arrangement, where the transducers are flat, immersion 20MHz, 0.125-inch diameter. A computer controlled setup which allows to articulate the angle of incidence from 12 to 80 degrees is utilized. The receiving transducer is placed at the null zone of the leaky lamb wave field. At incidence angles from 18 to 45 degrees at increments of 0.25 degree, the frequency is varied in the range of 3 to 30 MHz and the minima of the reflection spectra are acquired.

The location of the minima in the reflection spectral response are identified by a software algorithm that distinguishes between noise and modes. Certain selection criteria are enforced to eliminate falsely measured modes. A plot of the frequency of the various plate wave modes as a function of the phase velocity is defined as the film dispersion curve. Since the objective of the current study is to examine the feasibility of using LW measurements of the thickness and elastic constants of polymer thin films, water was used as a convenient coupling medium. In future investigations where electric field will be applied to study the electroactivation behavior, water will be replaced by a silicon oil compliant to avoid potential electrolysis.

## LEAKY LAMB WAVES DATA

The phase velocity,  $v$ , is determined in terms of the angle of incidence using Snell's law,  $v = c/\sin(\theta)$ , where  $c$  is the acoustic wave speed in the coupling medium, and  $\theta$  is the incidence angle. The frequencies at which reflection minima occur are associated with the platewave modes. At these frequencies, the reflection coefficient  $R$  is zero;  $R$  itself may be expressed in the form

$$R = R(\omega, \nu; c_1, c_2, h) \quad (1)$$

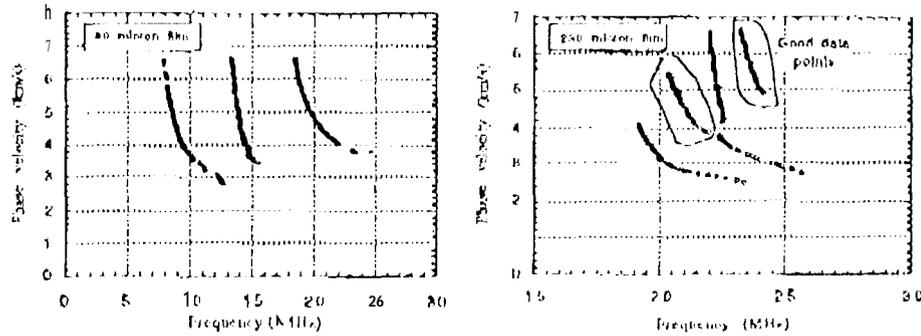


Figure 1: Dispersion data for 80 and 230  $\mu\text{m}$  thin polyethylene terephthalate films.

where  $\omega$  is the circular frequency,  $c_1$  and  $c_2$  are the P- and S-wave speeds of the film material, respectively, and  $h$  is the film thickness. Mathematical details are found elsewhere; see for example [5].

Examples of raw data are shown in Figs. 1 for two thin polyethylene terephthalate films whose thicknesses are 80  $\mu\text{m}$  and 230  $\mu\text{m}$ . It is to be noted that not all of the dispersion curves are measured in a single experiment. Also, the acquired frequency minima of the reflected spectrum may still be subject to some experimental errors, which does not occur very often. In principle, careful screening of the data should lead to detection of erroneous data points, i.e., a good judgment as to which data points should be used for inversion is always required. The data shown in Fig. 1 for the 80  $\mu\text{m}$  film are clean, and only some of which are used to recover the thin film parameters; thickness and elastic properties. For the 230  $\mu\text{m}$  film, however, a part of the data is rejected, which either represent noise or occur in a zone where the dispersion curves representing different modes are very close to each other.

### THE INVERSION ALGORITHM

Leaky Lamb wave measurements yield a set of points in the  $\omega - v$  space. An analytical dispersion relationship exists, which may be written in the form

$$\mathcal{F}(\omega, v; \rho, E, \nu, h) = \mathcal{G}(\omega, v; c_1, c_2, h) = 0 \quad (2)$$

in which  $E$ ,  $\nu$  and  $\rho$  are Young's modulus, Poisson's ratio and the density of the film material, respectively. Let  $(\omega_i, v_i)$  be the set of experimental data points. The inversion problem consists in solving the dispersion relationship

$$\mathcal{G}(\omega_i, v_i; c_1, c_2, h) = 0 \quad (3)$$

for  $c_1, c_2$  and  $h$ . Once  $c_1$  and  $c_2$  are determined,  $E$  and  $\nu$  can be calculated from

$$\nu = \frac{\frac{c_1^2}{c_2^2} - 2}{2\left(\frac{c_1^2}{c_2^2} - 1\right)}, \quad E = 2(1 + \nu)\rho c_2^2. \quad (4)$$

The technique used here to recover the parameters  $c_1$ ,  $c_2$  and  $h$  is based on the simplex algorithm [6]. This algorithm has been successfully used to invert leaky Lamb wave data for composite plates [7], and was found to converge much faster than algorithms based on local linearization and least square theories [8]. The algorithm is based on a search for a point  $(c_1^*, c_2^*, h^*)$  in the  $c_1 - c_2 - h$  parameter space at which the sum of squares of the residuals  $S_{SR}$  is minimum, where  $S_{SR}$  is defined by

$$S_{SR} = \sum_i G^2(\omega_i, v_i; c_1, c_2, h). \quad (5)$$

Ideally speaking, at the point  $(c_1^*, c_2^*, h^*)$  the  $S_{SR}$  must be zero. An initial four vertices are selected in the  $c_1 - c_2 - h$  parameter space and the response  $S_{SR}$  is calculated at each vertex. The vertices are then changes iteratively in such a way that  $S_{SR}$  is minimized. The vertex movements are governed by certain rules, which can be found elsewhere [6,7]. Eventually, these vertices become very close to the desired point. Iteration is terminated based on selected convergence criteria. To assure that inversion is accurate, only part of the data is used to recover the thin film thickness and properties. The properties and thickness are then used, in 110 analytical dispersion relationship, to predict all data point.

## RESULTS AND DISCUSSION

Dispersion data for the two polyethylene terephthalate thin films are shown in Figs. 2 and 3, along with theoretical dispersion curves. The parameters resulting from data inversion are used to calculate these curves. For the polyethylene terephthalate films  $c_1$ ,  $c_2$ ,  $h$ ,  $E$  and  $\nu$  were respectively found to be 2.67km/s, 1.3km/s, 86 $\mu$ m, 5.2GPa, and 0.35 for the first (80 $\mu$ m) film, and 2.9km/s, 1.32km/s, 234 $\mu$ m, 5.3GPa and 0.37 for the second (230 $\mu$ m) film.  $E$  is calculate using Eq. (4) for a density  $\rho = 1.15$ . The values 80 and 230 were measured independently by a different method prior to the test. The difference between the values determined by inversion of leaky Lamb wave data and those measured prior to the test are small, which implies that the algorithm is reliable and can be used to invert leaky Lamb wave data with a fairly acceptable precision.

Although the two films are made of the same material, it is noted that slight differences in their wave speeds  $c_1$  and  $c_2$  values exist. At this moment the authors have not tried to explain these differences. However, it can be speculated that statistical variability may exist in film properties, particularly if one considers the complex nature of molecular chains comprising such thin films.

The results for the 1mm s-PMMA film are given in Fig. 4. For this film,  $c_1$ ,  $c_2$ ,  $h$ ,  $E$  and  $\nu$  were respectively found to be 1.94km/s, 0.92km/s, 1mm, 2.7GPa, and 0.35.  $E$  is calculate using Eq. (4) for a density  $\rho = 1.15$ . Young's modulus values for PMMA in the range 2.2-3.2GPa were reported [9].

## SUMMARY

In this communication, a preliminary study is conducted to investigate the potential use of platewave dispersion curve measurements as a technique for indirect

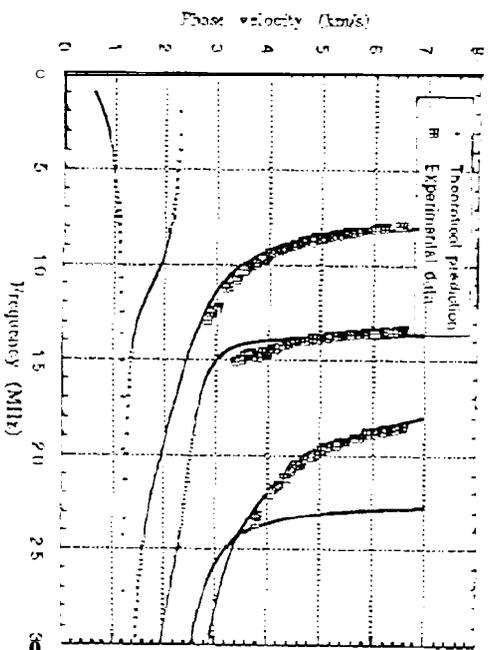


Figure 2: Comparison between experimental data and theoretical curves for an 80µm polyethylene terephthalate film.

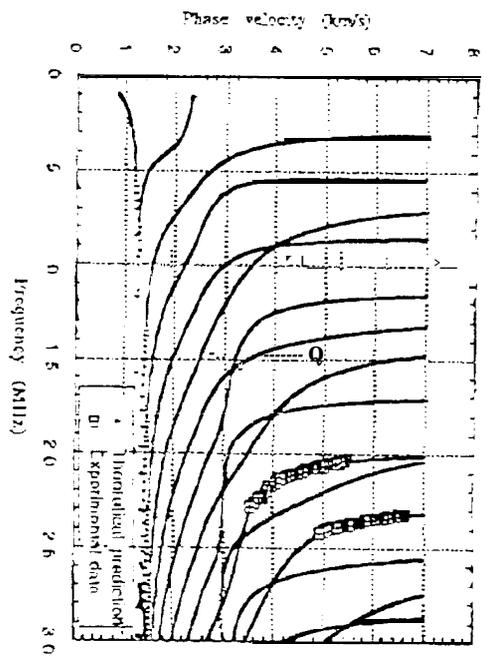


Figure 3: Comparison between experimental data and theoretical curves for a 230µm polyethylene terephthalate thin film.

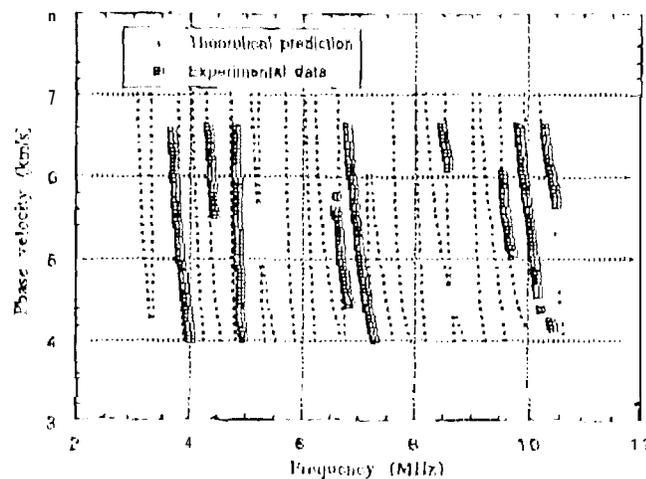


Figure 4: Comparison between experimental data and theoretical curves for a 1 mm s-PMMA film.

measurement of the elastic properties and thickness of electroactive thin film polymers. Three polymer films were tested; a 1 mm s-PMMA film, and 80 $\mu$ m and 230 $\mu$ m thin polyethylene terephthalate films. The dispersion curves are measured, and the simplex algorithm is applied to recover the thickness and elastic constants of the thin films. Preliminary results show that the technique can be a viable gauging tool for electroactive thin film polymers.

#### ACKNOWLEDGMENT

The part of the study that was carried out at the Jet Propulsion Laboratory (JPL), California Institute of Technology (Caltech), was performed under a contract with the National Aeronautics and Space Administration (NASA).

#### REFERENCES

1. R.G. Kepler and R.A. Anderson, "Ferroelectricity in Polyvinylidene Fluoride," *J. Appl. Phys.*, 48 (1978) 1232-1235.
2. B. Sasner, "The Piezoelectric Polymer PVDF and Its Applications," in: *IEEE Ultrasonics Symposium (1979)* pp. 491-498.
3. C.-K. Lee and F.C. Moon, "Modal Sensors/Actuators," *ASME J. of Appl. Mech.*, 57 (1990) 434-441.

4. Y. Bar-Cohen, A.K. Mal and S.-S. Lib, "NDE of Composite Materials Using Ultrasonic Oblique Insonification," *Materials Evaluation*, 51 (1993) 1285-1296.
5. T. Kundu and A.K. Mal, "Acoustic Material Signature of a Layered Plate," *Int. J. Eng. Sci.*, 24 (1986) 1819-1829.
6. M.S. Cacci and W.P. Cacheris, "Fitting Curves to Data, the Simplex Algorithm is the Answer," *Int. J. Eng. Sci.* vol. 28 (1990) 331-346.
7. M.R. Karim, A.K. Mal and Y. Bar-Cohen, "Inversion of Leaky Lam Wave Data by Simplex Algorithm," *Int. J. Eng. Sci.*, vol. 28 (1990) 331-346.
8. P.C. Xu, A.K. Mal and Y. Bar-Cohen, "Inversion of Leaky Lam Wave Data to Determine Cohesive Properties of Bonds," *Int. J. Eng. Sci.*, vol. 28 (1990) 331-346.
9. *Engineered Materials Handbook, Vol. 2: Engineering Plastics*, ASM International, Metals Park, OH, 1988.